

Sinkhole Detection with 3D Full Elastic Seismic Waveform Tomography

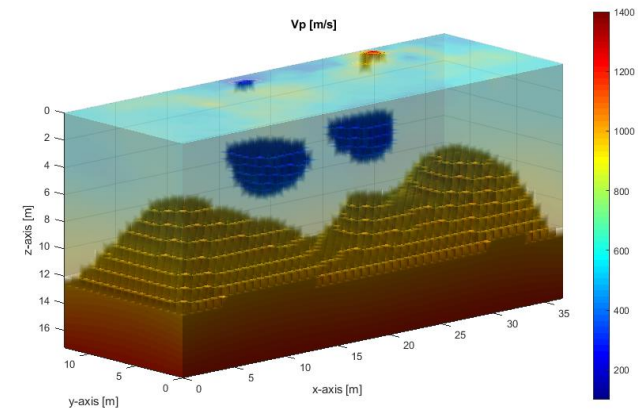
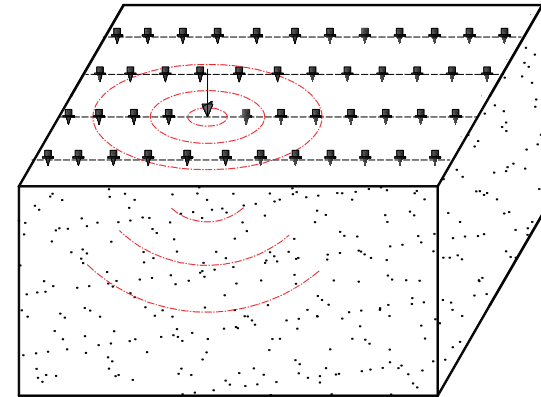
GRIP 2020

FDOT BDV31-977-82

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Presentation Outline

- Introduction and project background
- Project objectives
- Research motivation
- 3D FWI methodology
- Computational experiments
- Field experiments at 3 test sites
- ✓ Surface-based measurement
- ✓ SPT-seismic
- Summary of research conclusion
- Recommendations for implementation
- Project benefits
- Further research needed

Introduction and background

Identification of sinkhole

- Potential for rapid collapse and disruption of roadway traffic (318, 441, turnpike, etc.)
- Potential for structure collapse that cause significant property damage and even fatalities

Site investigation

- Seeing the bigger picture of the site's subsurface
- Typical invasive testing SPT, CPT – tests < 0.1% of material
- 3D seismic can accurately detect layering, karst features (pinnacles, anomalies/voids) over large area (Noninvasive test is faster and cheaper than most invasive tests)



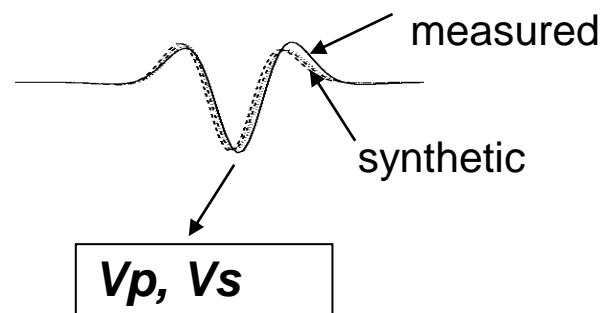
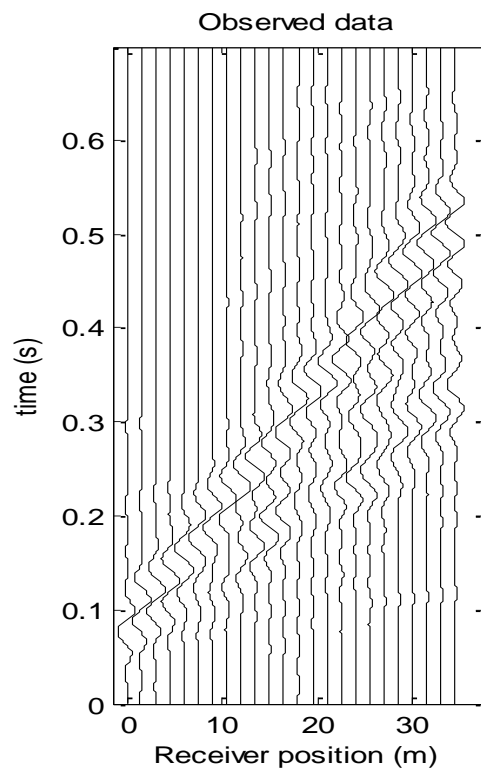
Massive sinkhole (250 x 220 x 50 ft) damaged 2 homes in Land O'Lakes, FL (July 14, 2017)

Project objectives

- Develop a 3D FWI method using surface-based seismic waves for detection of subsurface anomalies/voids
- Image vertical and lateral extents of 3D voids

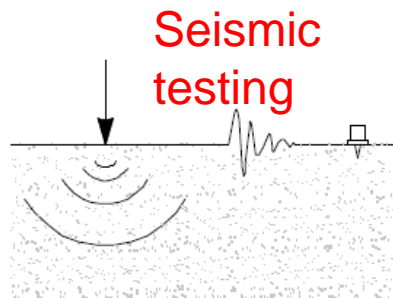
3D FWI Motivation

- 3D FWI is wave-equation based and has the potential to
 - use full information content (waveforms), both phase and magnitude
 - characterize both V_p and V_s of 3D test domain at high resolution (ft pixel)
 - **provide 3D dimensions of a buried void**



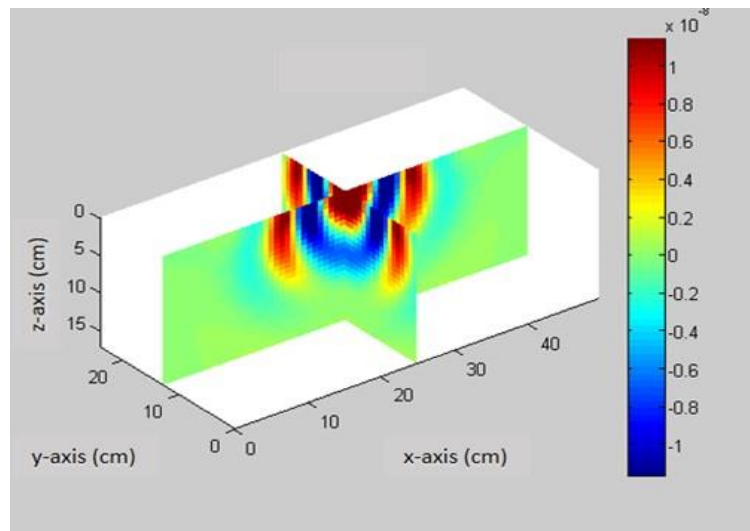
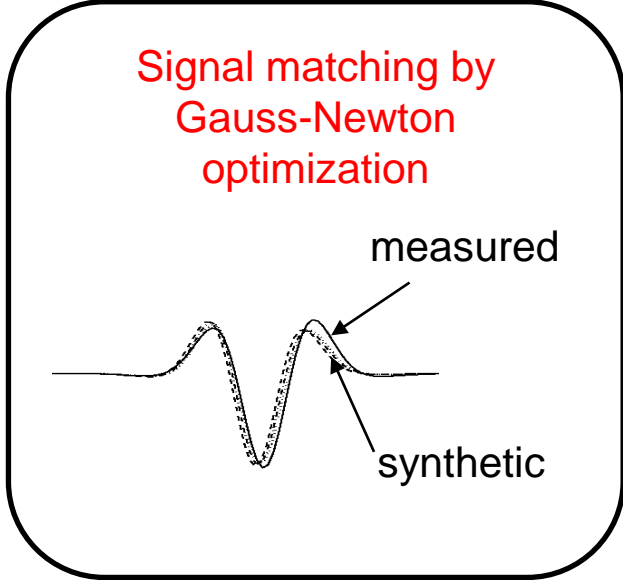
3D FWI Method

Material properties
Vs, Vp
?

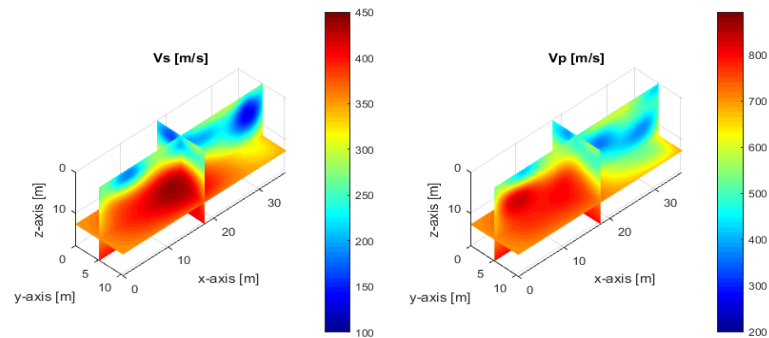


Measured data

Synthetic data



3D wave propagation



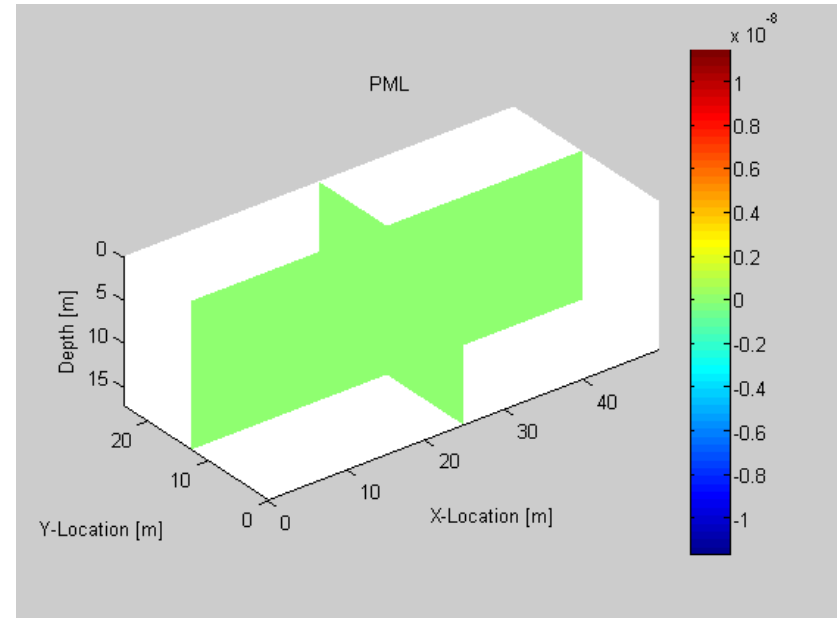
3D FWI method

➤ Forward modeling
by 3-D wave equations

$$\rho \frac{\partial v_i}{\partial t} = \frac{\partial \sigma_{ij}}{\partial x_j} + f_i \quad \text{where } i, j = 1, 2, 3$$

$$\frac{\partial \sigma_{ij}}{\partial t} = \lambda \frac{\partial v_k}{\partial x_k} + 2\mu \frac{\partial v_i}{\partial x_j} \quad \text{if } i \equiv j$$

$$\frac{\partial \sigma_{ij}}{\partial t} = \mu \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) \quad \text{if } i \neq j$$



PML is used at bottom and 4 vertical boundaries.

3D FWI method

➤ Model updating by Gauss-Newton

- Velocity residual: $\Delta \mathbf{d}_{i,j} = \mathbf{F}_{i,j}(\mathbf{m}) - \mathbf{d}_{i,j}$

- Misfit function: $E(\mathbf{m}) = \frac{1}{2} \Delta \mathbf{d}^t \Delta \mathbf{d}$ Filter, focus, balance gradient vector, as a weighting function

- Model updating: $\mathbf{m}^{n+1} = \mathbf{m}^n - \alpha^n [\mathbf{J}^t \mathbf{J} + \lambda_1 \mathbf{P}^t \mathbf{P} + \lambda_2 \mathbf{I}^t \mathbf{I}]^{-1} \mathbf{J}^t \Delta \mathbf{d},$

- Jacobian matrix: $\mathbf{J}_{i,j} = \frac{\partial \mathbf{F}_{i,j}(\mathbf{m})}{\partial m_p}$

Derivative wave-field: matrix J

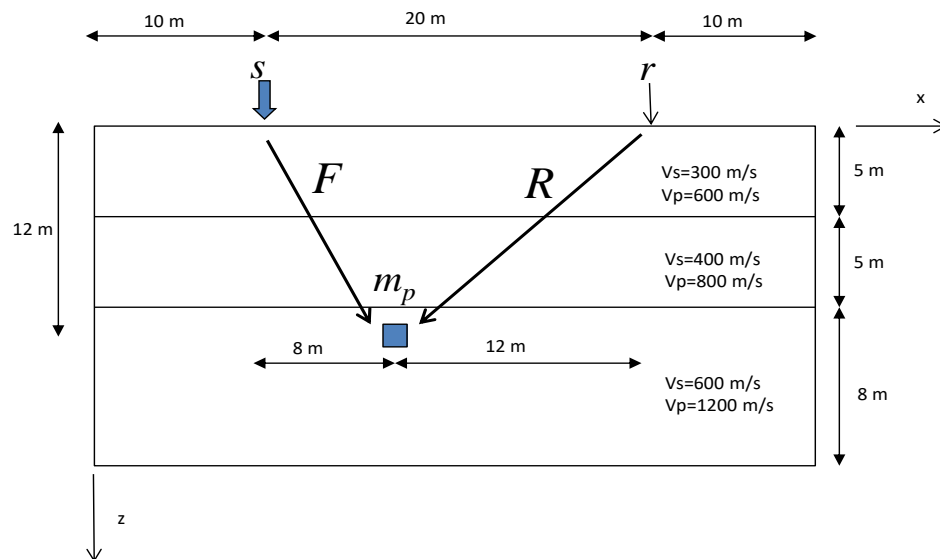
➤ Explicit

- two forward simulations with and without the model perturbation for each unknown
- Required number of forward simulations = *number of shots* × (*number of unknowns* + 1)

➤ Implicit

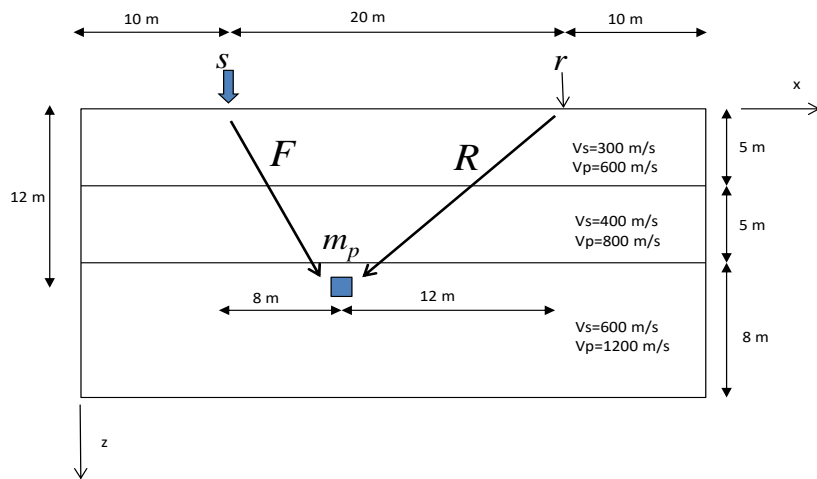
- Virtual source (F) and reciprocal wave-fields (R)
- Required number of forward simulations = (*number of shots* + *number of receivers*)

$$J_{i,j}^p = \frac{\partial F_{i,j}(\mathbf{m})}{\partial m_p} = \frac{F_{i,j}(\mathbf{m} + \Delta m_p) - F_{i,j}(\mathbf{m})}{\Delta m_p}$$

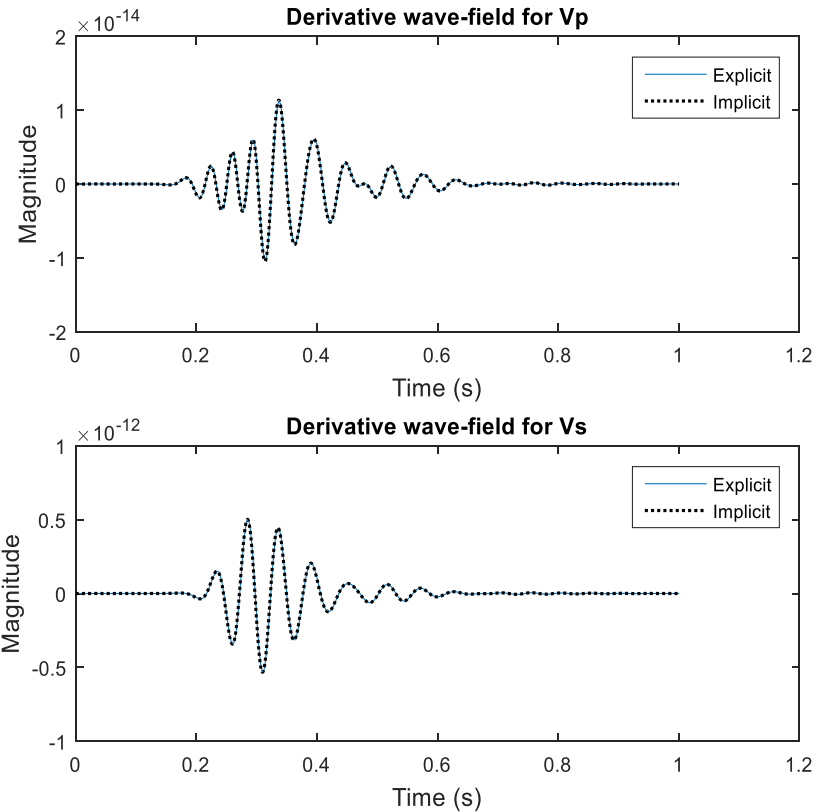


$$J_{i,j}^p = F_x * R_x + F_y * R_y + F_z * R_z$$

Comparison of derivative wave-field



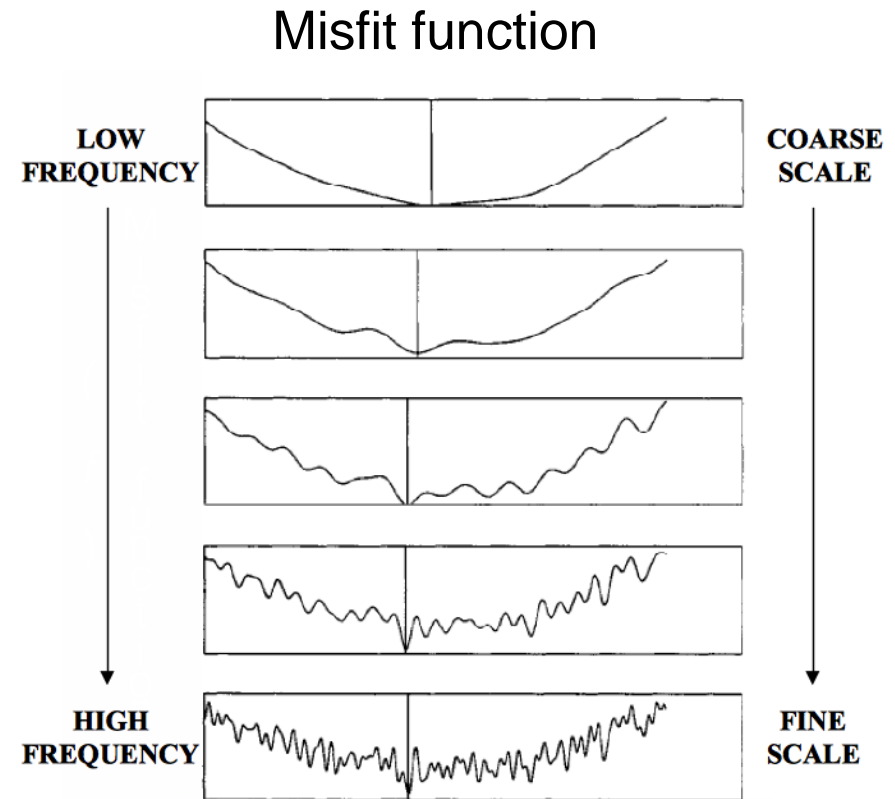
40 x 40 x 18 m
model of 3 layers



Explicit and Implicit are identical

Data Analysis

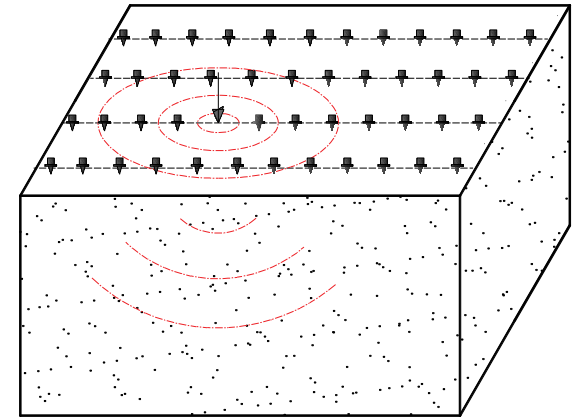
- Start analysis at lowest frequencies and move up
- Low frequencies (large wavelengths) require less detailed information of initial model
- Adding high frequency data gradually helps improve resolution to resolve fine features



Bunks et al. (1995)

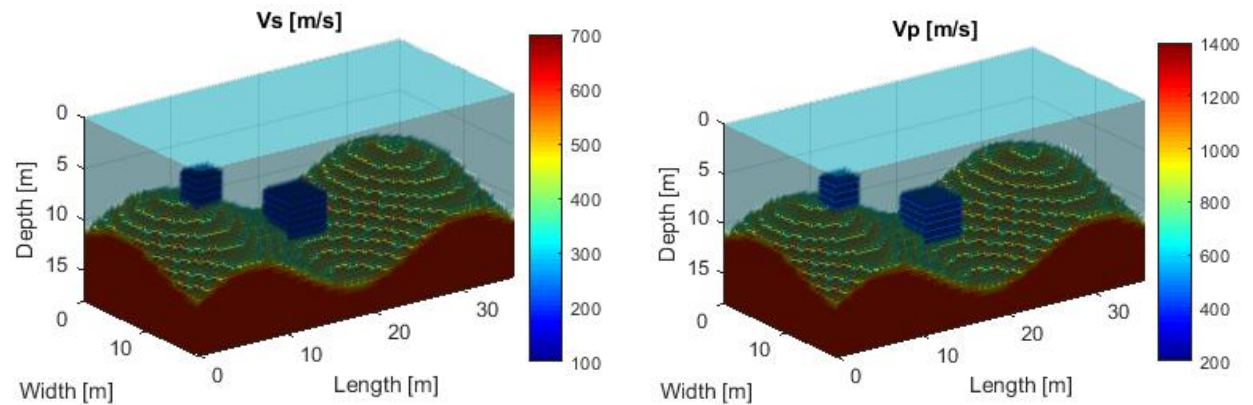
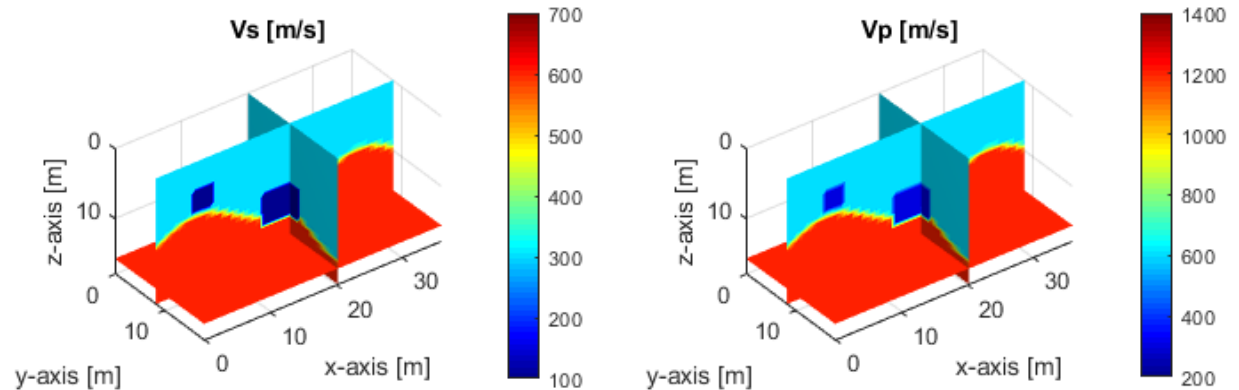
Optimal Test Configurations and Active Sources for Void Detection

- We have tested the 3D FWI on various source/receiver spacing of 10 to 30 ft, the optimal spacing is 1-2 times of void size.
- We have also tested the 3D FWI on various frequency ranges. The optimal frequency range is from 5 to 35 Hz for selection of active sources (Big bang, PEG, hammer)



Synthetic test on void

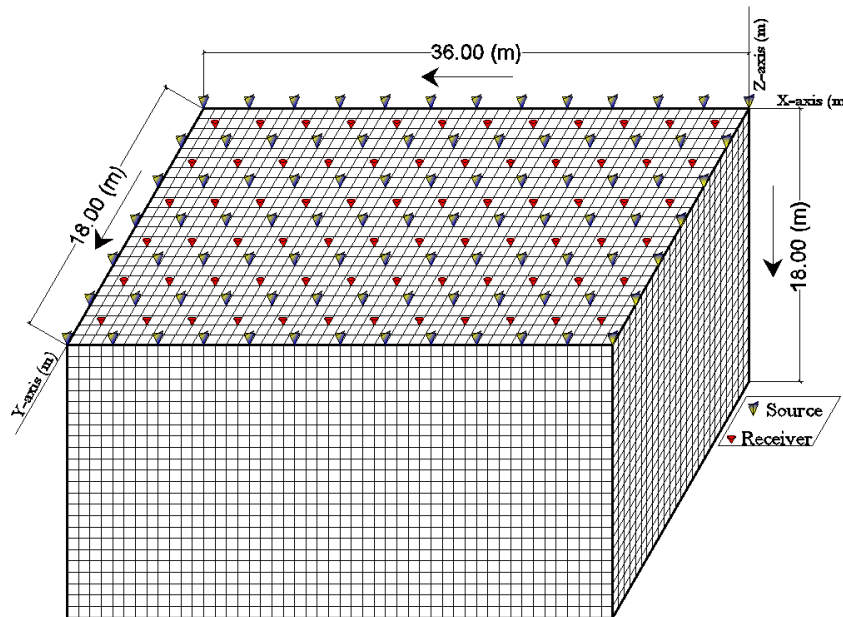
- 24 x 36 x 18 m model of variable soil/rock
- Two voids buried at 6 and 9 m depth



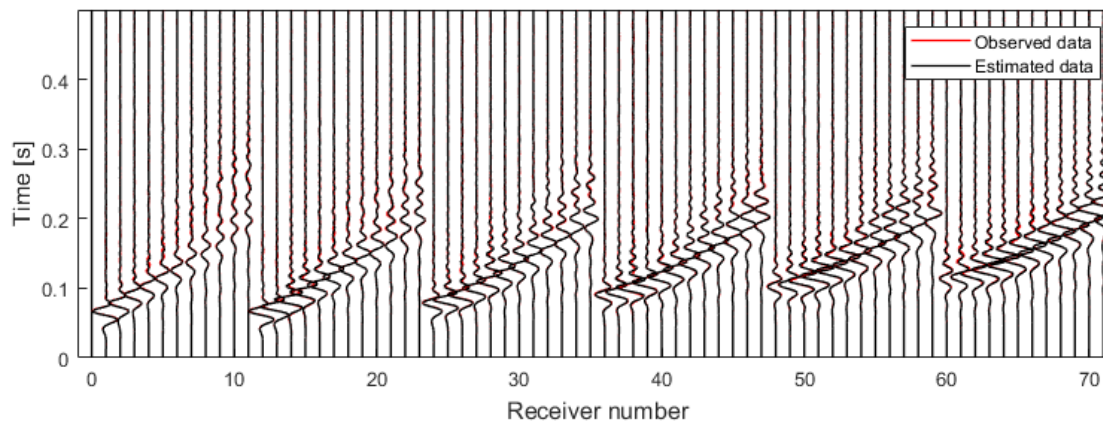
Synthetic test on void

➤ Test configuration

- 6x12 (72) receivers at 3 m spacing
- 7x13 (91) shots at 3 m spacing

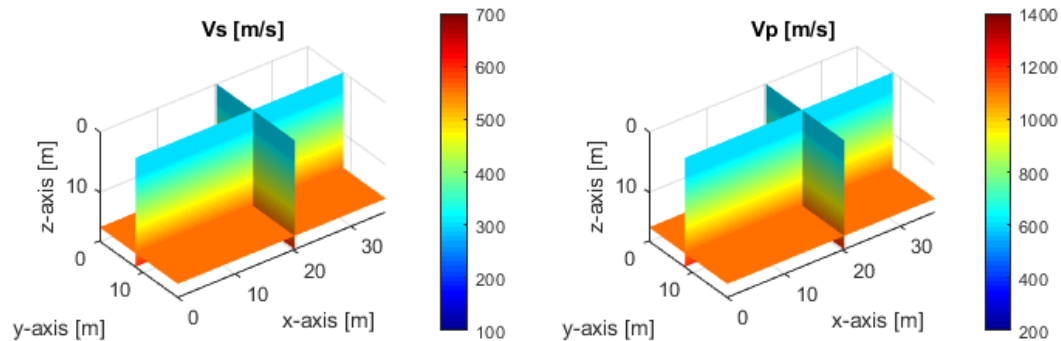


➤ Sample data for a shot

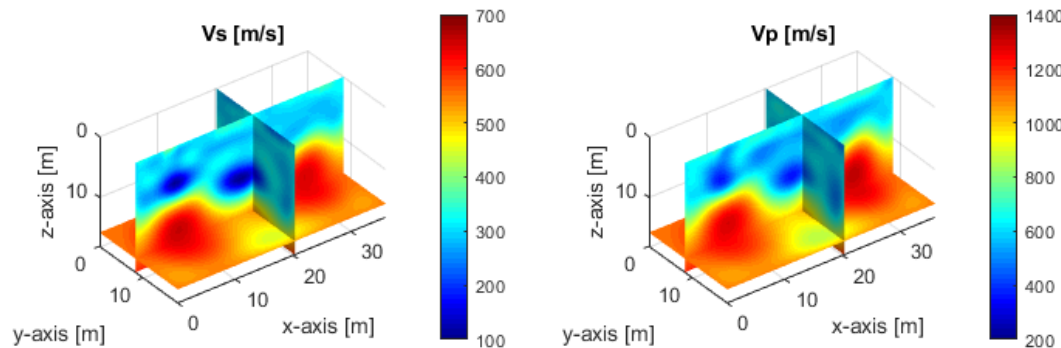


Synthetic result: 3D view

- 2 inversion runs at 15 and 25 Hz central frequencies
- 40 hours on a desktop computer (40 cores of 2.4 GHz each and 1.0 TB RAM)

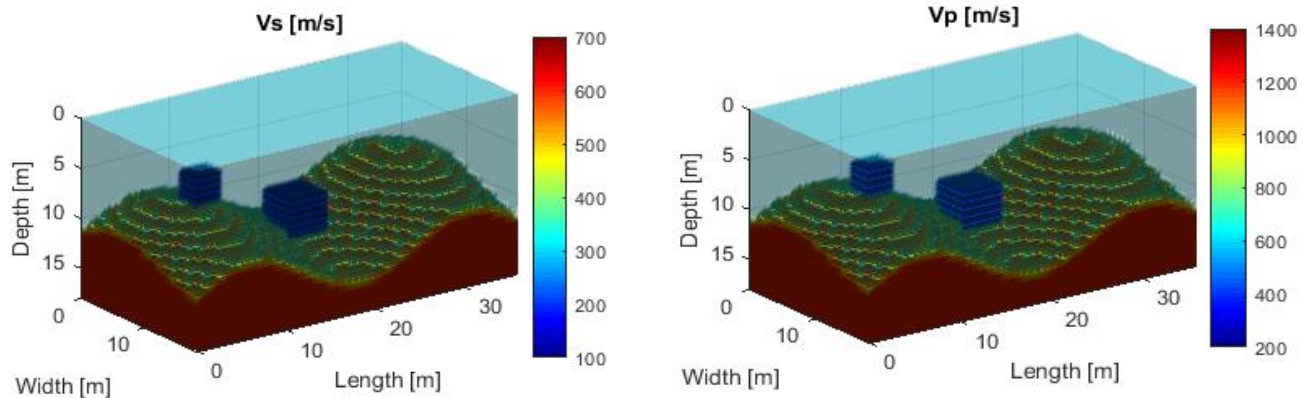


Initial model

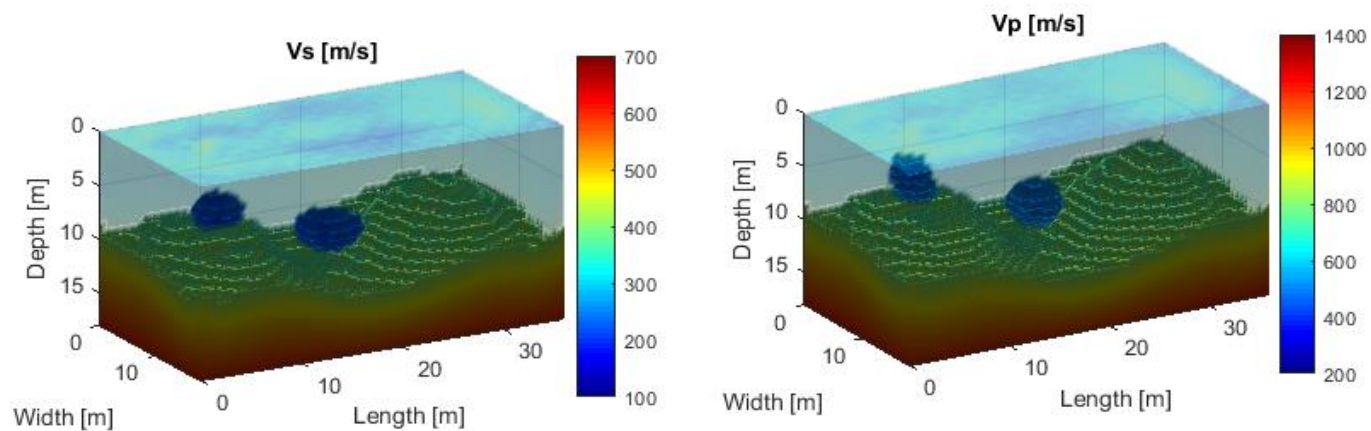


Inverted result

Synthetic result: 3D rendering



True model

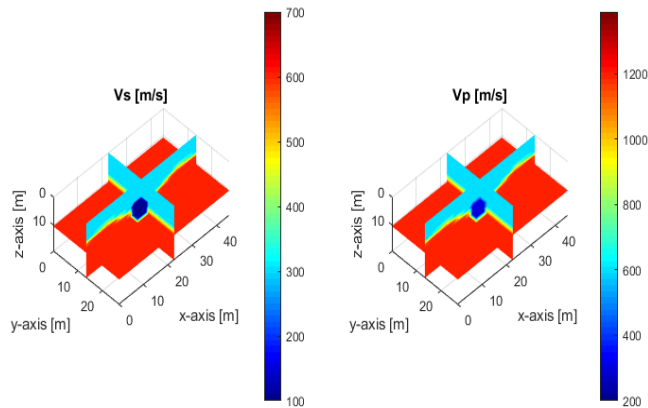


Inverted model

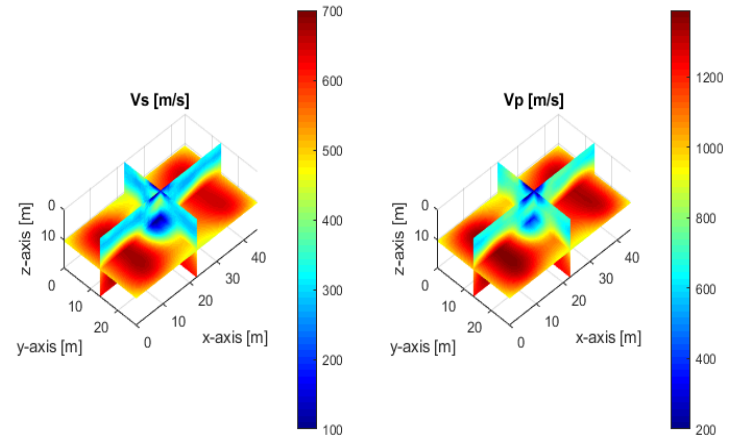
How deep a buried void can be detected by 3D FWI of surface data?

- detectable depth of a void depends on:
 - 1) Void size
 - 2) Test configuration
(receiver/shot number and spacing)
 - 3) Frequency content of measured data
(8 to 60 Hz for PEG or sledgehammer)

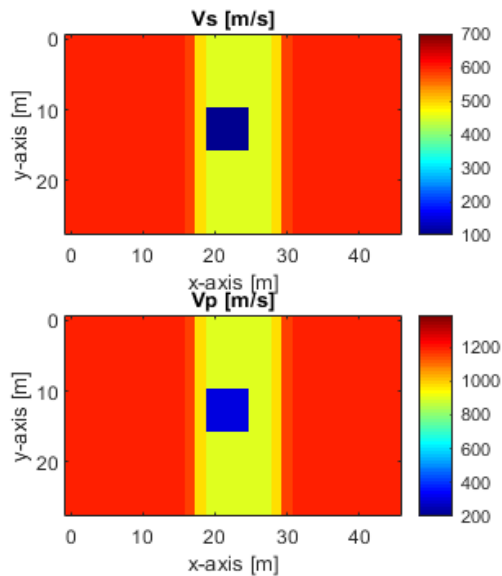
Void at depth of 2 diameters (30 ft)



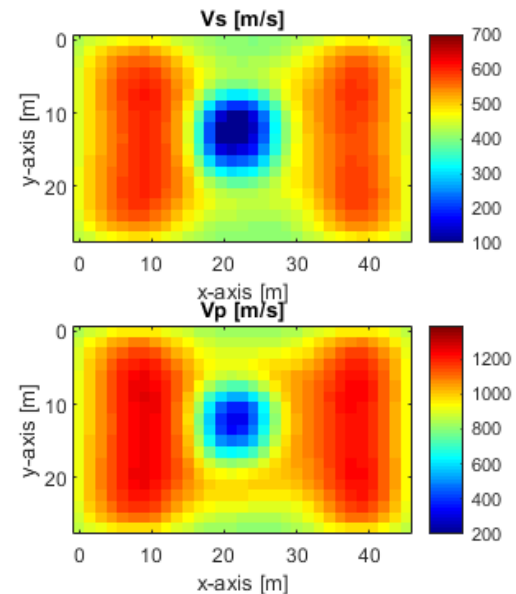
True



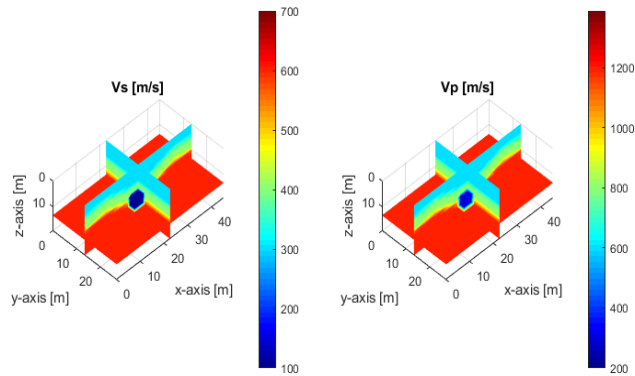
Inverted



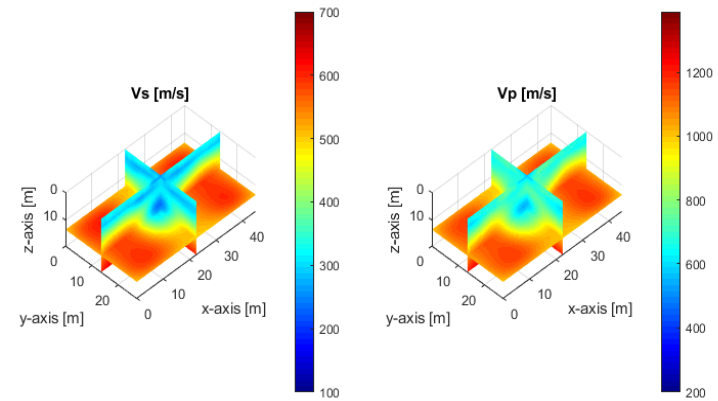
Horizontal view
@ void center



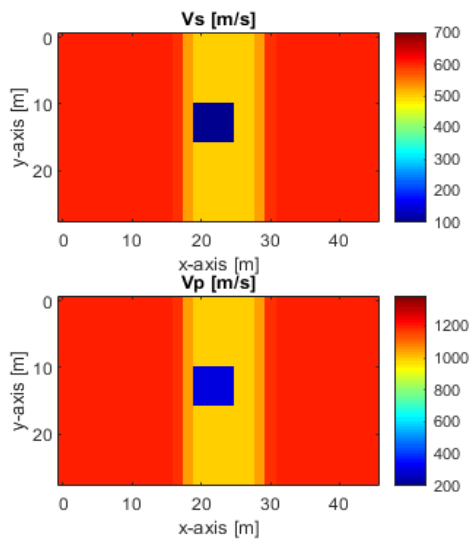
Void at depth of 3 diameters (45 ft)



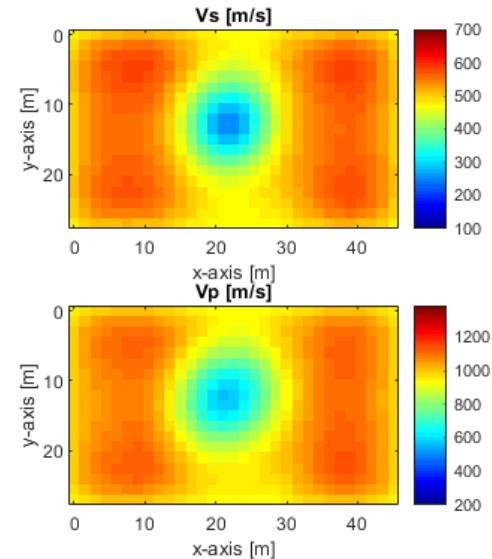
True



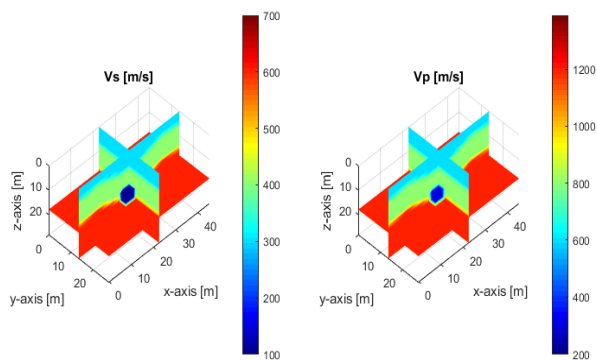
Inverted



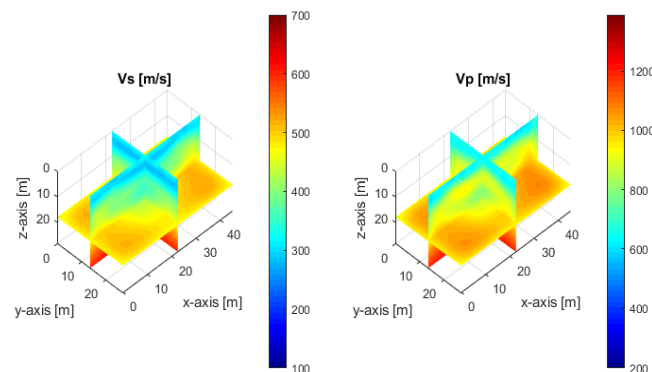
Horizontal view
@ void center



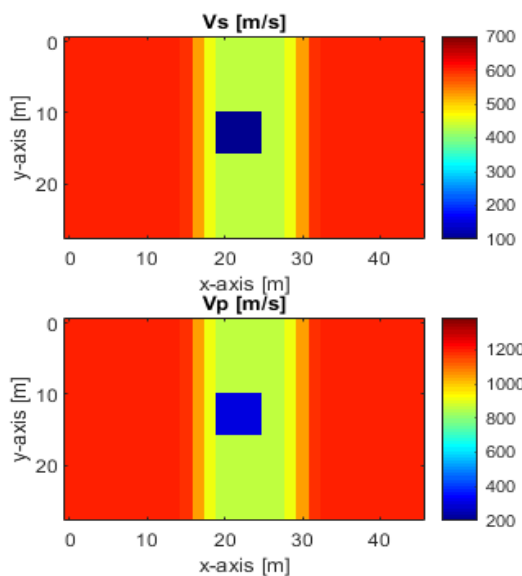
Void at depth of 4 diameters (60 ft)



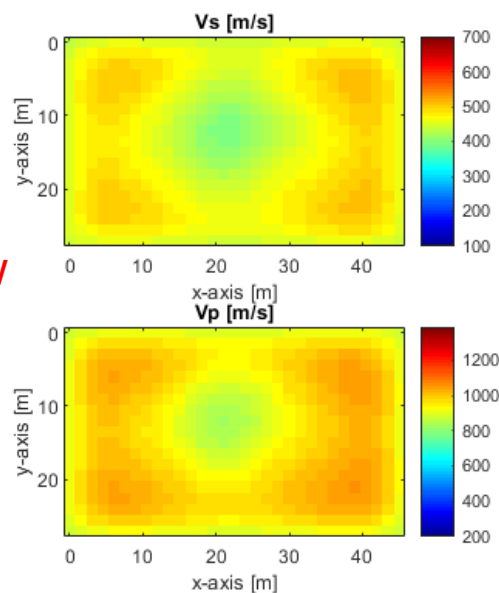
True



Inverted



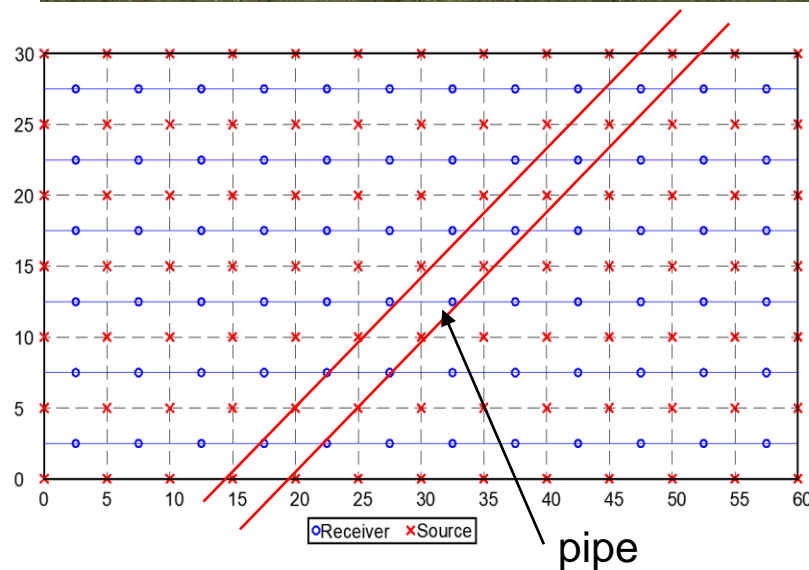
Horizontal view
@ void center



Verification of 3D FWI on Field Experiments

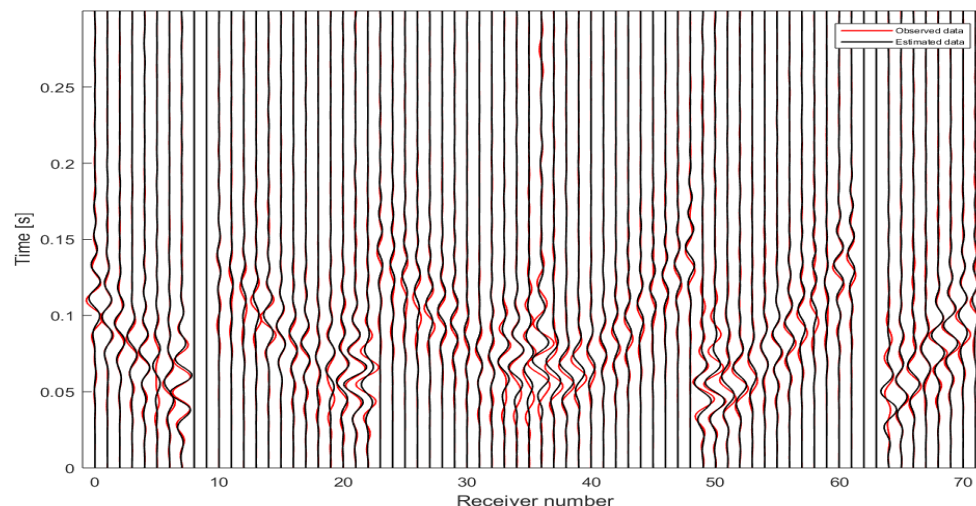
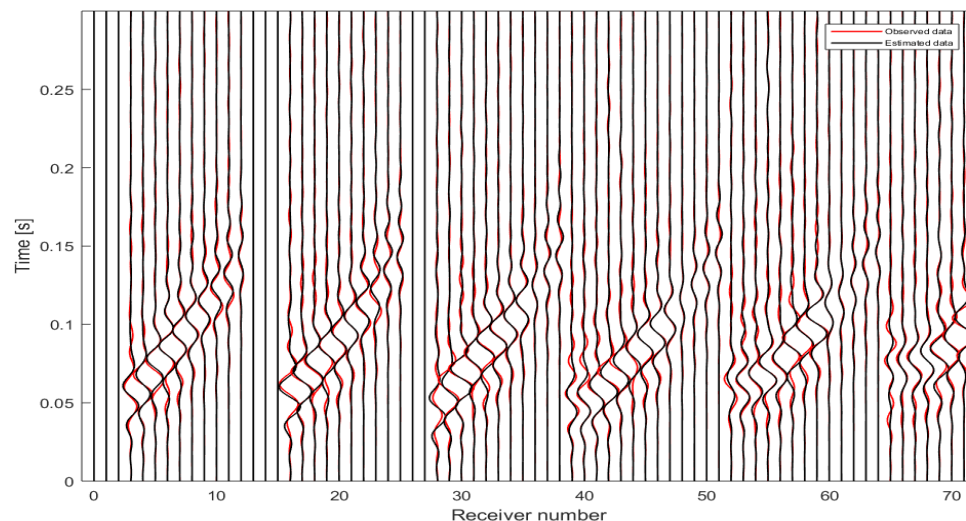
1) UF Campus: Stormwater Pipe

- Plastic stormwater pipe: 40" diameter, buried at 10 ft depth.
- Test area of 30 x 60 ft
- 72 geophones located in 12 x 6 grid at 5 ft spacing
- 91 shots located in 13 x 7 grid at 5 ft spacing
- 10 lb. sledgehammer

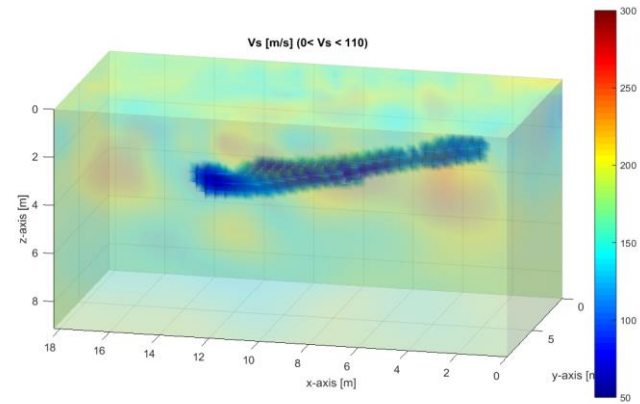
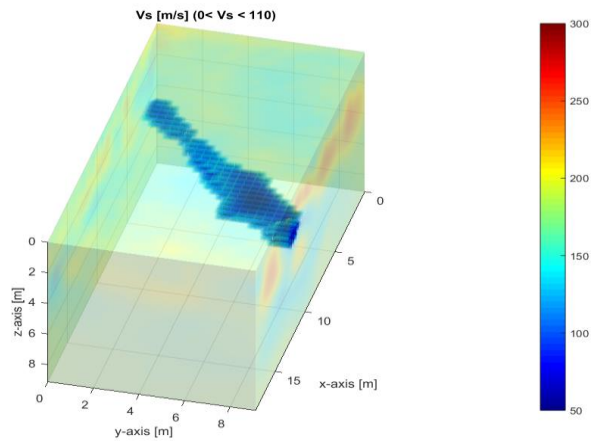
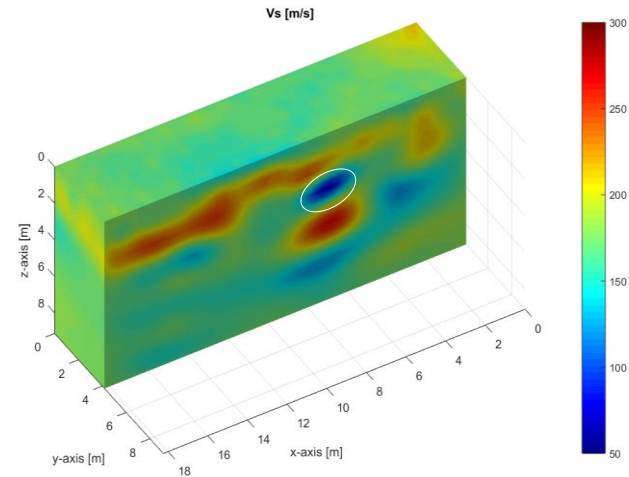
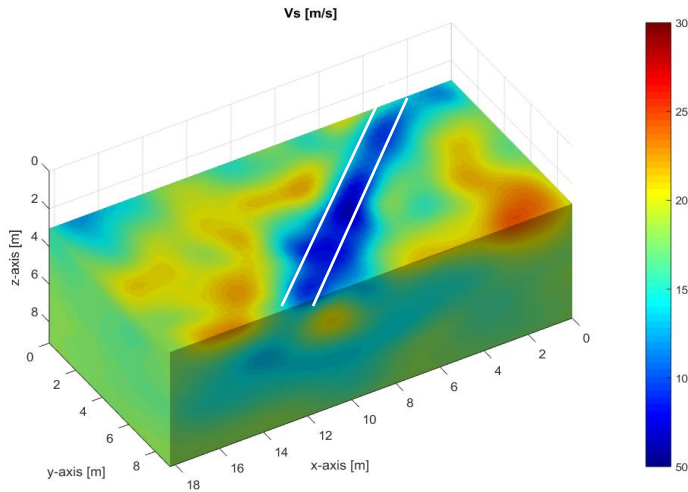


UF campus: stormwater pipe

- Test domain is divided into 27,000 cube cells of 1.25 ft size
- One inversion run from 10 to 60 Hz
- 15 hours of computer time on a desktop computer

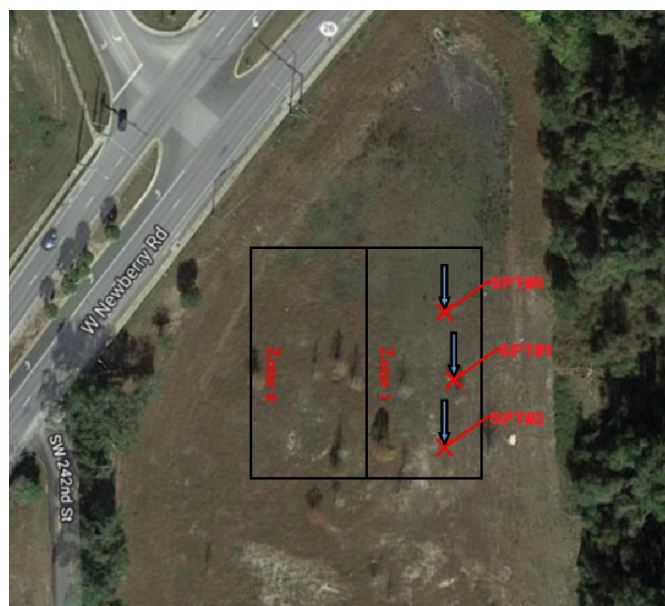
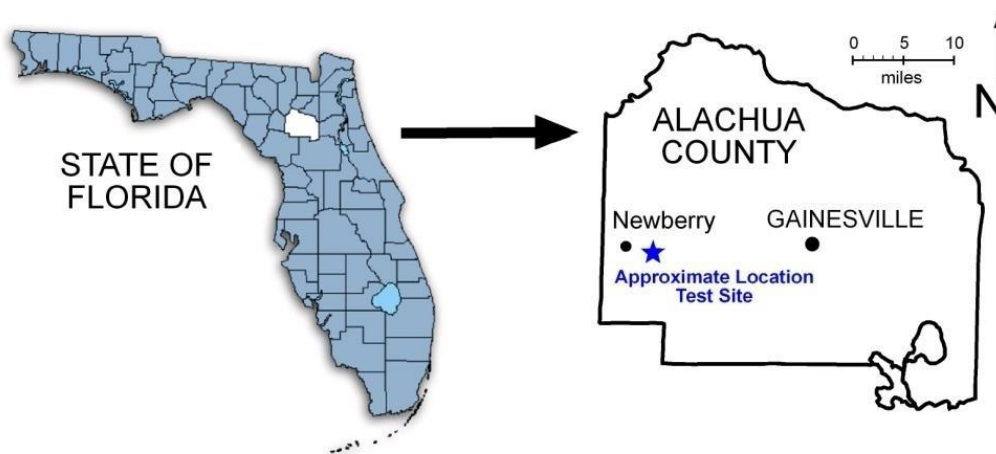


UF campus: stormwater pipe



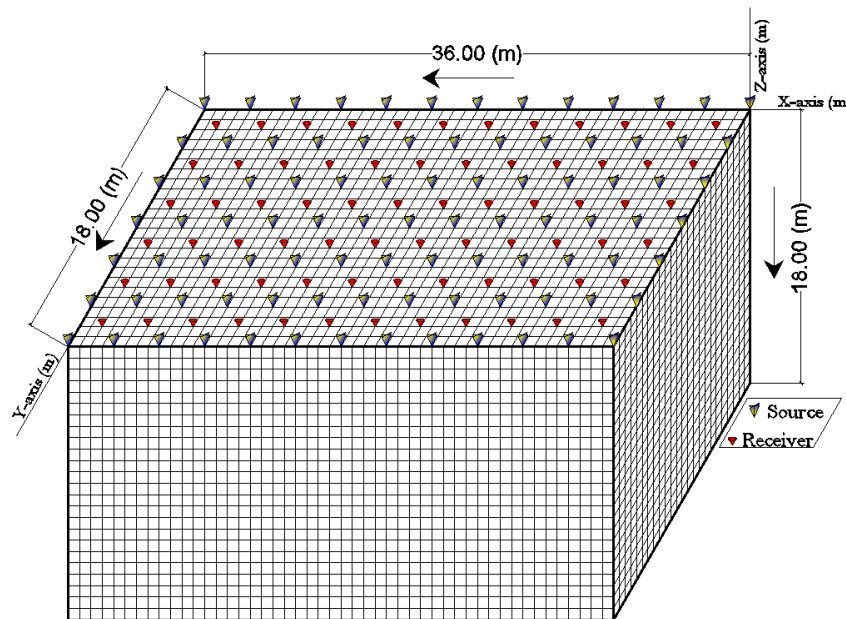
2) Newberry site

- Dry retention pond in Newberry, FL
- Top of bedrock from 2-10 m depth
- Site was marked by 25 lines (A to Y) at 3 m spacing
- Conducted blind tests on 2 new areas, each of 60 x 120 ft



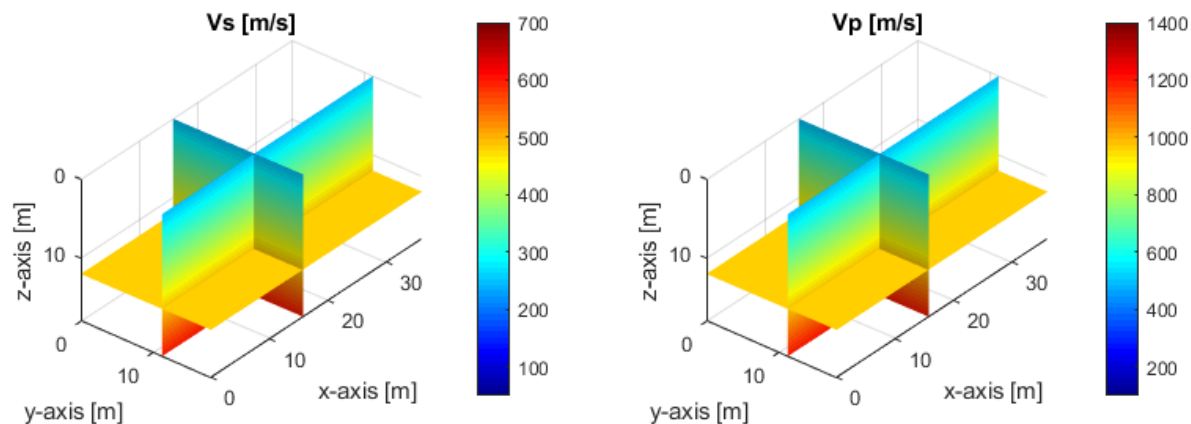
Newbery site

- Test area of 36 x 18 m (120 x 60 ft)
- 72 geophones located in 12 x 6 grid at 3 m (10 ft) spacing
- 91 shots located in 13 x 7 grid at 3 m spacing
- Propelled energy generator (PEG-40 kg) source

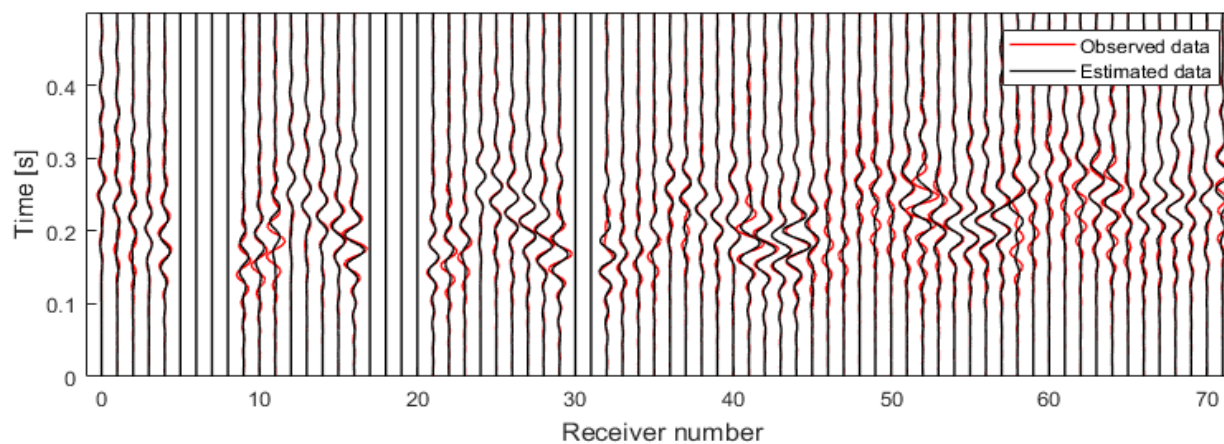


Newberry analysis

- 2 inversion runs at 15 and 25 Hz central frequencies
- 40 hours on a desktop computer

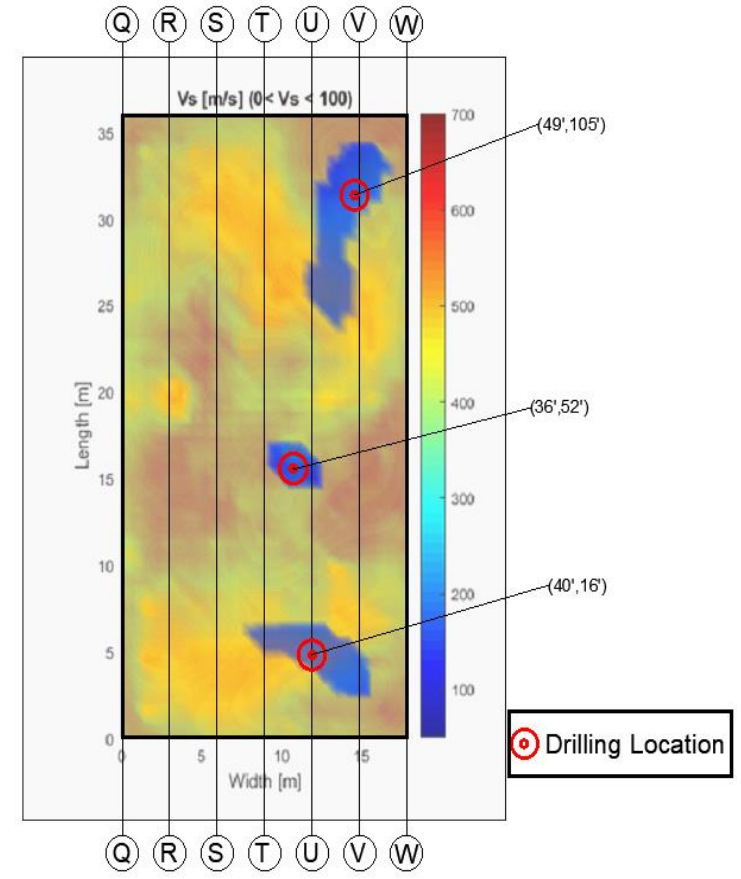
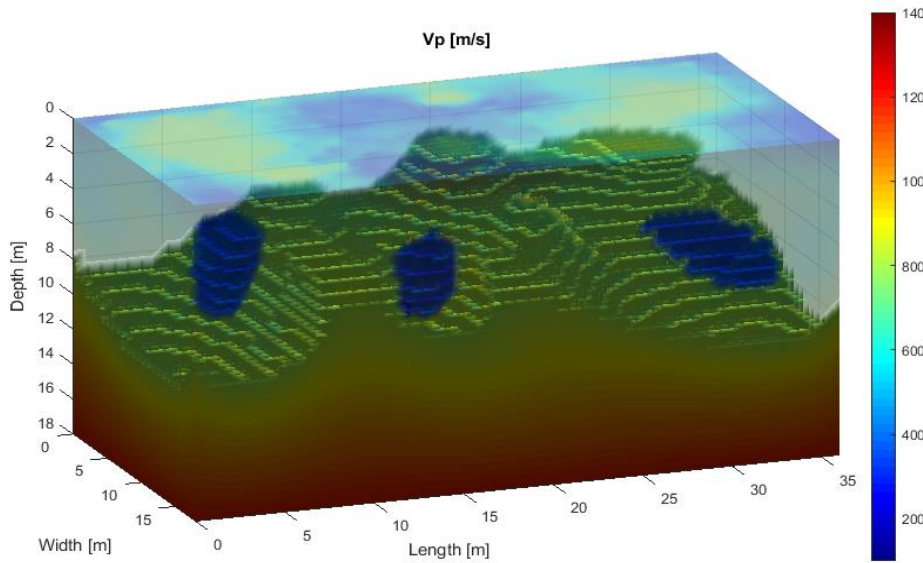
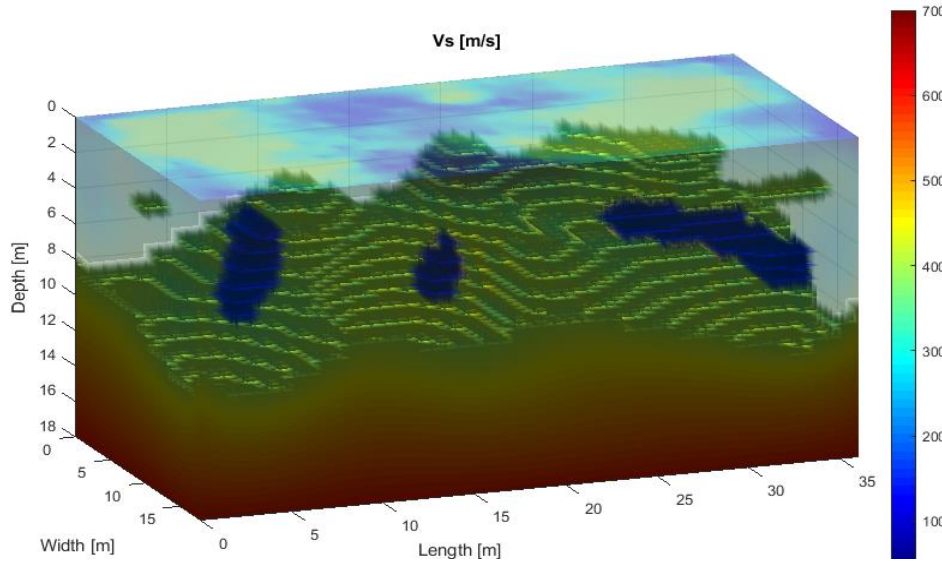


Initial model

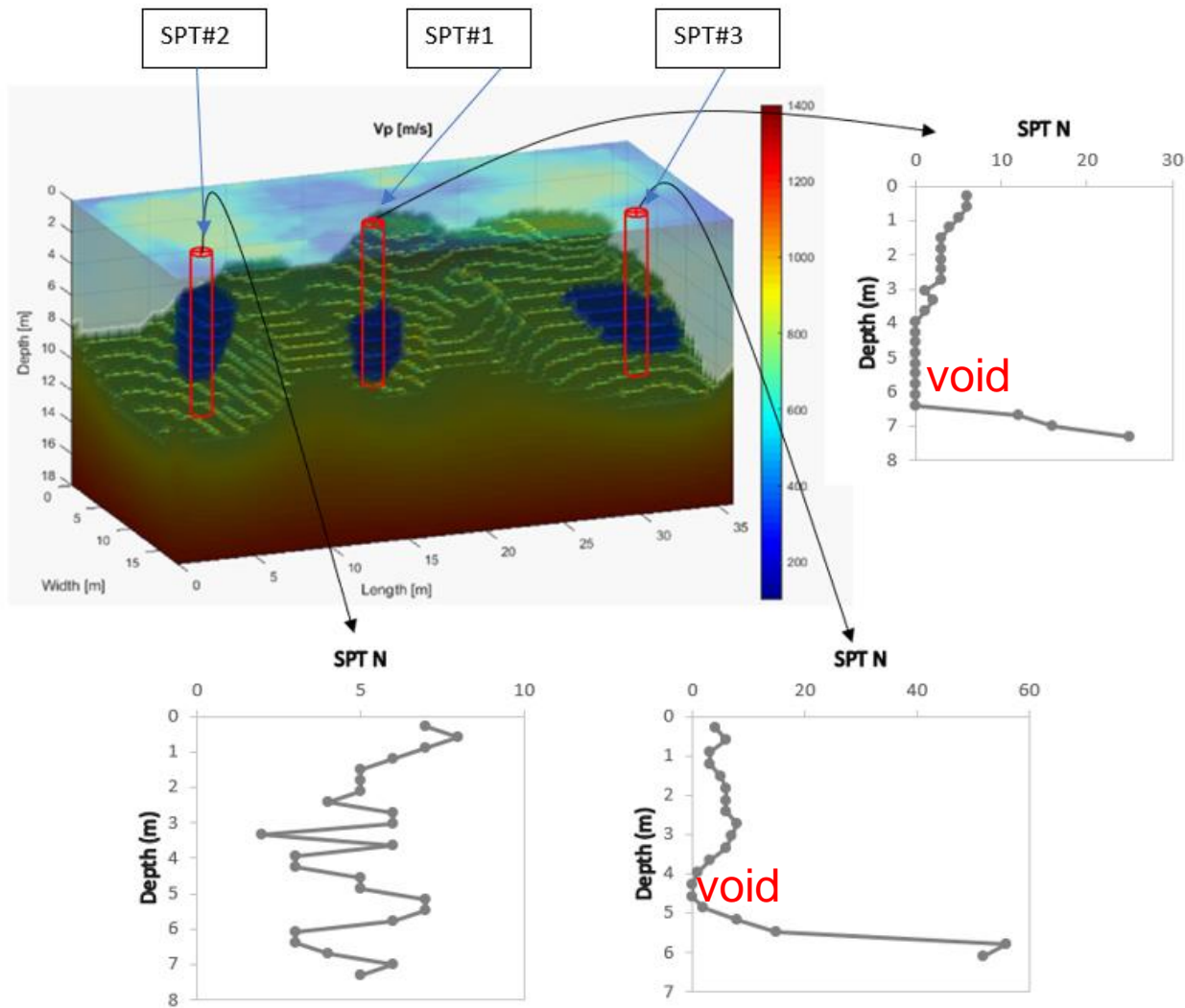


Wave comparison

Newberry result: 3D rendering

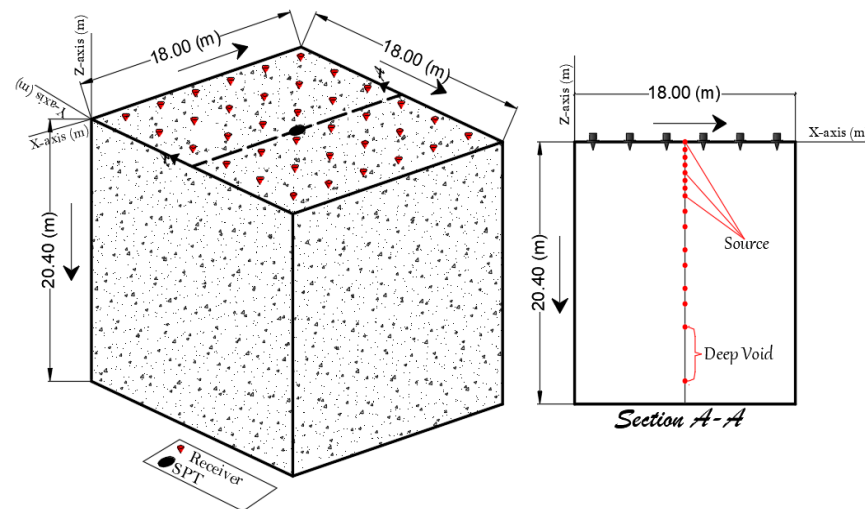


SPT confirmation



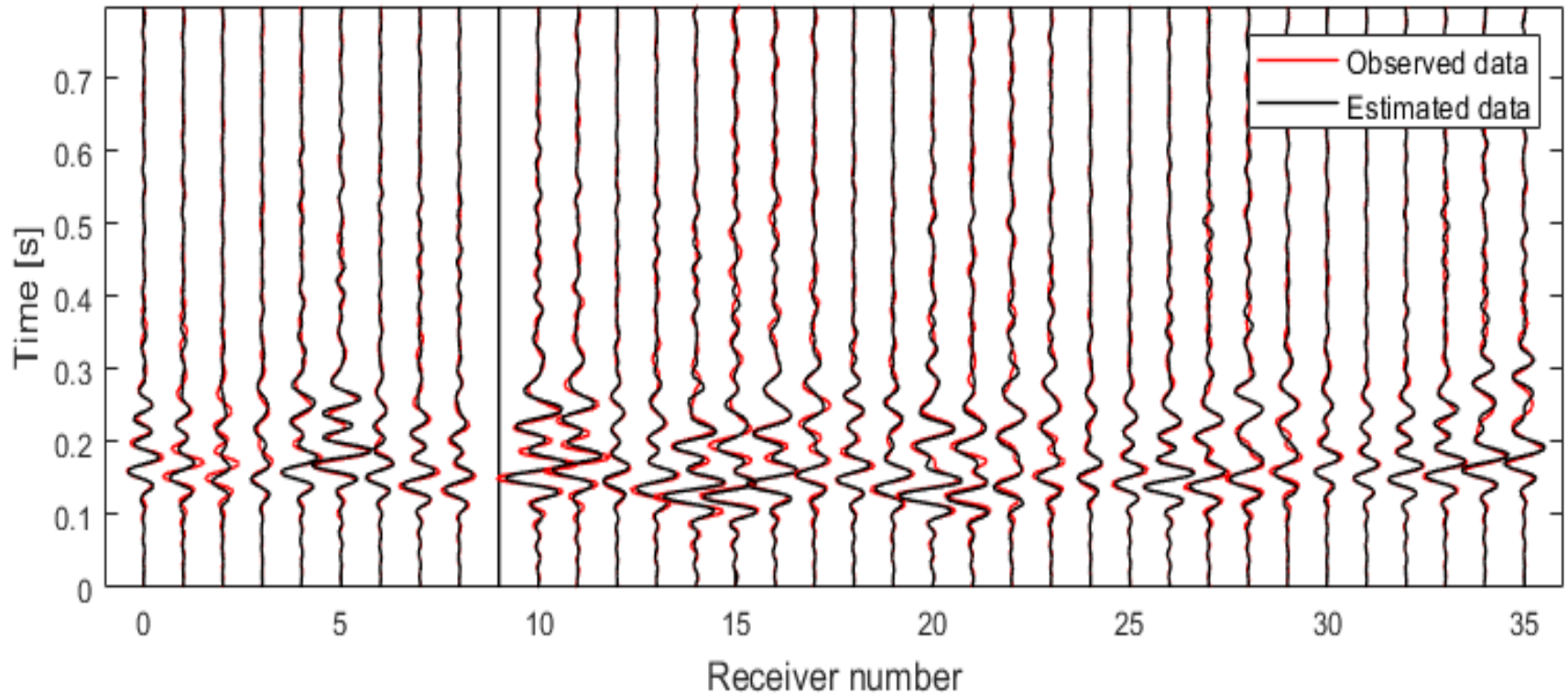
Newbery site: SPT-seismic

- In-depth source is rich of body waves for high-resolution imaging at deeper depth
- Test area of 60 x 60 ft (18 x 18 m)
- 36 geophones located in 6 x 6 grid at 10 ft spacing
- SPT-seismic source at depths of 2 ft intervals
- Trigger is attached to SPT rod to activate seismograph



Newbery site: SPT-seismic

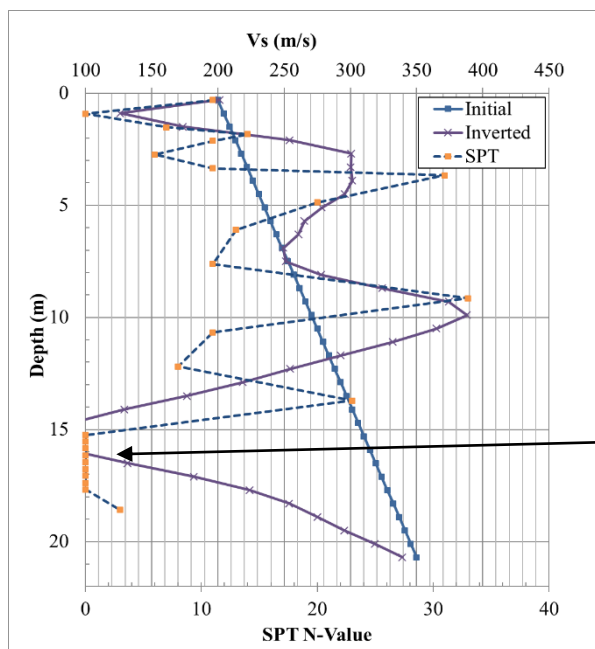
- SPT-seismic data is analyzed by the developed 3D FWI



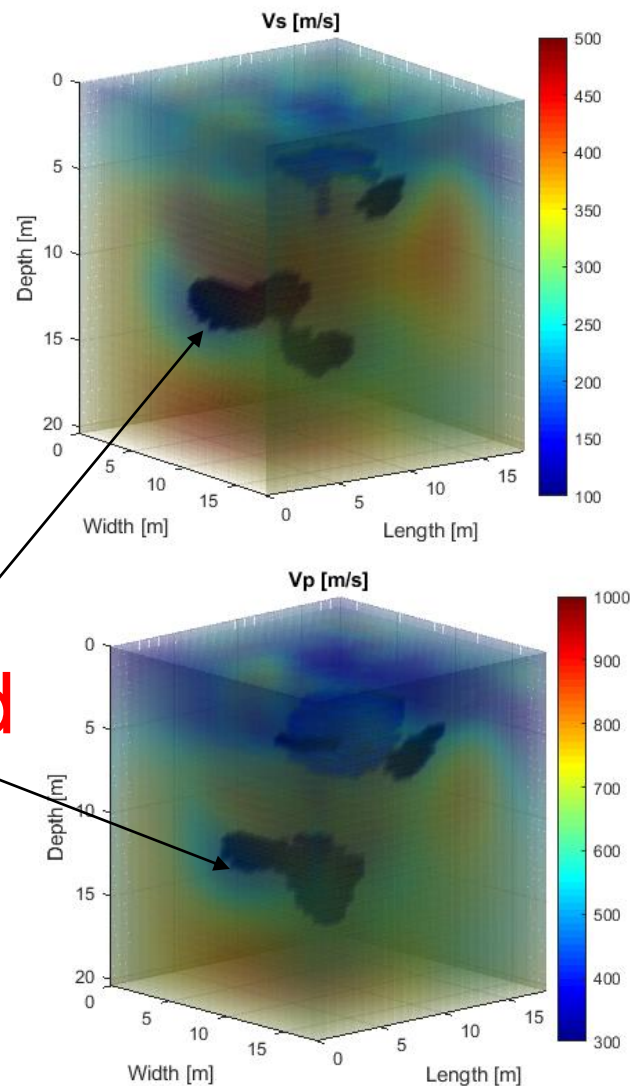
Comparison of wavefield generated by SPT at 18-m depth

Newbery site: SPT-seismic

- SPT-seismic data is analyzed by the developed 3D FWI

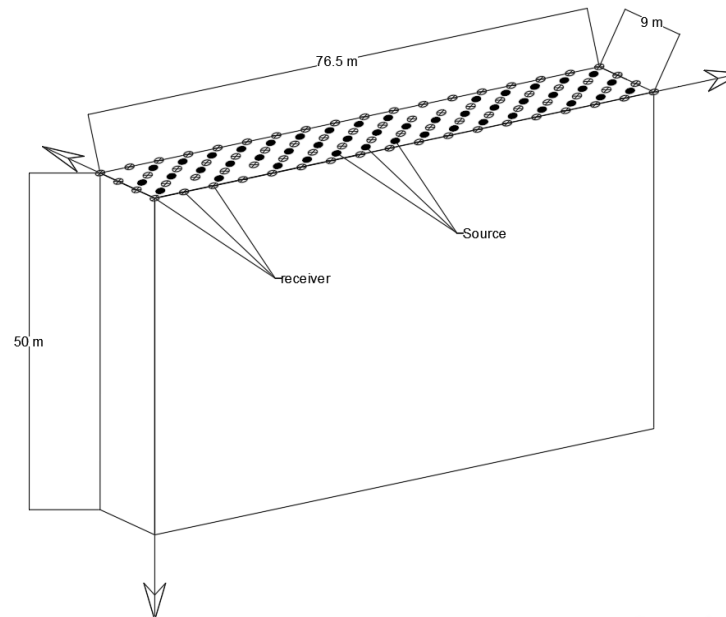


void

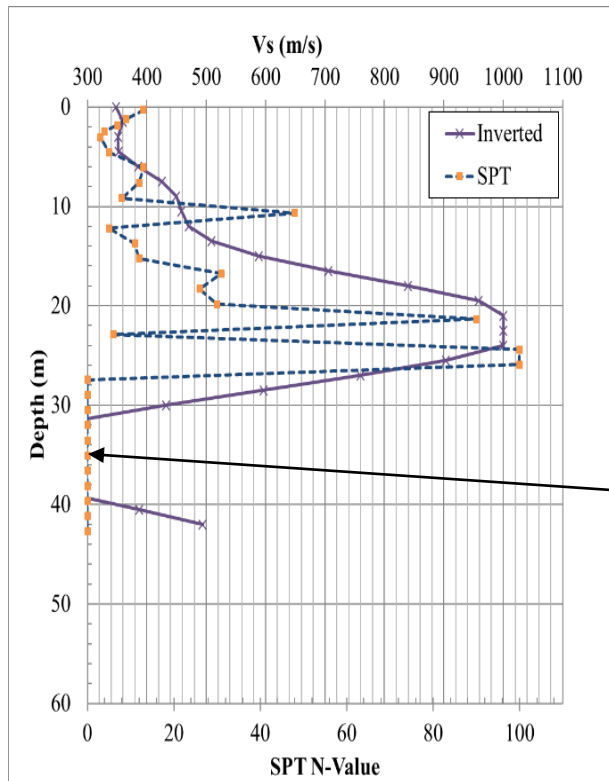


3) Miami site: surface test

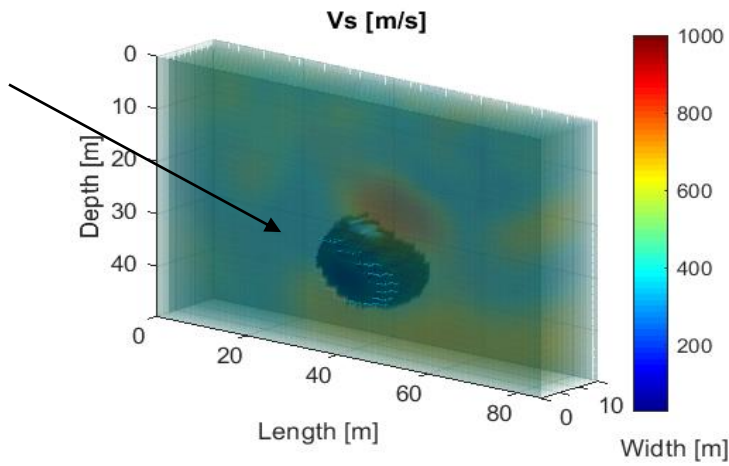
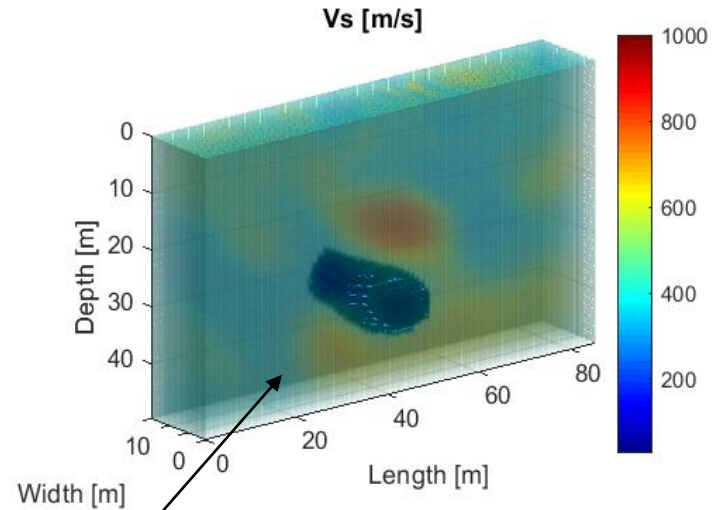
- Imaging a large and deep void (60 ft diameter at 80-140 ft depth)
- Surface testing with heavy source (Big Bang, 340 kg drop weight)
- 72 geophones located in 18 x 4 grid at 15'x10 ft spacing



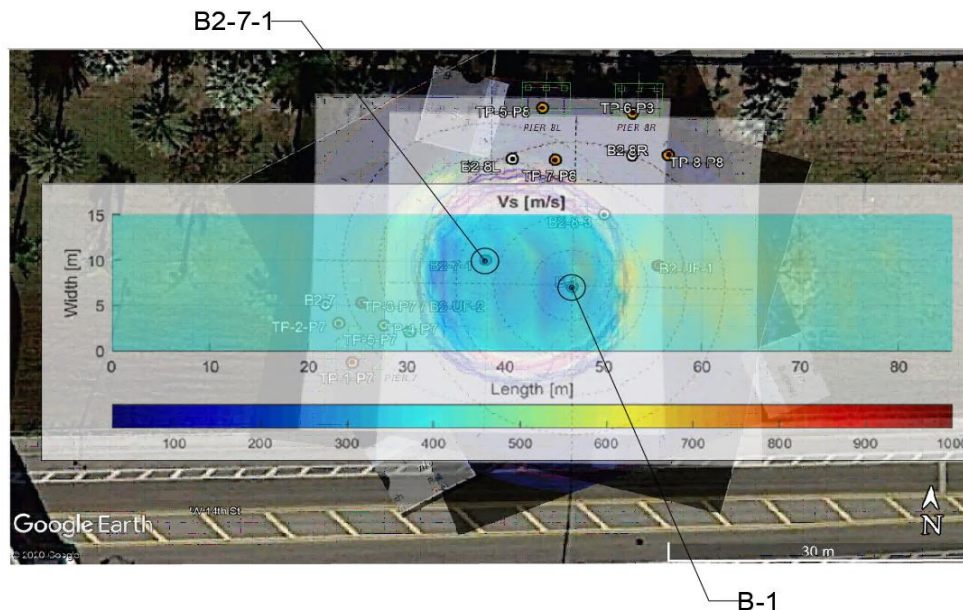
Miami site: surface test results



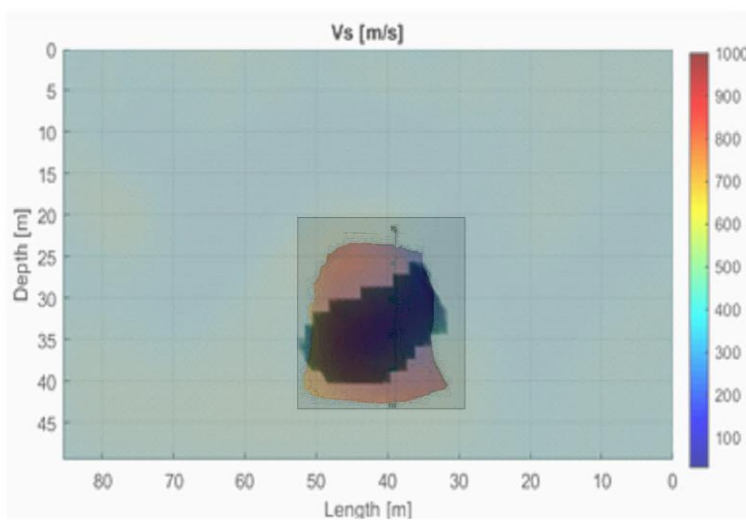
void



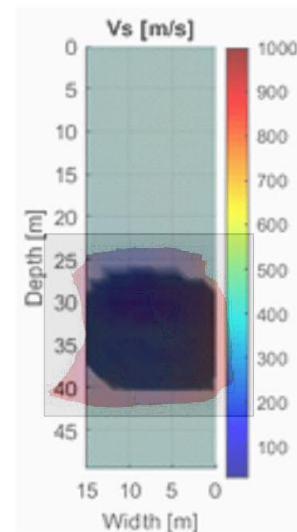
Miami site: surface FWI vs sonar



Top-down overlay



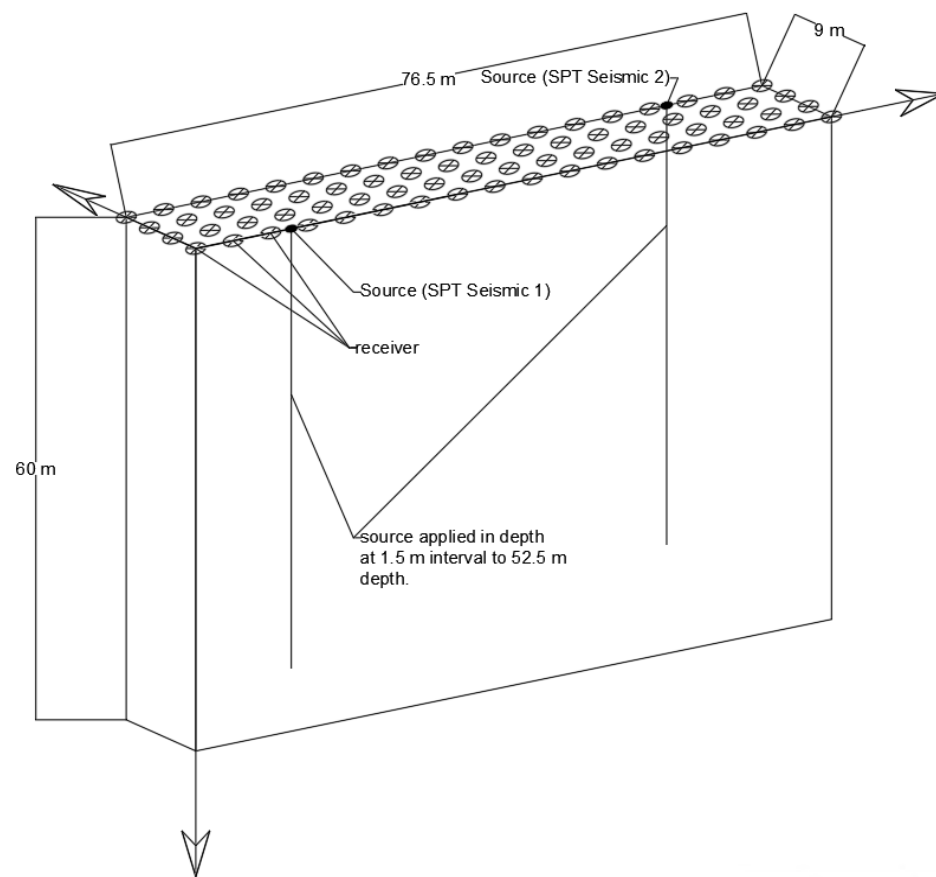
North-south overlay



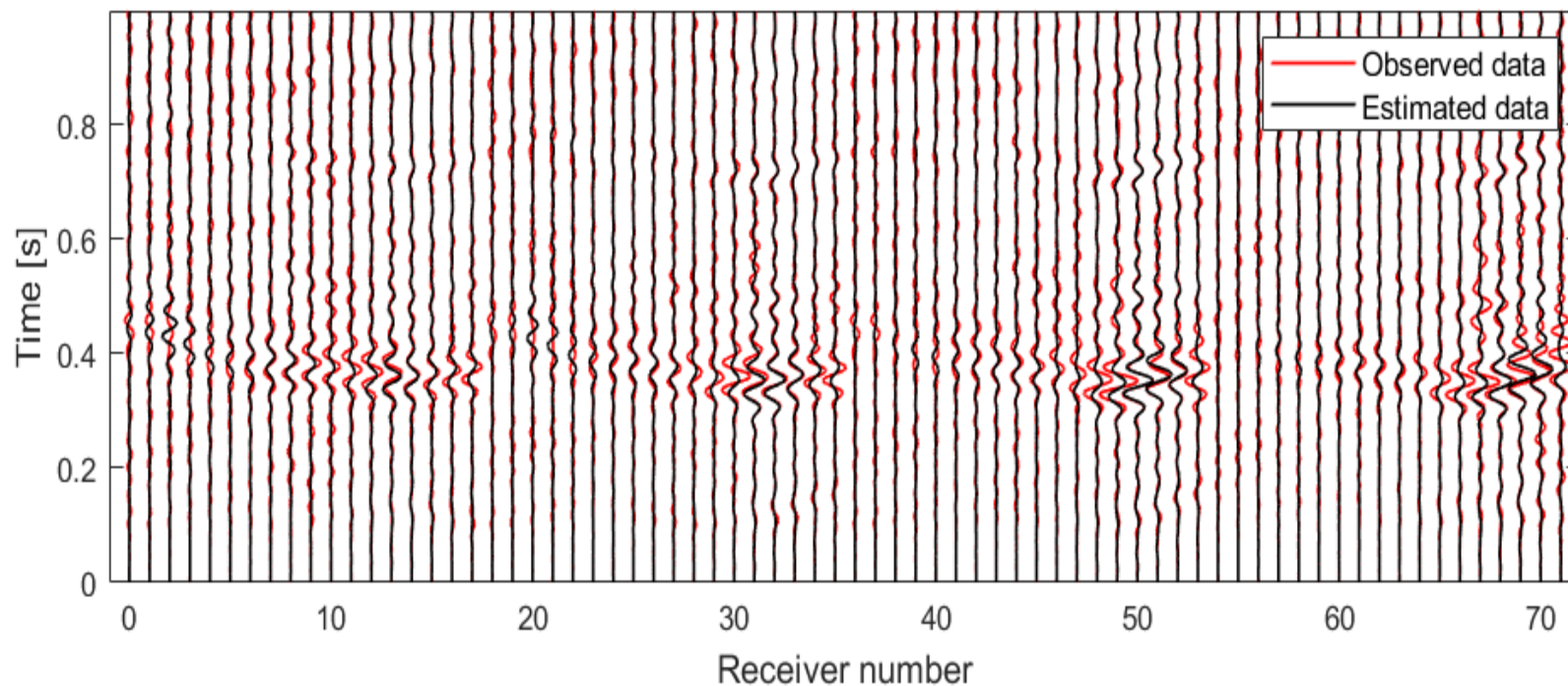
East-west overlay

Miami site: SPT-seismic

- 2 SPTs to 175 ft depth at 5' intervals
- 72 geophones located in 18 x 4 grid at 15'x10' spacing

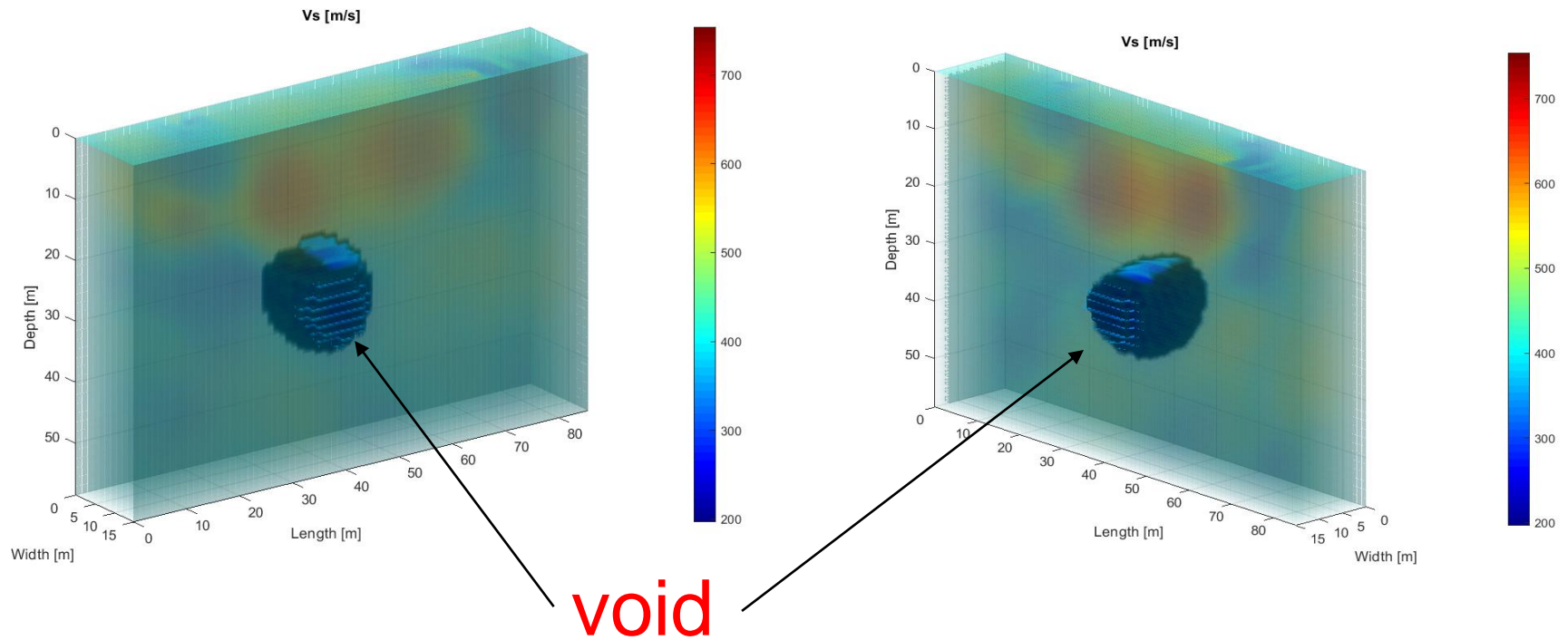


Miami site: SPT-seismic

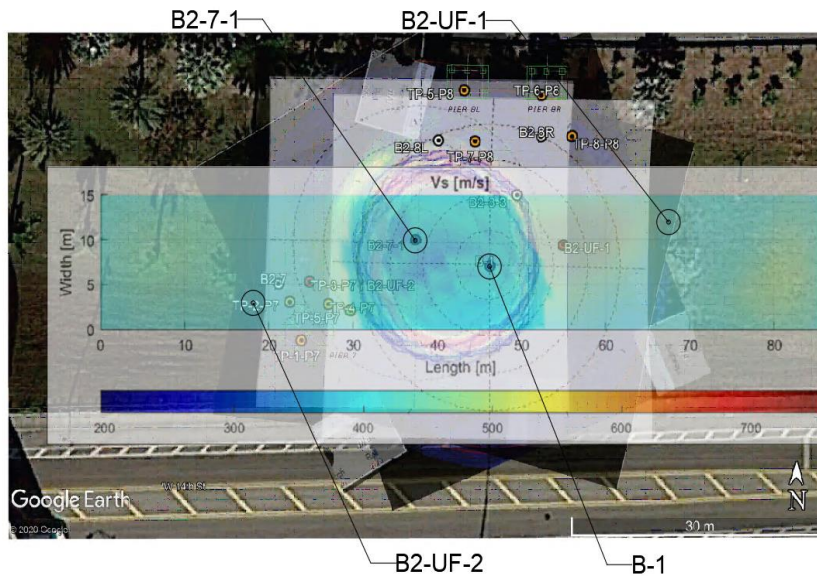


Comparison of wavefield generated by SPT source

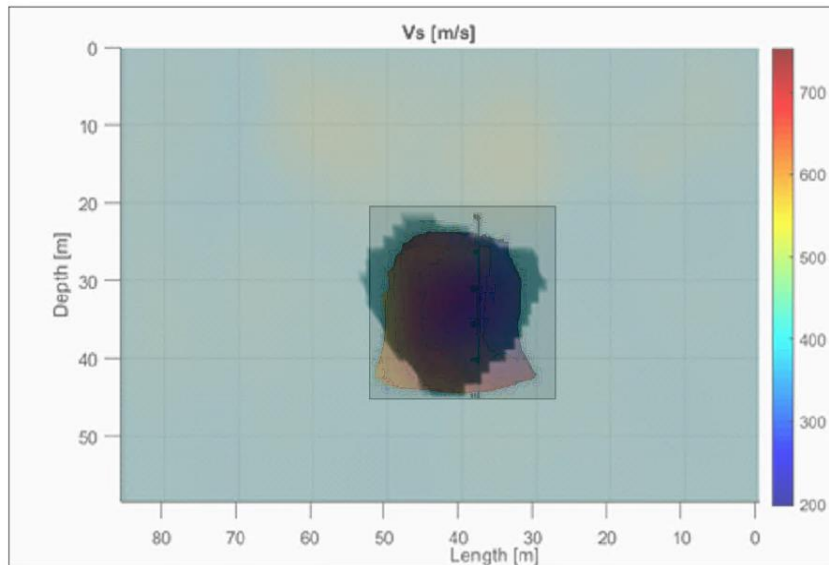
Miami site: SPT-seismic results



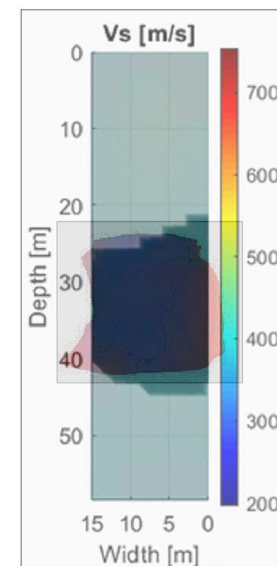
Miami site: SPT-seismic FWI vs Sonar



Top-down overlay



North-south overlay



East-west overlay

Summary of Research Conclusions

- We have successfully developed a novel 3D FWI for void detection at high resolution and accuracy
- For surface testing, both V_s and V_p can be characterized at 2-ft resolution to 60 ft depth, and at 5-ft resolution to 150 ft depth
- Buried voids can be identified to 3-diameter depth with only surface measurement
- For SPT-seismic, soil/rock and void can be characterized within 30' around SPT location to the boring depth.
- 30 - 40 hours of computer time for each test area of 120 x 60 ft

Recommendations

- Surface seismic testing
 - Used when surface area is available for sufficient 2D grid of geophones
 - Depth of investigation $\sim \frac{1}{2}$ larger dimension of geophone grid
 - Geophone spacing ~ 1 -2 times of targeted void diameter
 - Maximum wavelength $>$ depth of investigation

- For SPT-seismic testing
 - Used whenever conducting SPT, particularly for case limited test area (right of way)
 - Record data at 2-5 ft intervals

Project Benefits

- Florida has significant soil/rock uncertainty (layering & properties), karst features (sinkholes) as well as weathered conditions (soil & rock interleaved) with less than 0.1% of soil/rock tested (SPT) on a site
- New 3D FWI allows voids/sinkholes, soil/rock layering to be accurately characterized in 3D at high resolution (2-ft pixel to 60 ft depth, and at 5-ft pixel to 150 ft depth), and provides much more subsurface information than 2D (Seismic, GPR, Resistivity) and 1D (SPT, CPT)
- The 3D FWI greatly reduces soil/rock uncertainty (layering, properties), and identification of karst features which reduces cost in the design, construction and maintenance of FDOT structures. For instance, in case of 60-ft void near the planned I-395 pier - the foundation may be either relocated or the planned foundation element (Auger Cast) may be changed (e.g. steel cased drilled shaft)

Further research

- Automation of SPT-seismic testing
 - Record seismic data for all blows without interference with SPT crew
 - Improve 3D FWI to analyze all recorded data for extraction of material properties at high-resolution (one foot pixel)

- Development of GUI software for 3D FWI method
 - Users can graphically input receiver/source locations, raw seismic data, condition and analyze data
 - Analyze surface data for 3D subsurface images over large volume
 - Analyze SPT-seismic data for detailed material properties

Publications

1. Mirzanejad M., Tran K.T., McVay M., Horhota D. and Wasman S. (2020), “Sinkhole detection with 3D full seismic waveform tomography” *Geophysics*, Vol. 85 (5), <https://doi.org/10.1190/geo2019-0490.1> (Impact Factor: 2.793).
2. Mirzanejad M., Tran K.T., McVay M., Horhota D. and Wasman S. (2020), “Coupling of SPT and 3D full waveform inversion for deep site characterization” *Soil Dynamics and Earthquake Engineering*, Vol. 36, 12 pages, <https://doi.org/10.1016/j.soildyn.2020.106196> (Impact Factor: 2.578).
3. Tran K.T., Mirzanejad M., McVay M., and Horhota D. (2019), “3D Time-Domain Gauss-Newton Full Waveform Inversion for Near-Surface Site Characterization”, *Geophysical Journal International*, 217, 206–218, (Impact Factor: 2.777).

Thank You!

