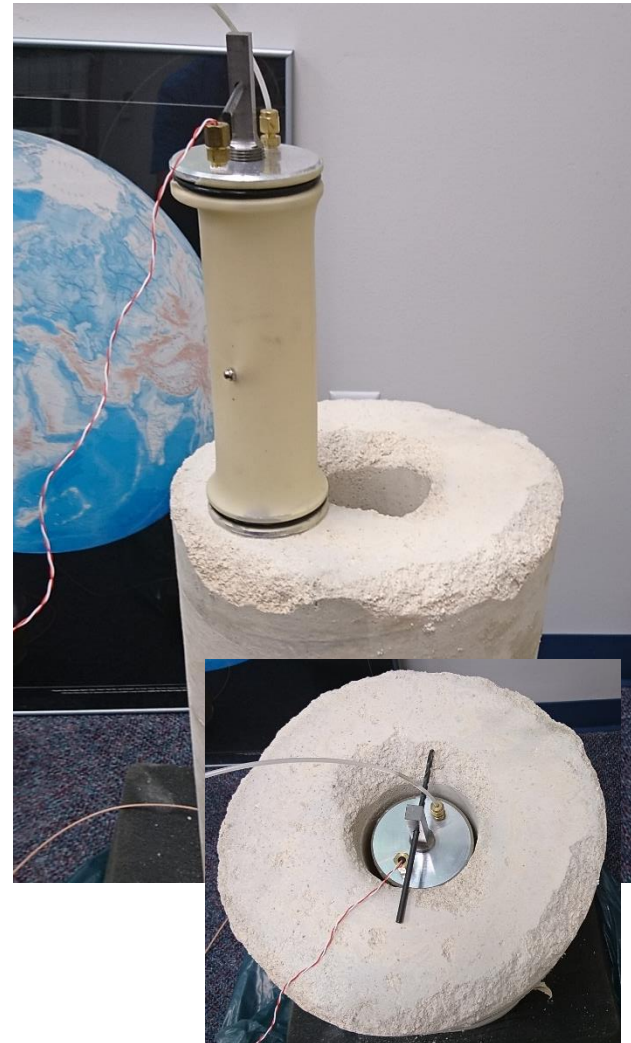


Implementation of Down-Hole Geophysical Testing for Rock Sockets

Dennis R. Hiltunen
University of Florida

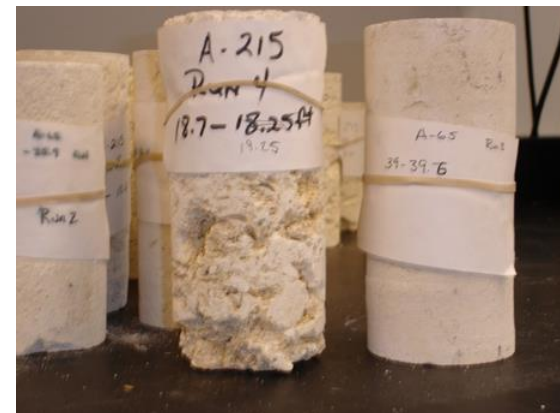
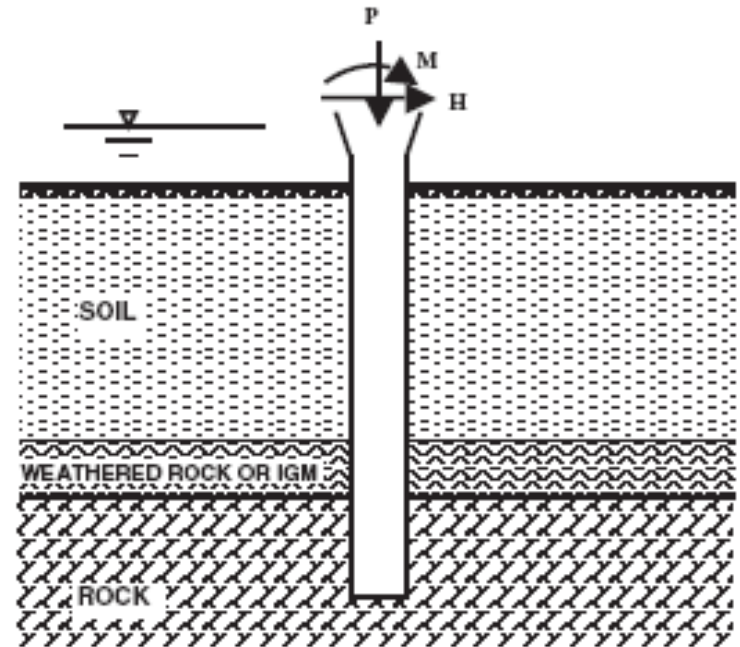
FDOT GRIP

August 9, 2018

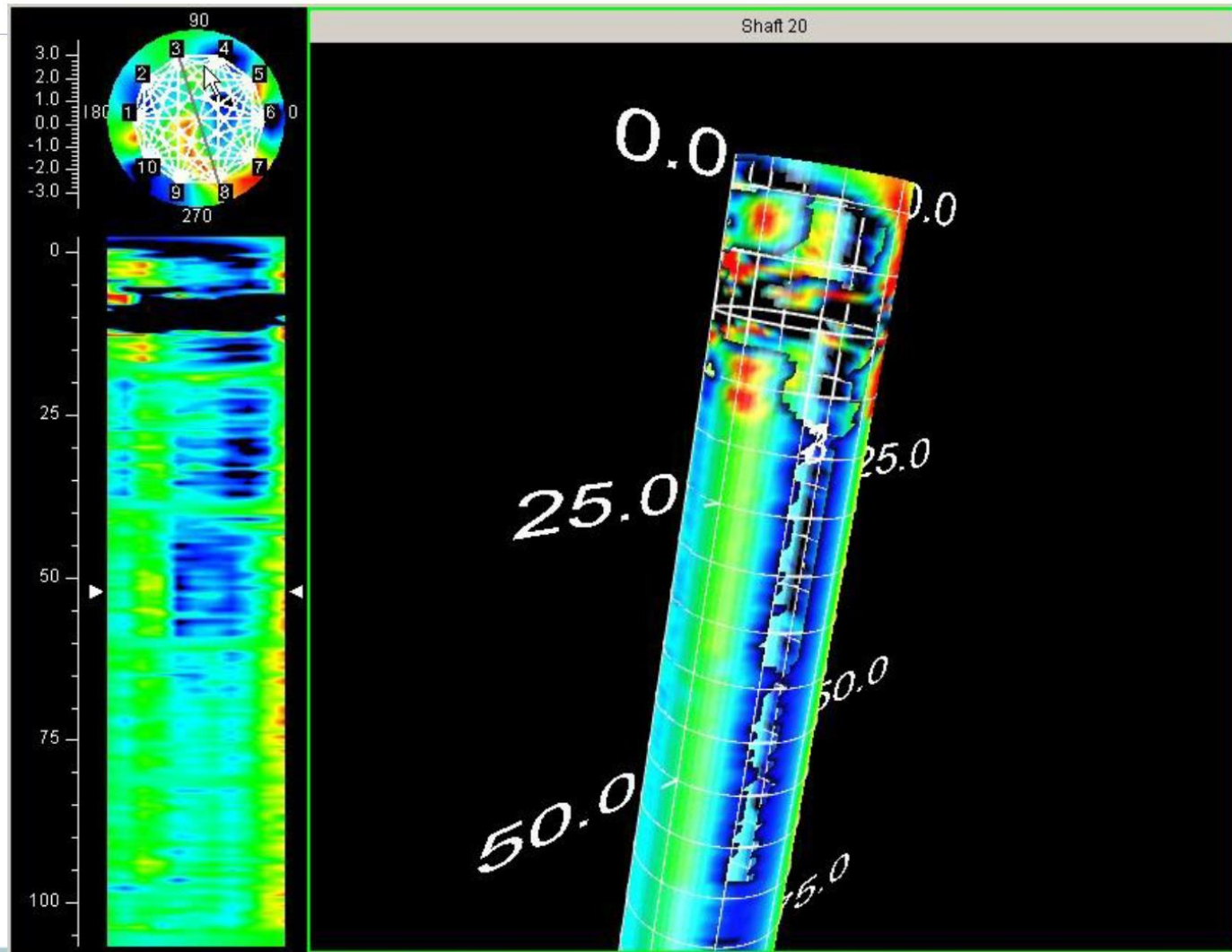


Geophysical Characterization of Rock Sockets

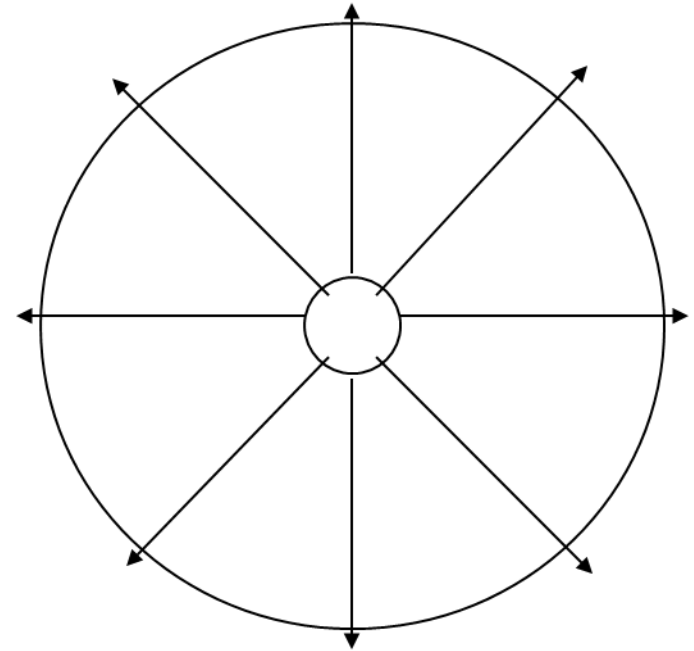
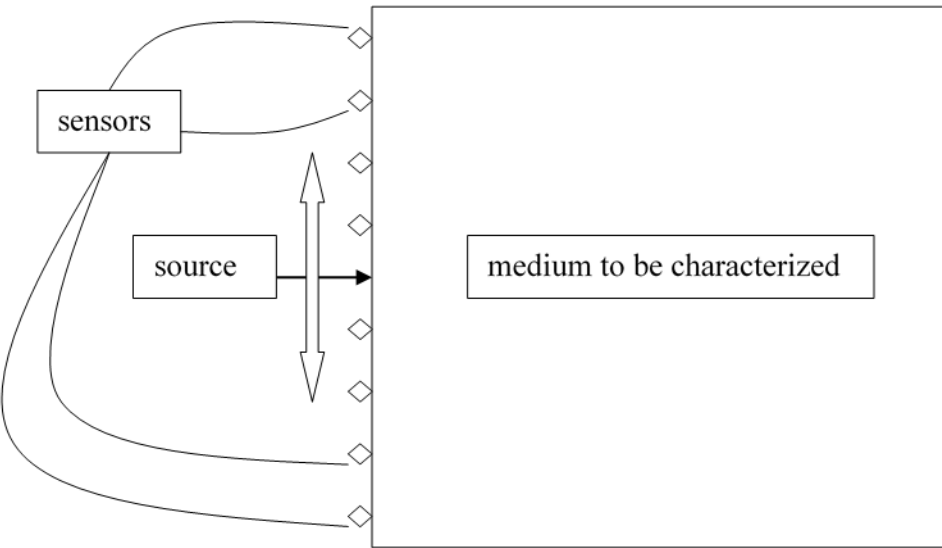
- Rock highly variable: extend characterization to ~5 ft laterally from borehole
- Develop geophysical technique to supplement boring cores and lab results
- Utilize only the one standard borehole
- Integrate with current boring, sampling, and testing tools



Geophysical Characterization of Rock Sockets



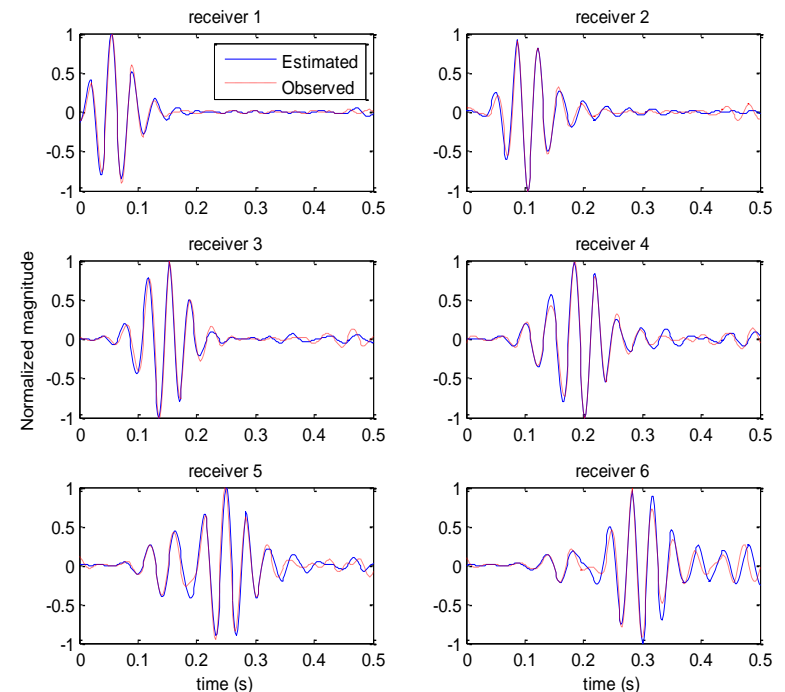
Borehole Tool Schematic



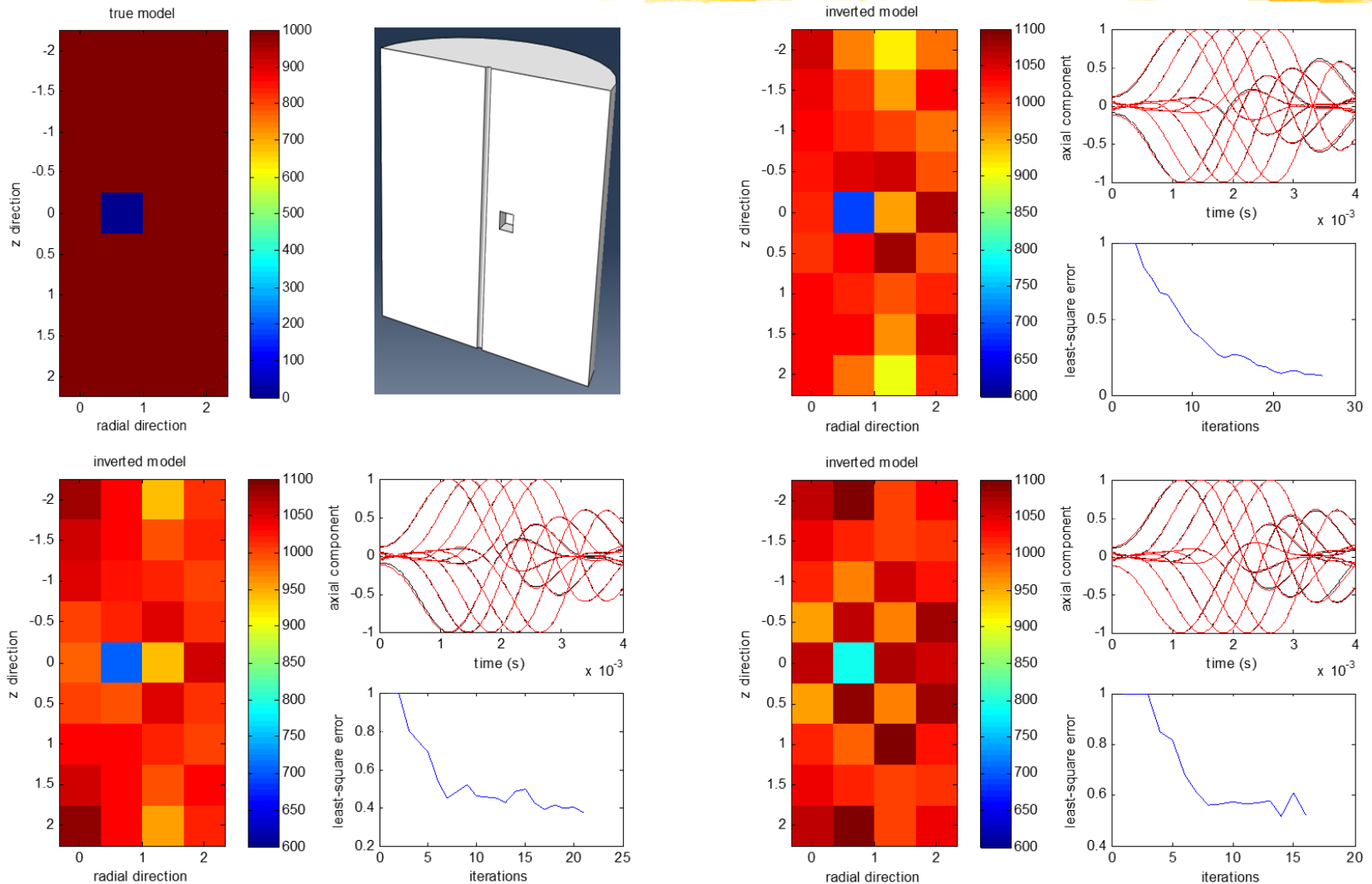
A joining of borehole instrumentation with full waveform inversion

Full Waveform Inversion (FWI)

- Invert for model parameters by matching full waveforms
- Complex profiles create difficulties for traditional techniques (e.g, G, T, O'N, L)
- Studies have demonstrated improved resolution with FWI
- Advancements in wave propagation modeling, inversion algorithms, and computing have made this possible
- Have demonstrated for some challenging synthetic and field data sets



Isolated Anomaly in Homogeneous

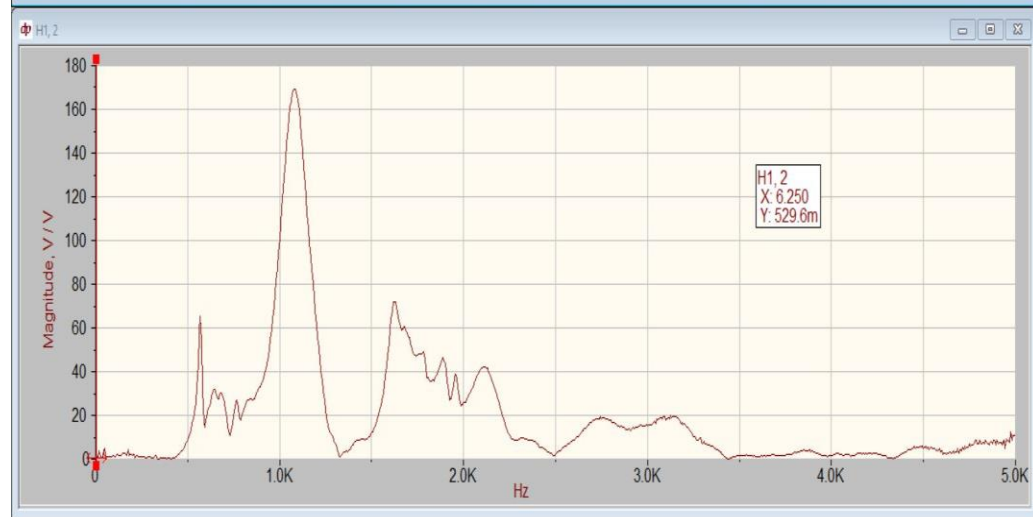
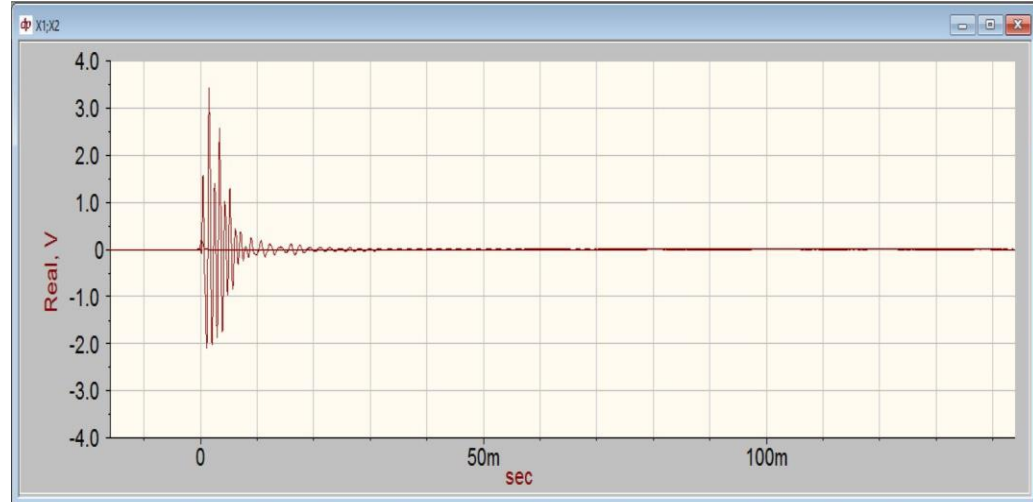


Workplan

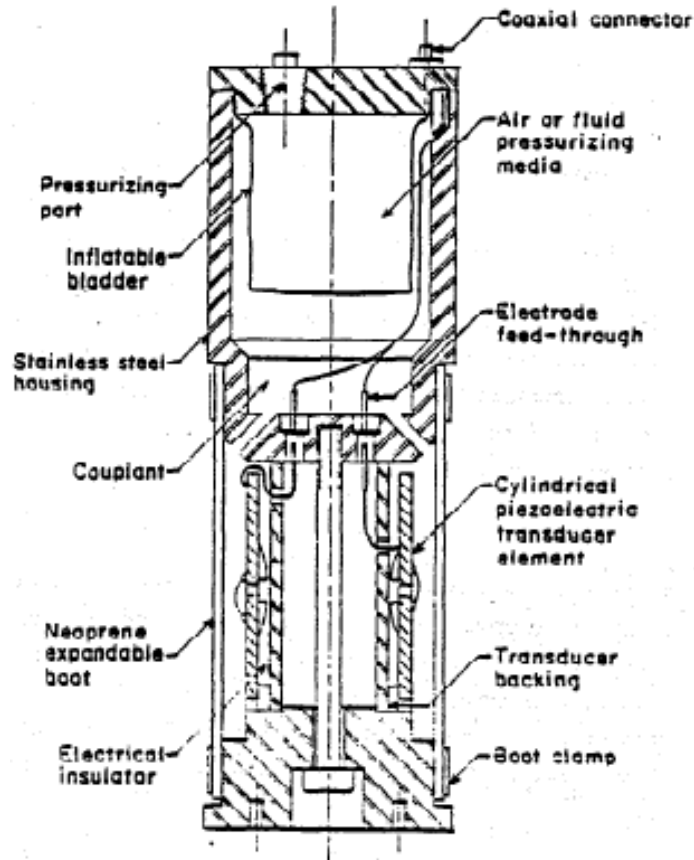


- **Task 1: Borehole Instrument**
 - **Source for generating seismic (mechanical) waves**
 - **Receiver array for capturing the wavefield**
- **Task 2: Inversion Software**
 - **ABAQUS forward model**
 - **Stand-alone forward model for borehole geometry**
 - **Artificial neural network (ANN) trained by ABAQUS**
- **Task 3: Validation Experiments**
 - **Large laboratory block of synthetic limerock**
 - **Newberry and Kanapaha test sites**
- **Task 4: Report**

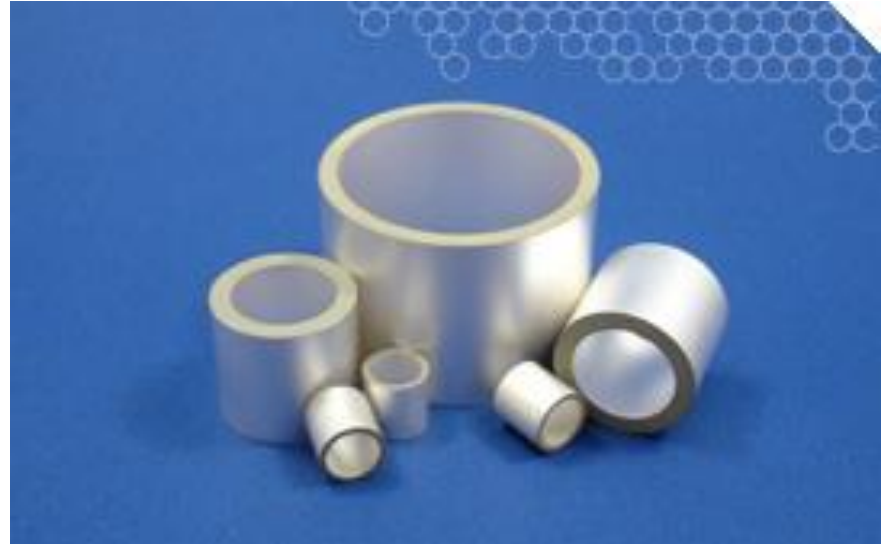
Borehole Receiver



Piezoelectric Borehole Source



Thill (1978)

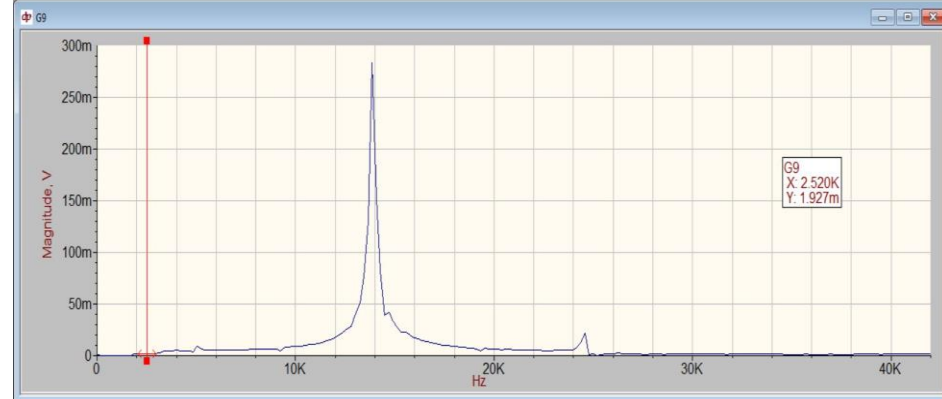
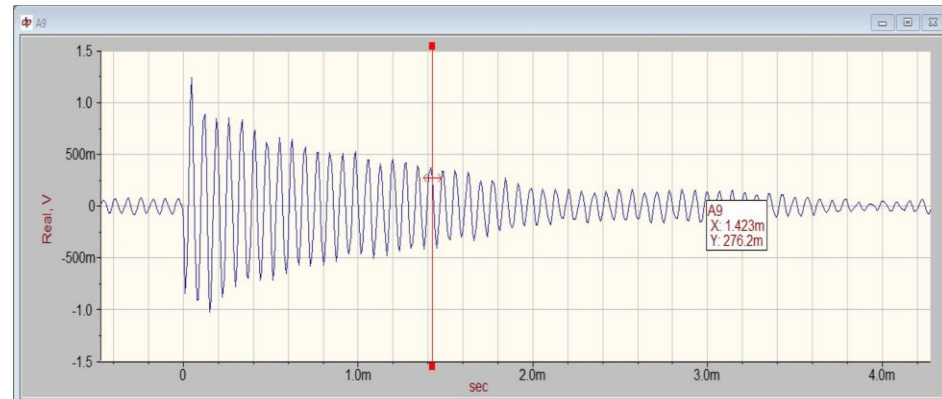


Piezoelectric Cylinders

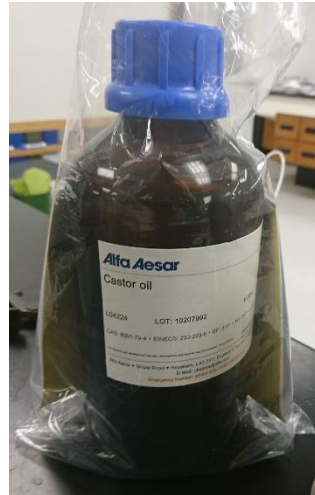
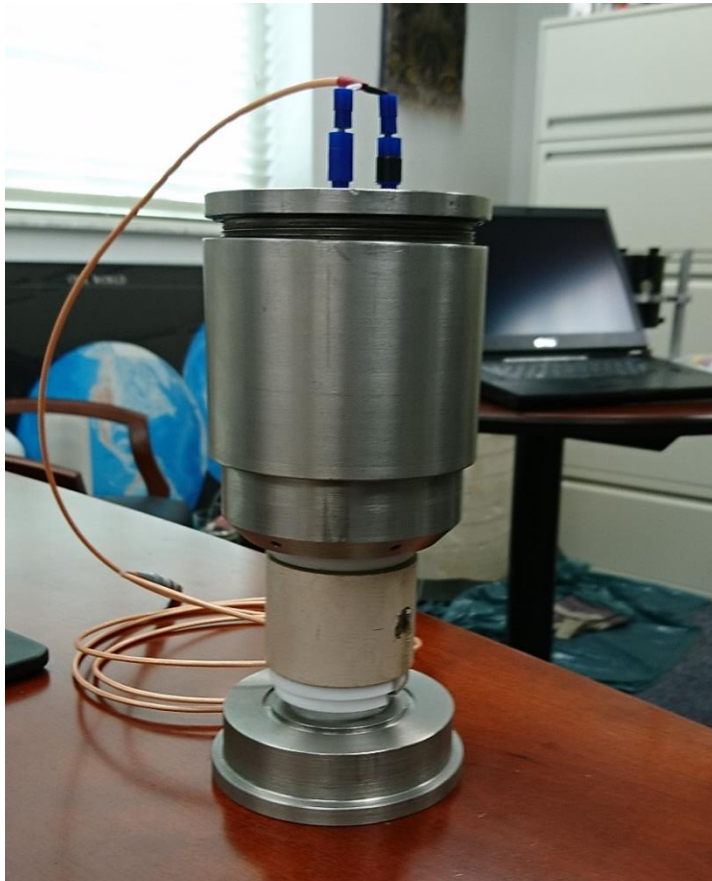


CSL Sensor

Cylinder and Amplifier: 3rd Generation



Inflatable Borehole Source: 17 kHz



Inflatable Source: Stacked 14 kHz



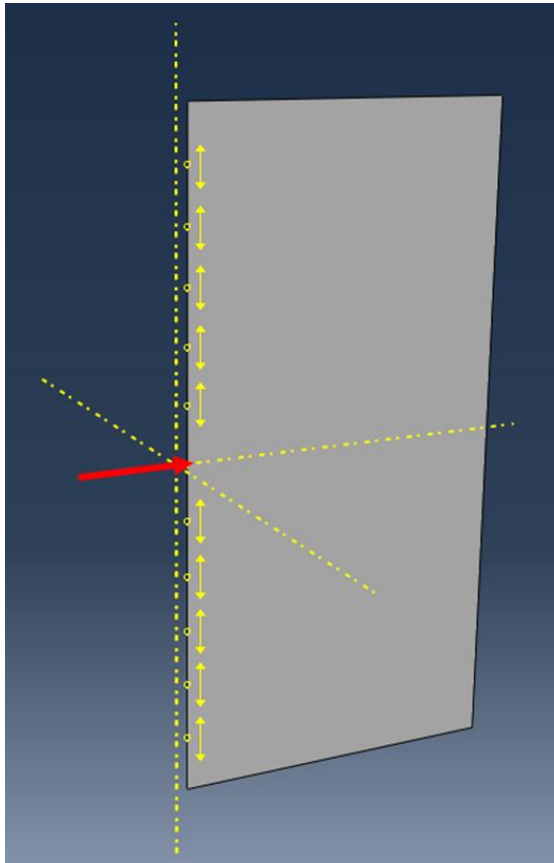
Workplan



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Inversion Schematic

ABAQUS 2.5D FEM

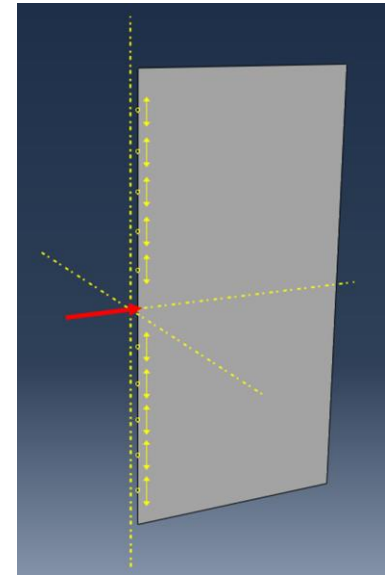


Regularized Gauss-Newton Method

- Residual wave field: $\Delta \mathbf{d} = \mathbf{F}(\mathbf{m}) - \mathbf{d}$
- Least-squares error: $E(\mathbf{m}) = \frac{1}{2} \Delta \mathbf{d}' \Delta \mathbf{d}$
- Model updating: $\mathbf{m}^{n+1} = \mathbf{m}^n - \alpha^n [\mathbf{J}' \mathbf{J} + \lambda_1 \mathbf{P}' \mathbf{P} + \lambda_2 \mathbf{I}' \mathbf{I}]^{-1} \mathbf{J}' \Delta \mathbf{d},$
- Gradient matrix \mathbf{J} : $\mathbf{J} = \frac{\partial \mathbf{F}(\mathbf{m})}{\partial m_p}$
- Step length: $\alpha^n \cong \frac{[\mathbf{J}' \mathbf{g}^n]' [\mathbf{F}(\mathbf{m}^n) - \mathbf{d}]}{[\mathbf{J}' \mathbf{g}^n]' [\mathbf{J}' \mathbf{g}^n]},$
 $\mathbf{g}^n = [\mathbf{J}' \mathbf{J} + \lambda_1 \mathbf{P}' \mathbf{P} + \lambda_2 \mathbf{I}' \mathbf{I}]^{-1} \mathbf{J}' [\mathbf{F}(\mathbf{m}^n) - \mathbf{d}].$

Inversion Software

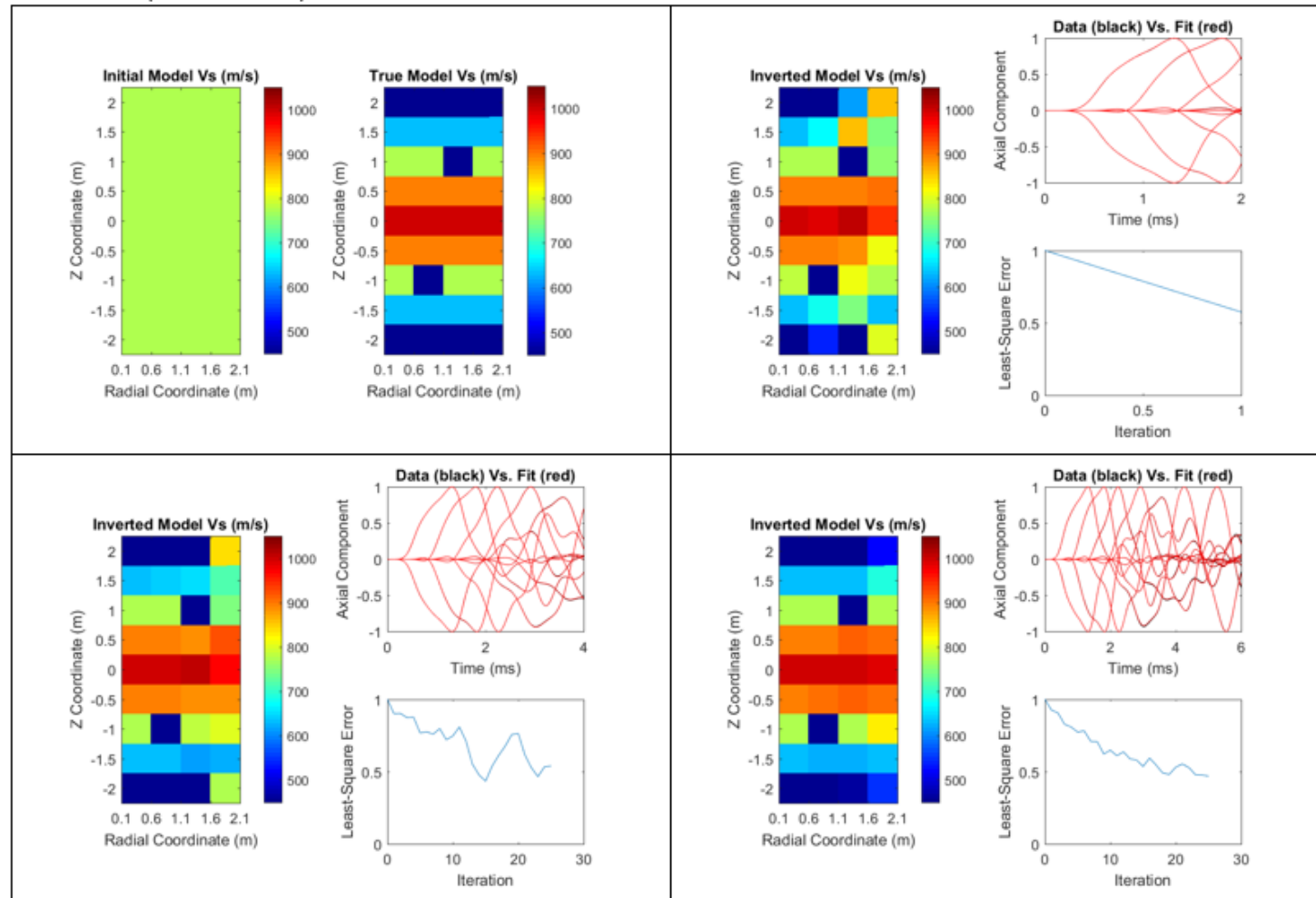
- ABAQUS 2.5D FEM and regularized Gauss-Newton method
- Improved FEM element and mesh and streamlined inversion code
- Implemented 2.5D borehole model in Student Version of ABAQUS (free)
- Inversion shell in MATLAB
- Improved speed to allow longer waveforms



- Residual wave field: $\Delta \mathbf{d} = \mathbf{F}(\mathbf{m}) - \mathbf{d}$
- Least-squares error: $E(\mathbf{m}) = \frac{1}{2} \Delta \mathbf{d}^T \Delta \mathbf{d}$
- Model updating: $\mathbf{m}^{n+1} = \mathbf{m}^n - \alpha^n [\mathbf{J}^T \mathbf{J} + \lambda_1 \mathbf{P}^T \mathbf{P} + \lambda_2 \mathbf{I}]^{-1} \mathbf{J}^T \Delta \mathbf{d}$,
- Gradient matrix \mathbf{J} : $\mathbf{J} = \frac{\partial \mathbf{F}(\mathbf{m})}{\partial \mathbf{m}_p}$
- Step length: $\alpha^n \cong \frac{[\mathbf{J}^T \mathbf{g}^n]^T [\mathbf{F}(\mathbf{m}^n) - \mathbf{d}]}{[\mathbf{J}^T \mathbf{g}^n]^T [\mathbf{J}^T \mathbf{g}^n]}$,
 $\mathbf{g}^n = [\mathbf{J}^T \mathbf{J} + \lambda_1 \mathbf{P}^T \mathbf{P} + \lambda_2 \mathbf{I}]^{-1} \mathbf{J}^T [\mathbf{F}(\mathbf{m}^n) - \mathbf{d}]$.

Two Anomalies Same Side

Case 3: Model (13.25m x 5.25m) for 6-ms simulation time

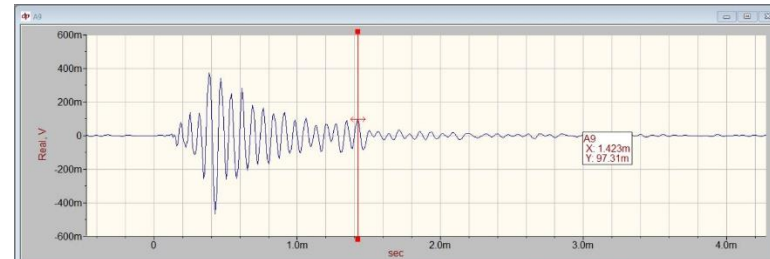
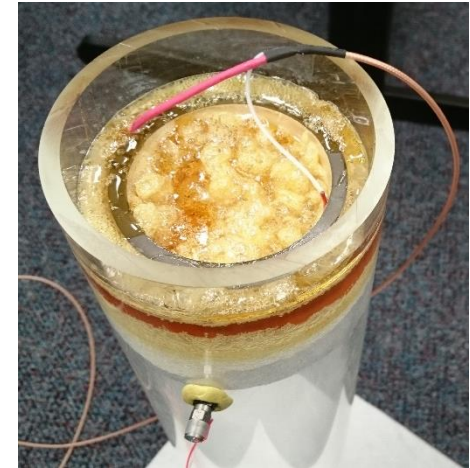


Workplan

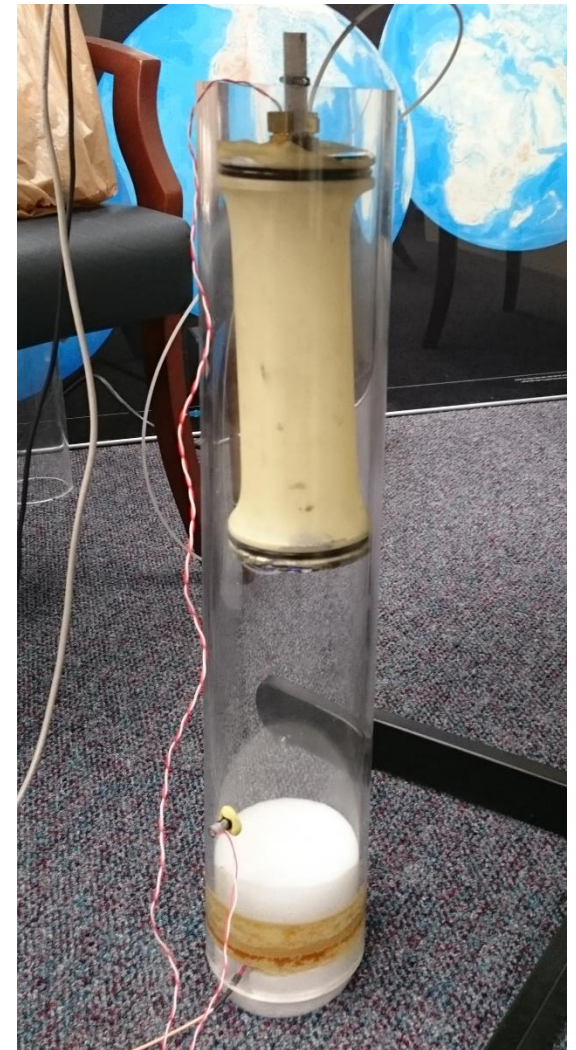


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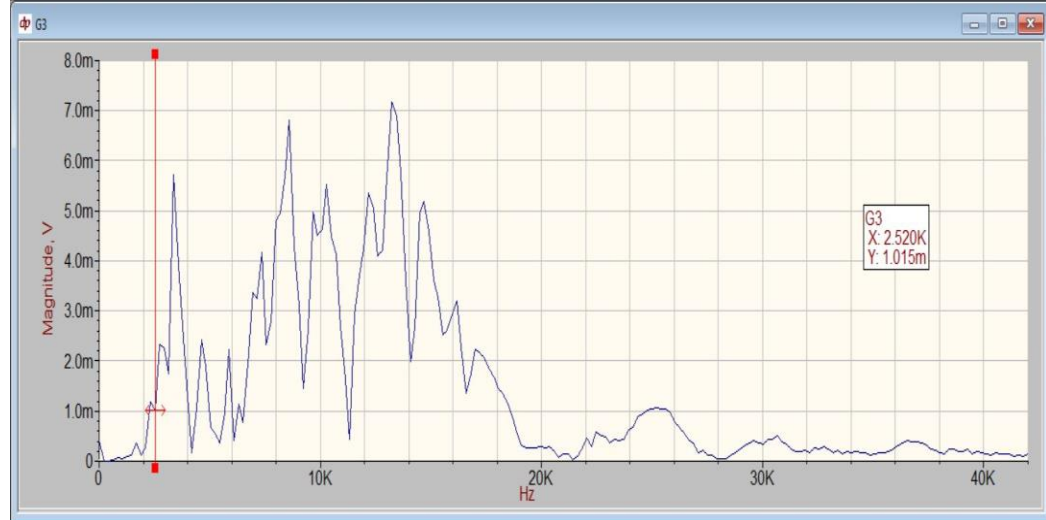
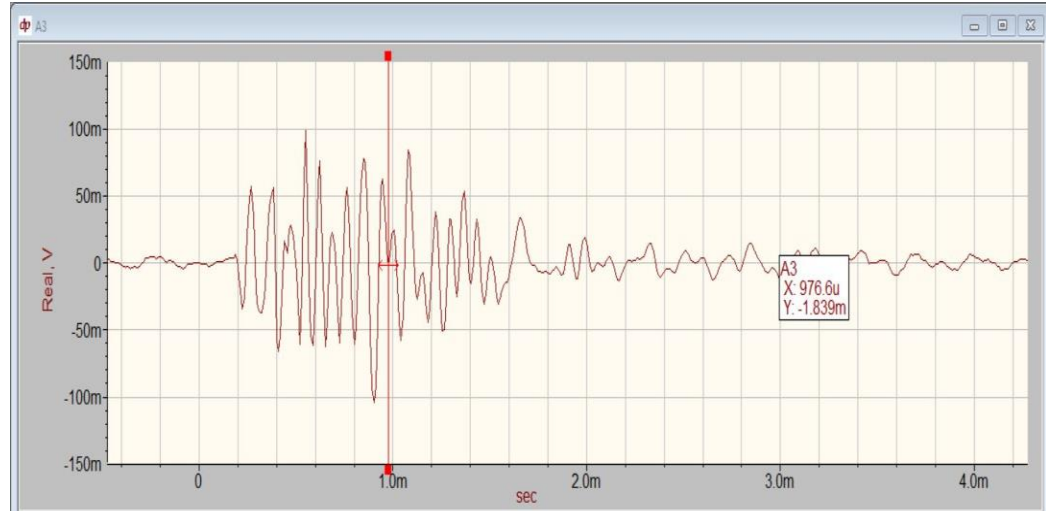
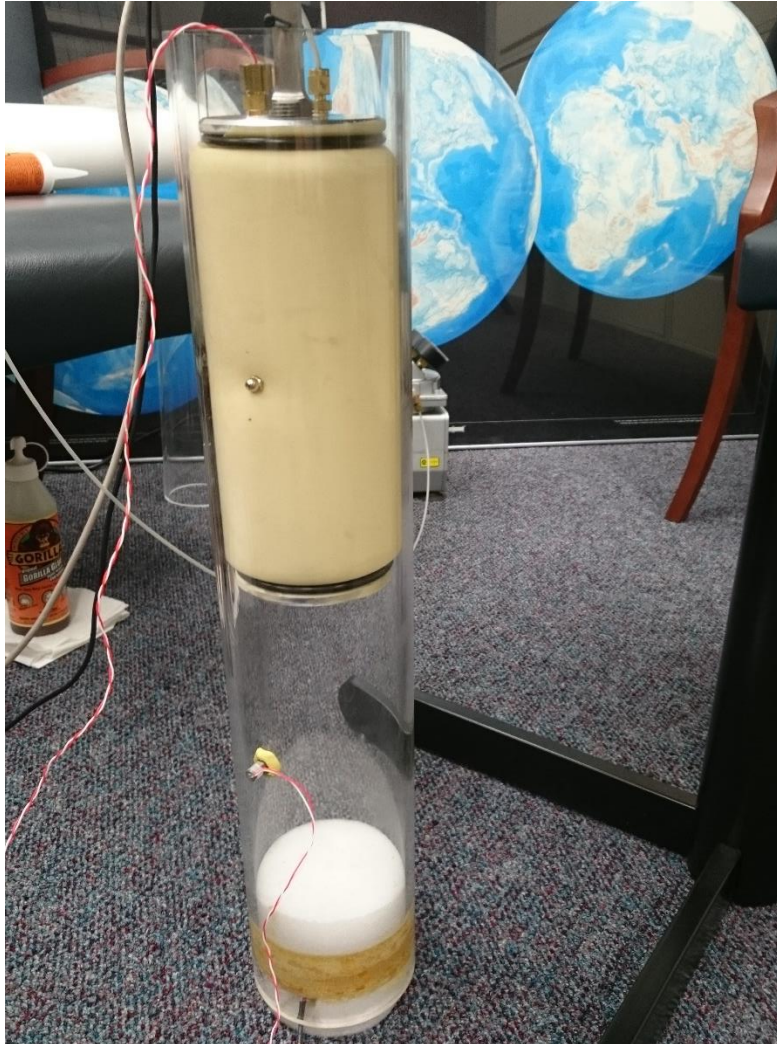
Acrylic Tube



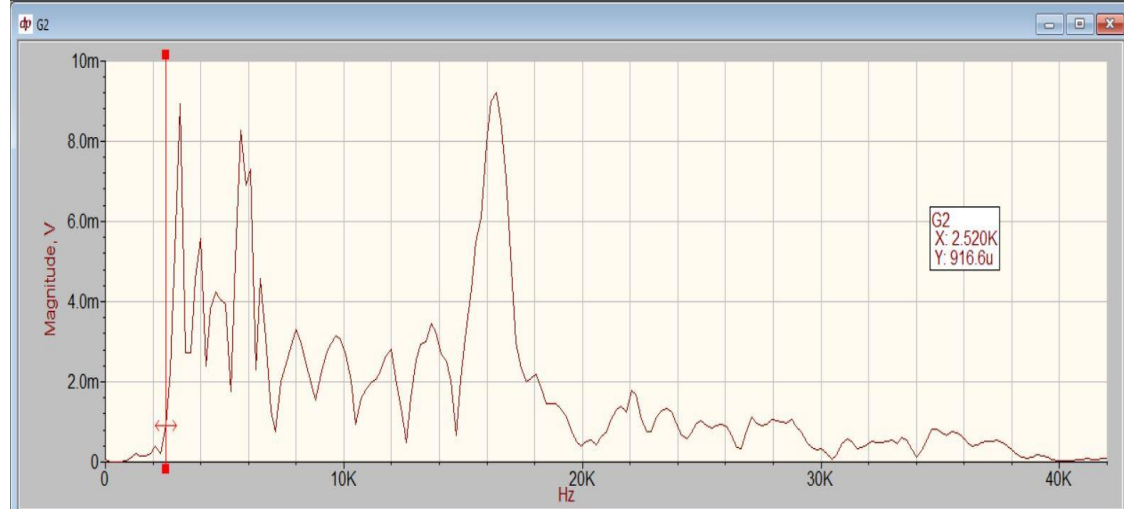
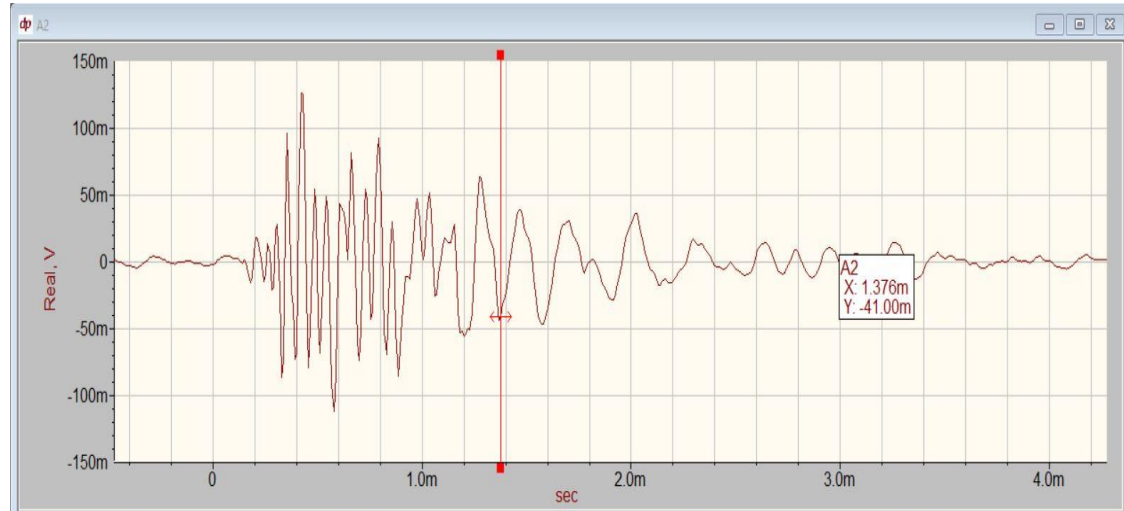
Combined Source/Receiver Concept



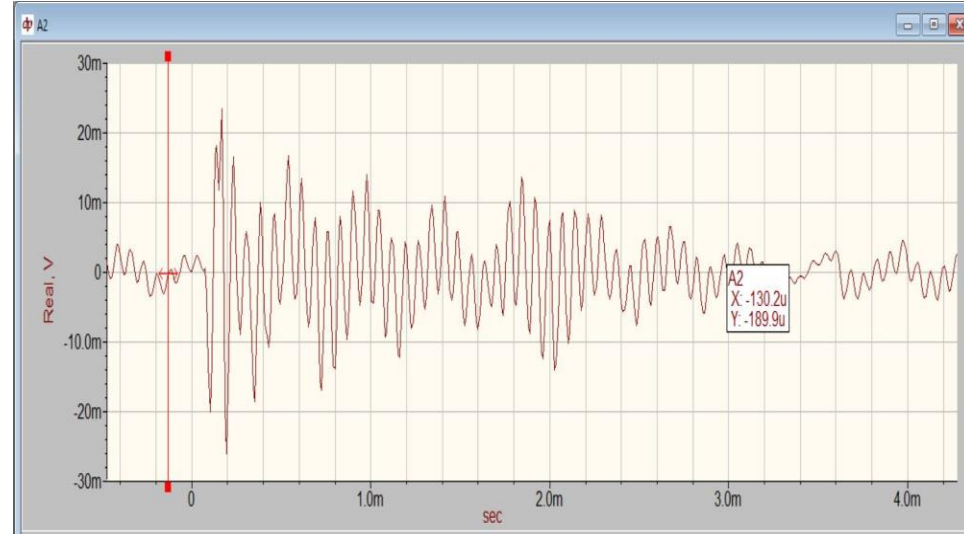
Receiver Improvements



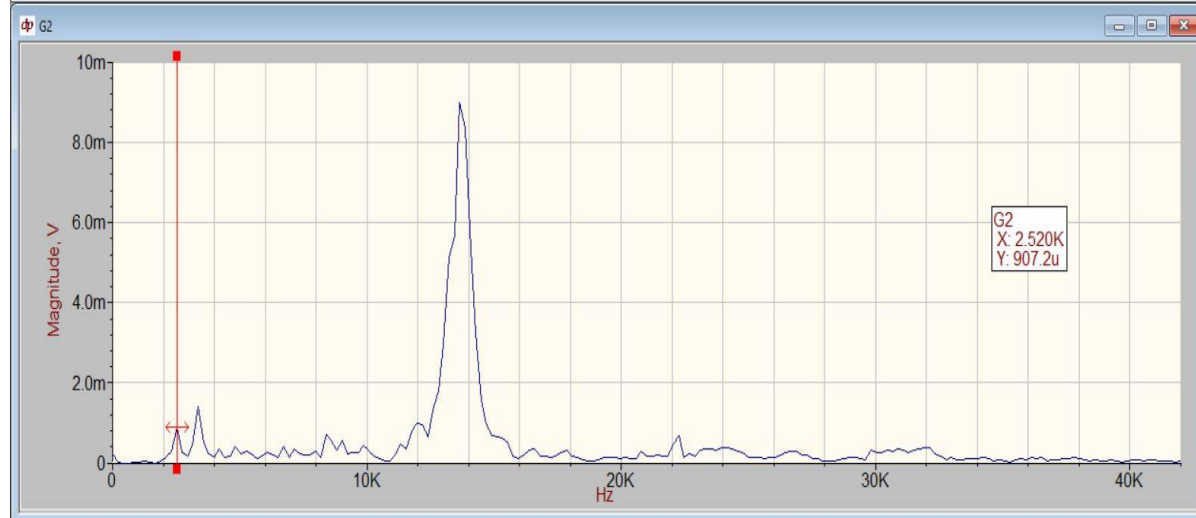
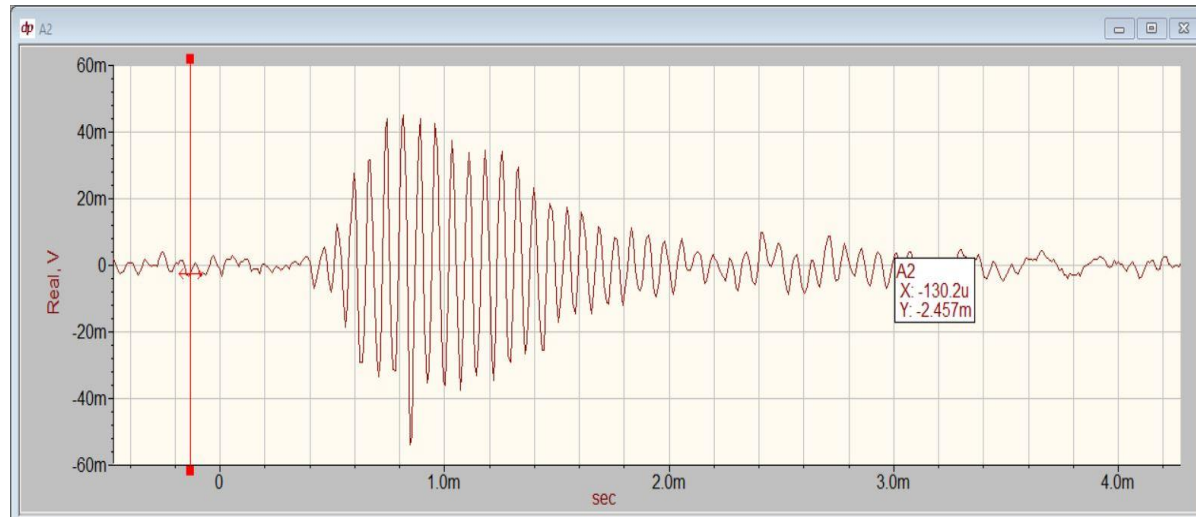
Inflatable Source and Receiver



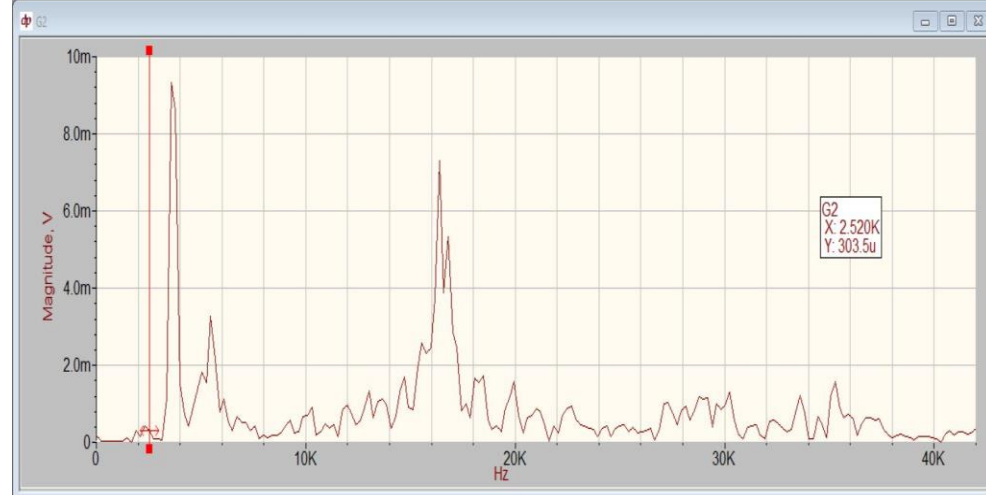
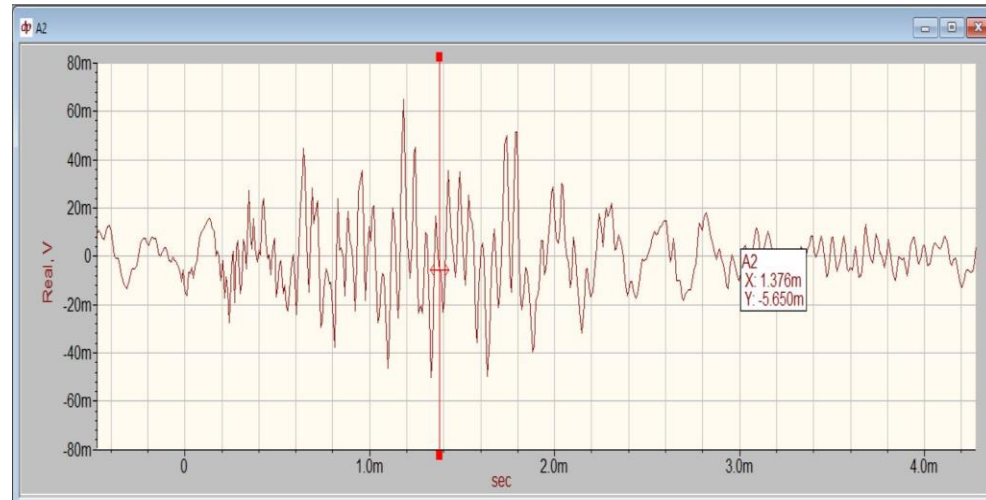
Synthetic Limerock Borehole Model



Synthetic Limerock Borehole Model

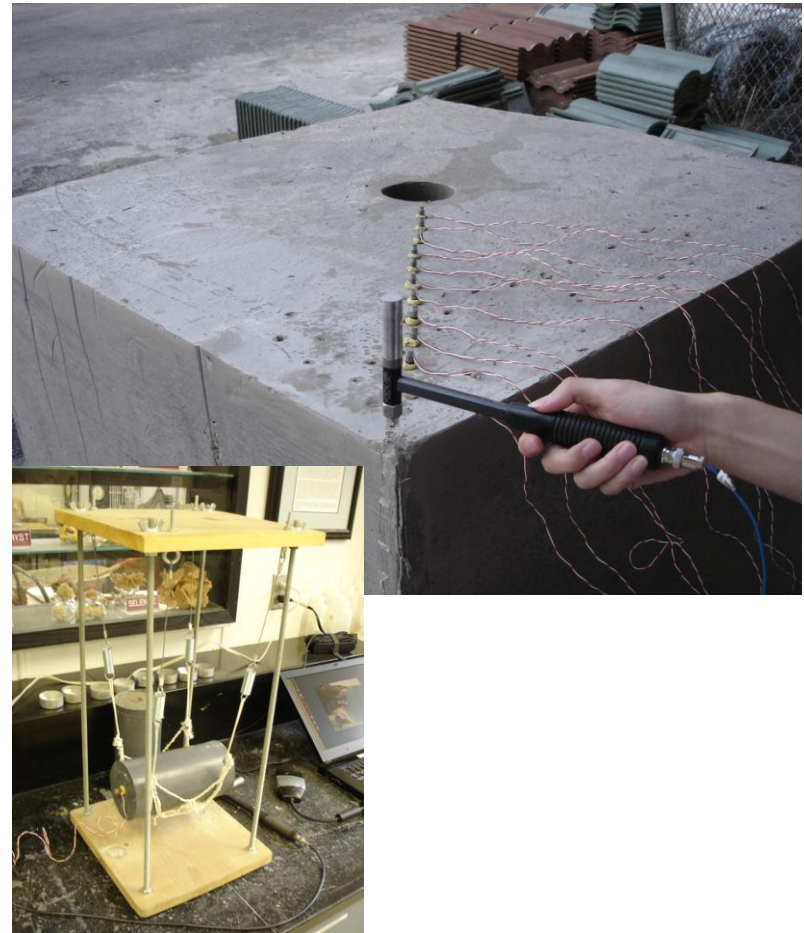


Synthetic Limerock Borehole Model

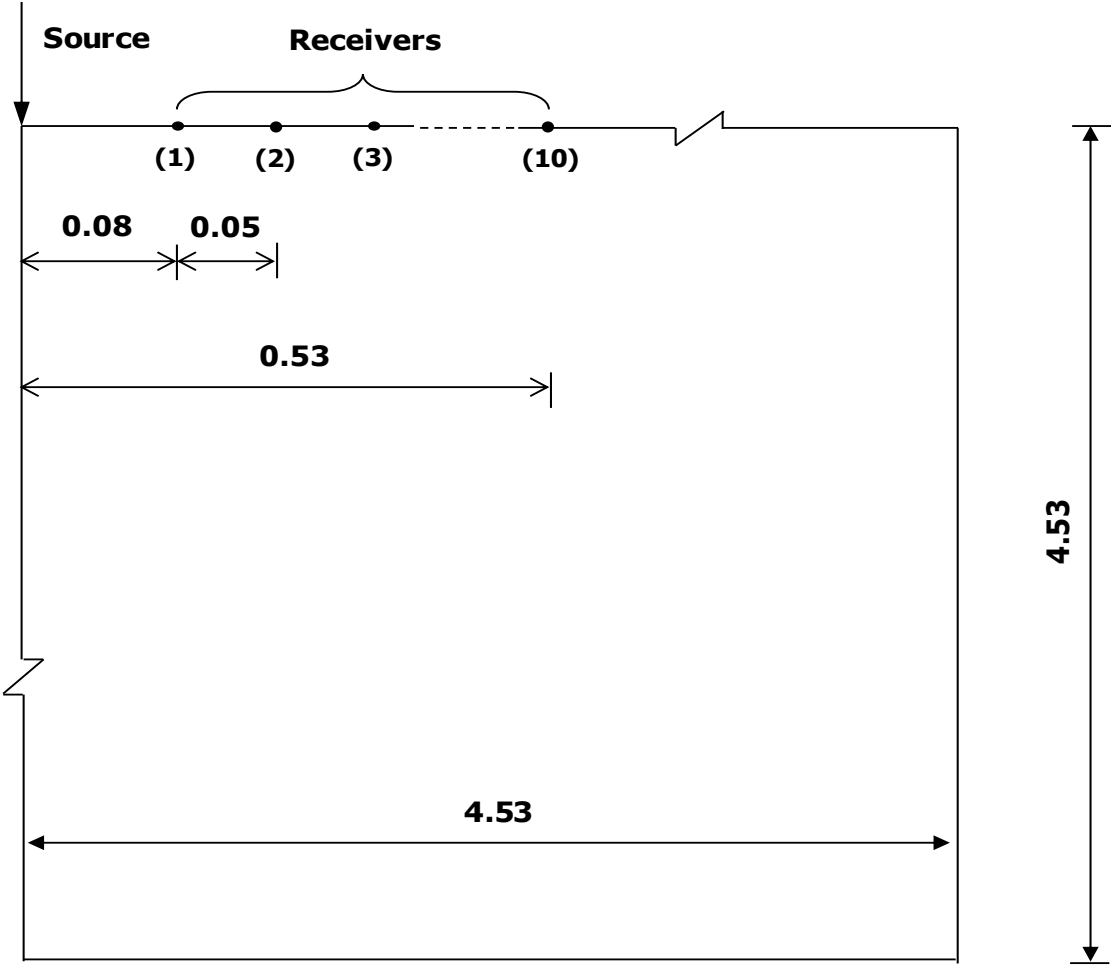


Synthetic Limerock Block: Experiments

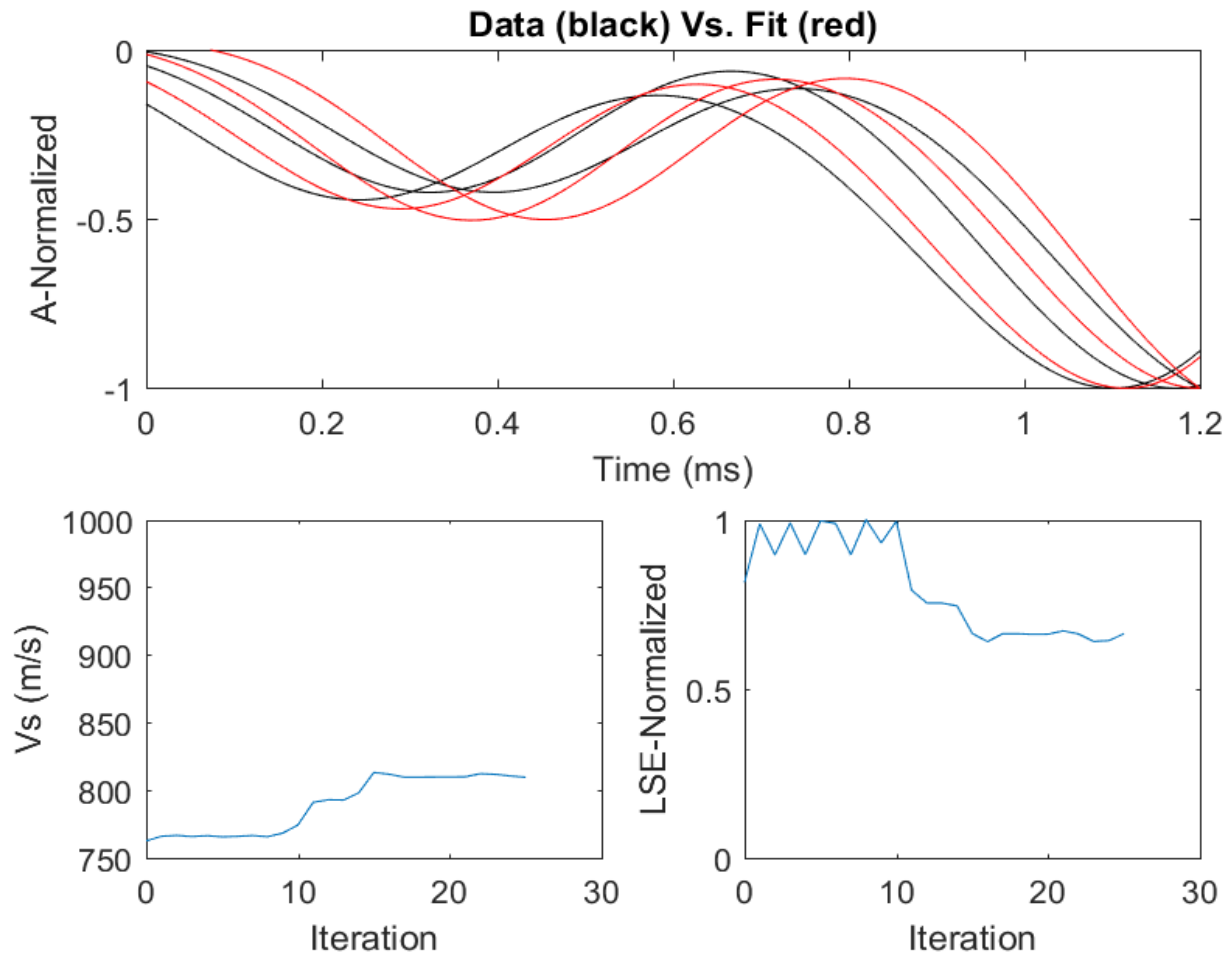
- Full waveform tests on top surface
- Free-free resonant column tests on companion cylinder
 - $V_p = 1500$ m/s
 - Poisson's ratio = 0.2
 - Thus $V_s = 920$ m/s



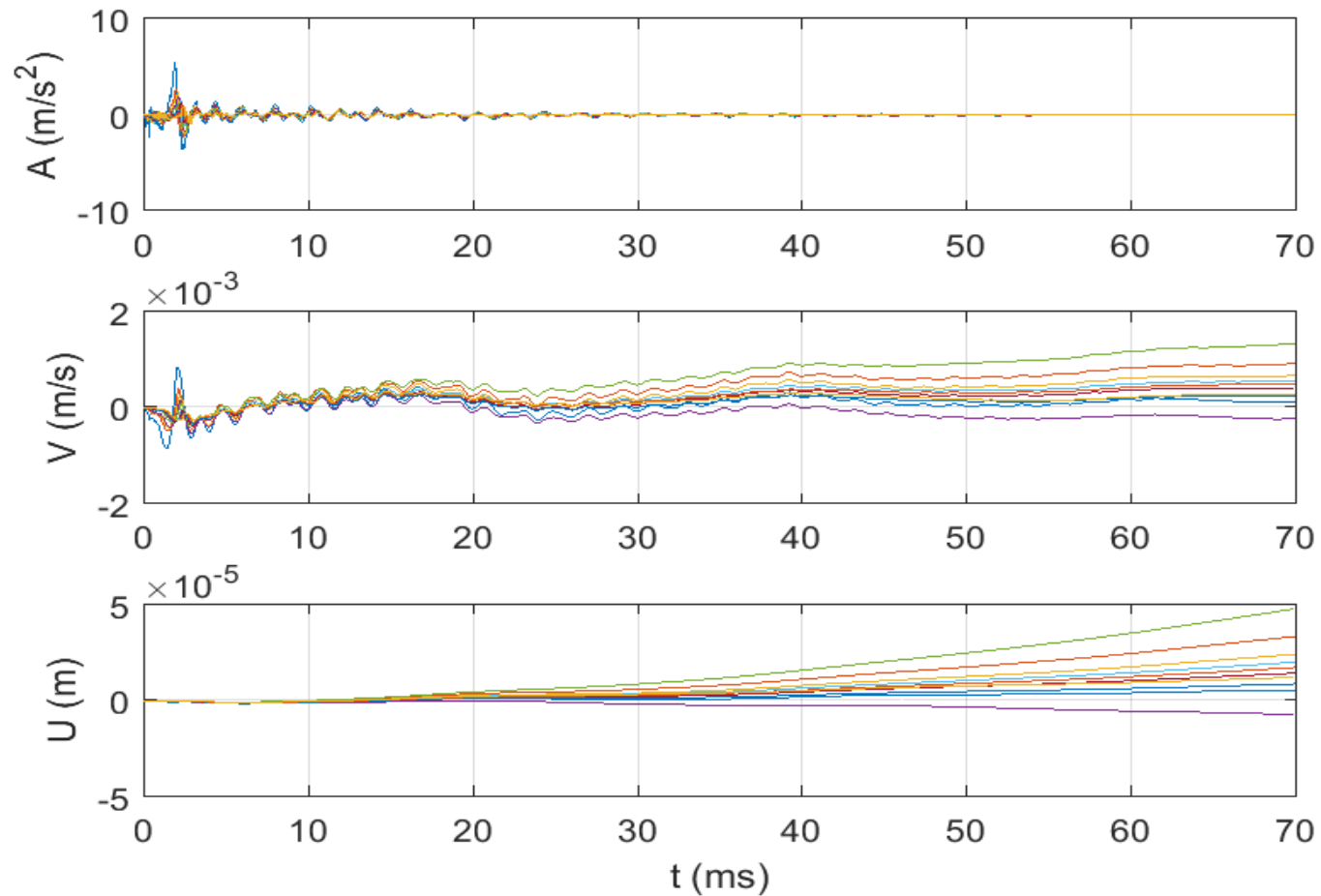
Synthetic Limerock Block: FEM Model



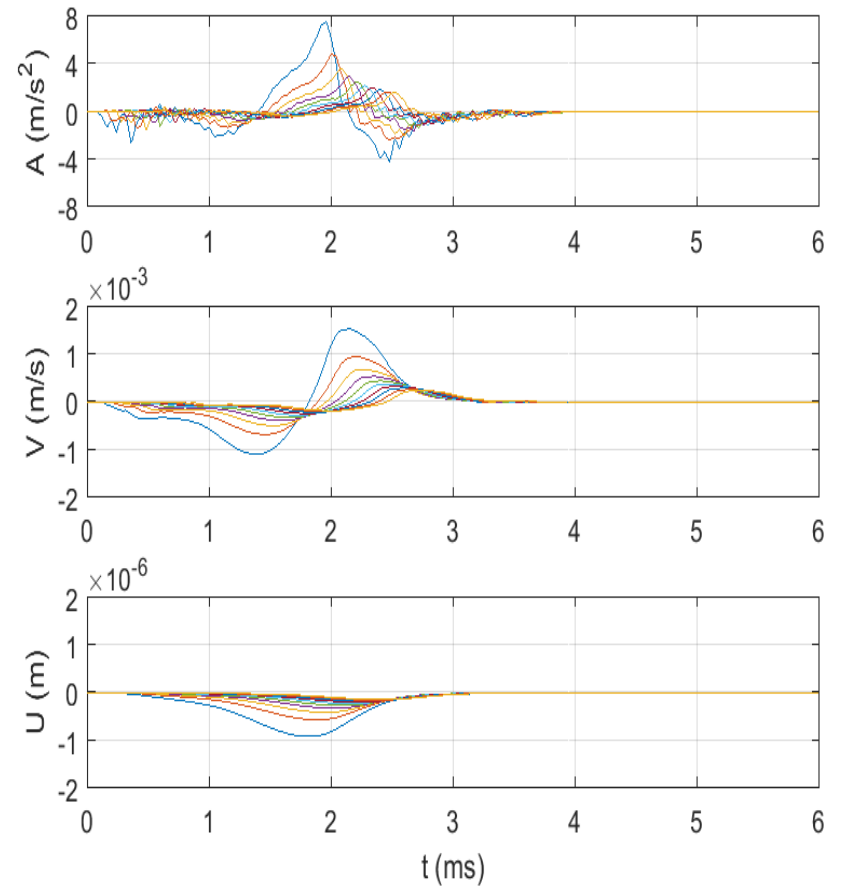
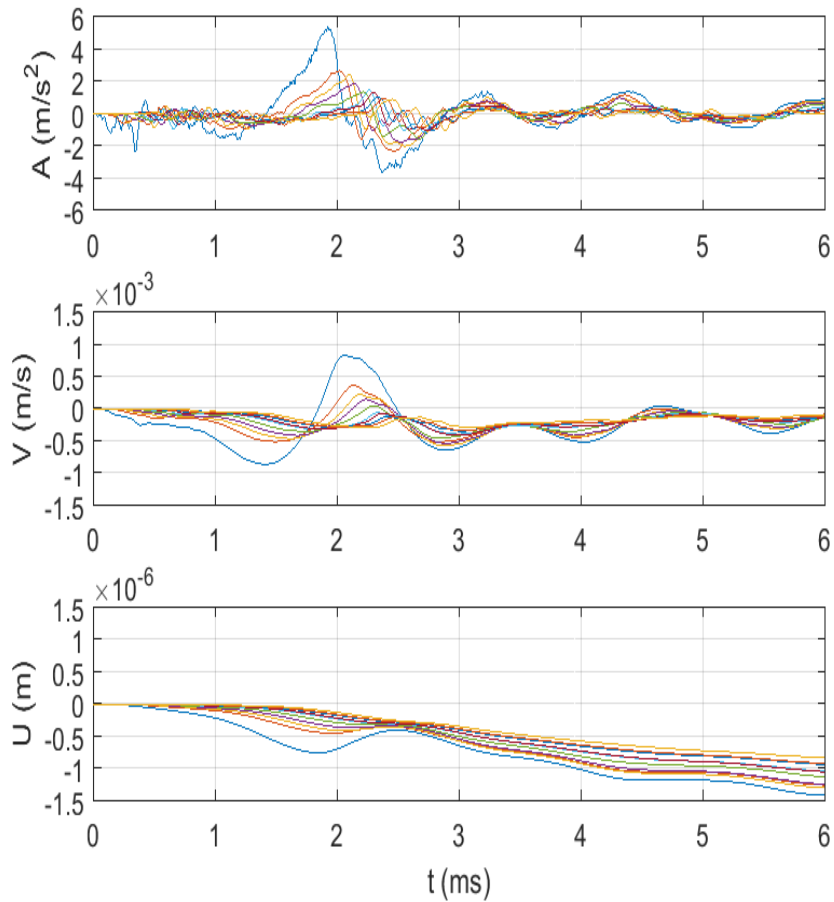
Synthetic Limerock Block: Acceleration



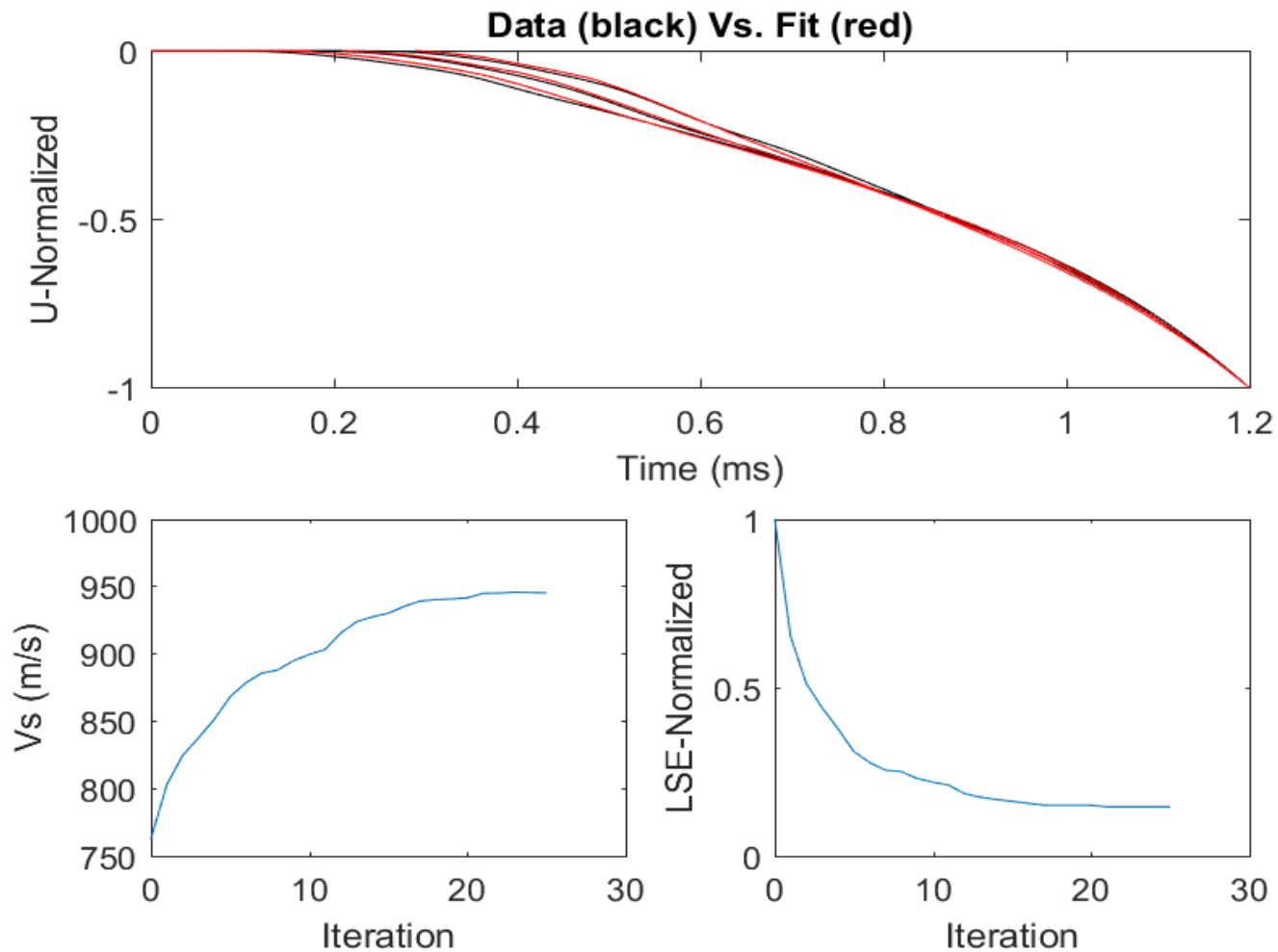
Synthetic Limerock Block: No Filter



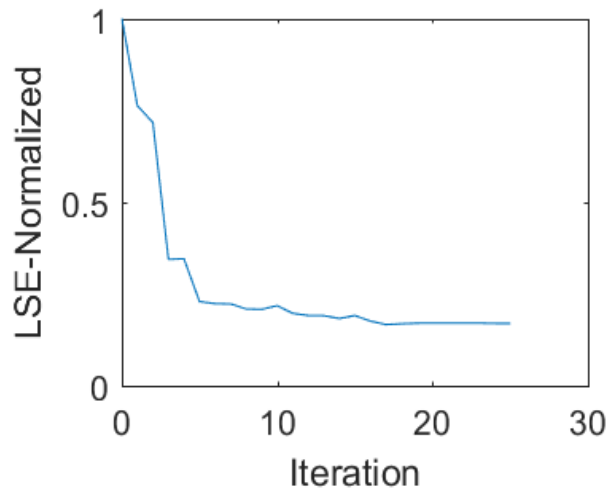
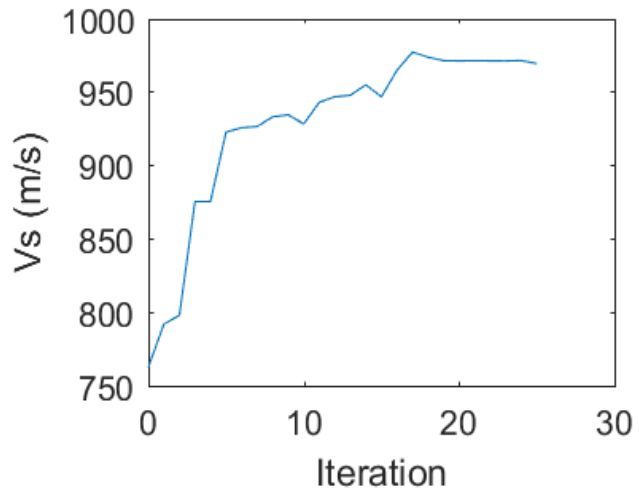
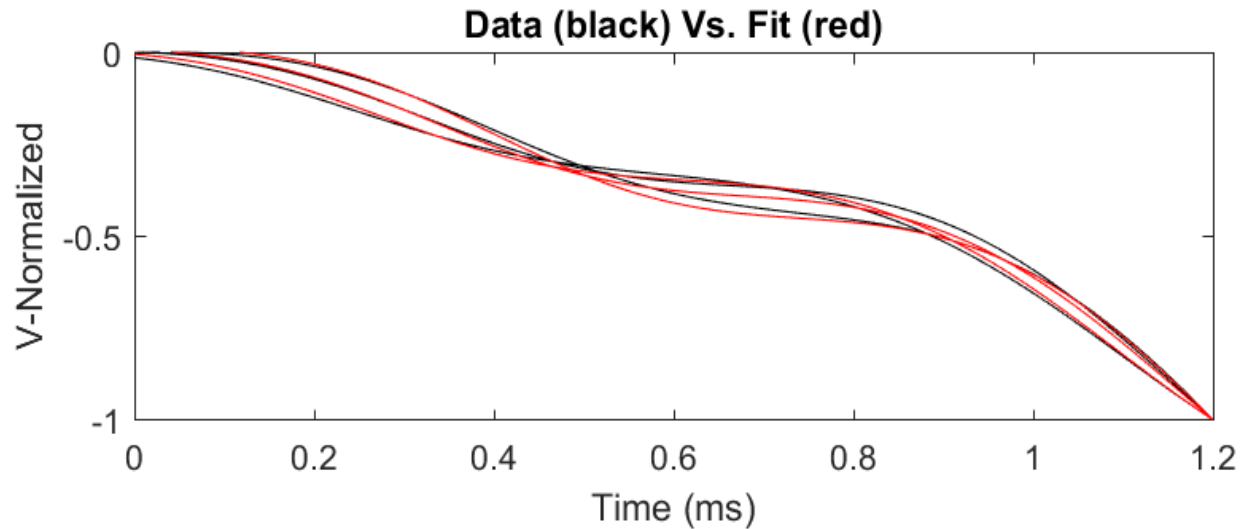
Synthetic Limerock Block: High-Pass



Synthetic Limerock Block: Displacement

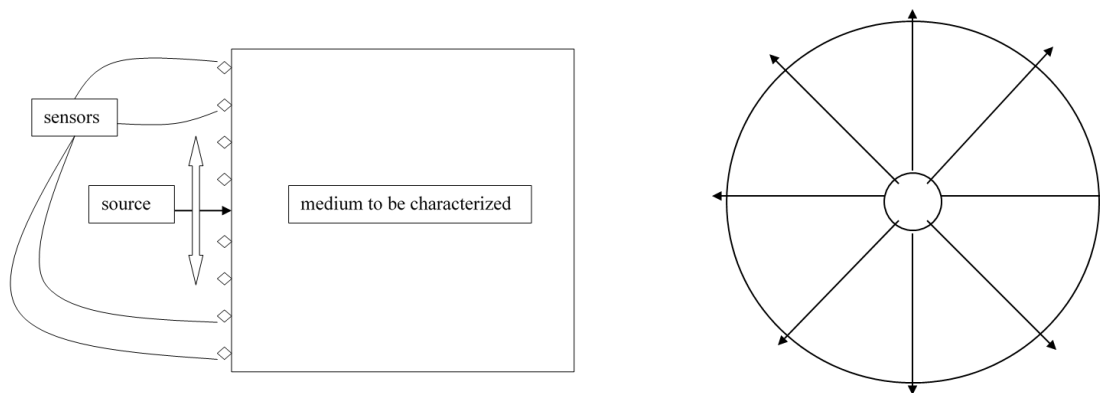


Synthetic Limerock Block: Velocity



Next Activities

- **Tune the source/receiver array to achieve 5-ft penetration: size, spacing, frequency, energy**
- **Continue development of processing and inversion techniques on data from field experiments**



Thank You!

