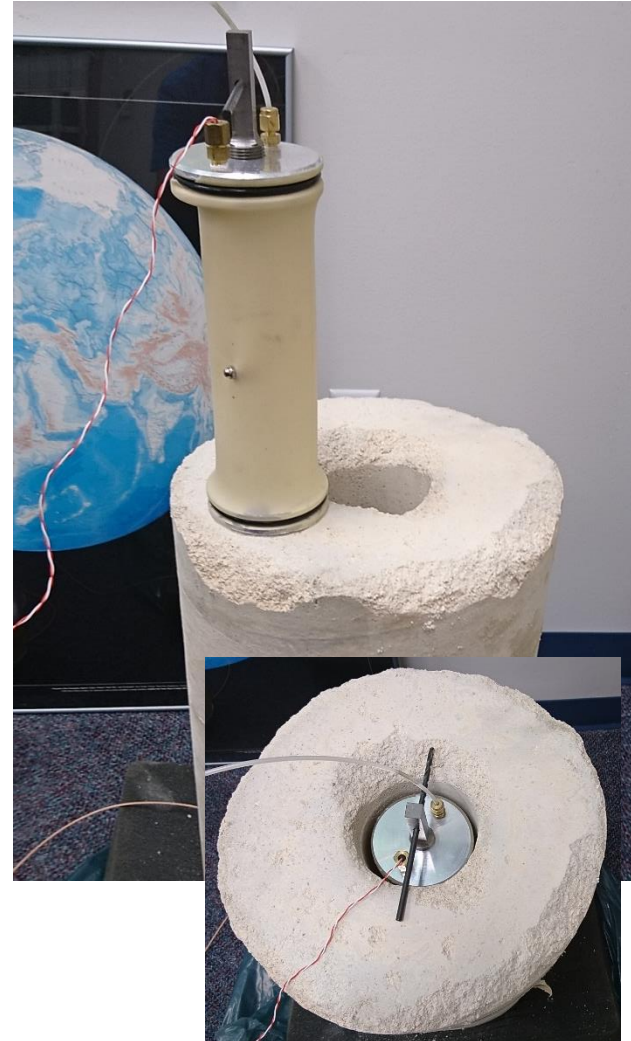


Implementation of Down-Hole Geophysical Testing for Rock Sockets

Dennis R. Hiltunen
University of Florida

FDOT GRIP

August 18, 2017



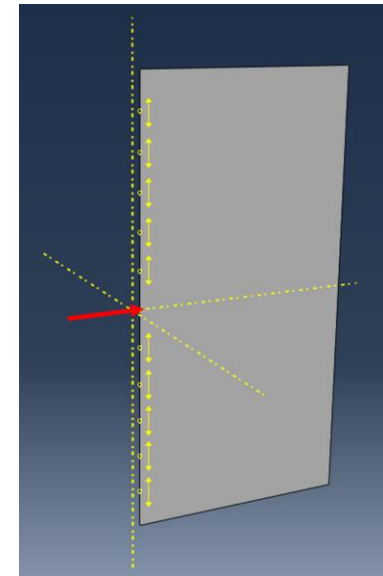
Workplan



- **Task 1: Borehole Instrument**
 - **Source for generating seismic (mechanical) waves**
 - **Receiver array for capturing the wavefield**
- **Task 2: Inversion Software**
 - **ABAQUS forward model**
 - **Stand-alone forward model for borehole geometry**
 - **Artificial neural network (ANN) trained by ABAQUS**
- **Task 3: Validation Experiments**
 - **Large laboratory block of synthetic limerock**
 - **Newberry and Kanapaha test sites**
- **Task 4: Report**

Inversion Software

- ABAQUS 2.5D FEM and regularized Gauss-Newton method
- Improved FEM element and mesh and streamlined inversion code
- Looked at open-source FEM, FD solution, and ANN
- Implemented 2.5D borehole model in Student Version of ABAQUS (free)
- Inversion shell in MATLAB

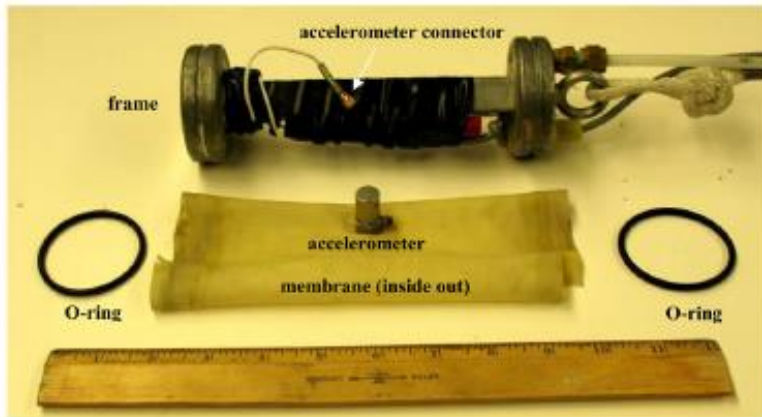


- Residual wave field: $\Delta \mathbf{d} = \mathbf{F}(\mathbf{m}) - \mathbf{d}$
- Least-squares error: $E(\mathbf{m}) = \frac{1}{2} \Delta \mathbf{d}^T \Delta \mathbf{d}$
- Model updating: $\mathbf{m}^{n+1} = \mathbf{m}^n - \alpha^n [\mathbf{J}^T \mathbf{J} + \lambda_1 \mathbf{P}^T \mathbf{P} + \lambda_2 \mathbf{I}]^{-1} \mathbf{J}^T \Delta \mathbf{d}$,
- Gradient matrix \mathbf{J} : $\mathbf{J} = \frac{\partial \mathbf{F}(\mathbf{m})}{\partial \mathbf{m}_p}$
- Step length: $\alpha^n \cong \frac{[\mathbf{J}^T \mathbf{g}^n]^T [\mathbf{F}(\mathbf{m}^n) - \mathbf{d}]}{[\mathbf{J}^T \mathbf{g}^n]^T [\mathbf{J}^T \mathbf{g}^n]}$,
 $\mathbf{g}^n = [\mathbf{J}^T \mathbf{J} + \lambda_1 \mathbf{P}^T \mathbf{P} + \lambda_2 \mathbf{I}]^{-1} \mathbf{J}^T [\mathbf{F}(\mathbf{m}^n) - \mathbf{d}]$.

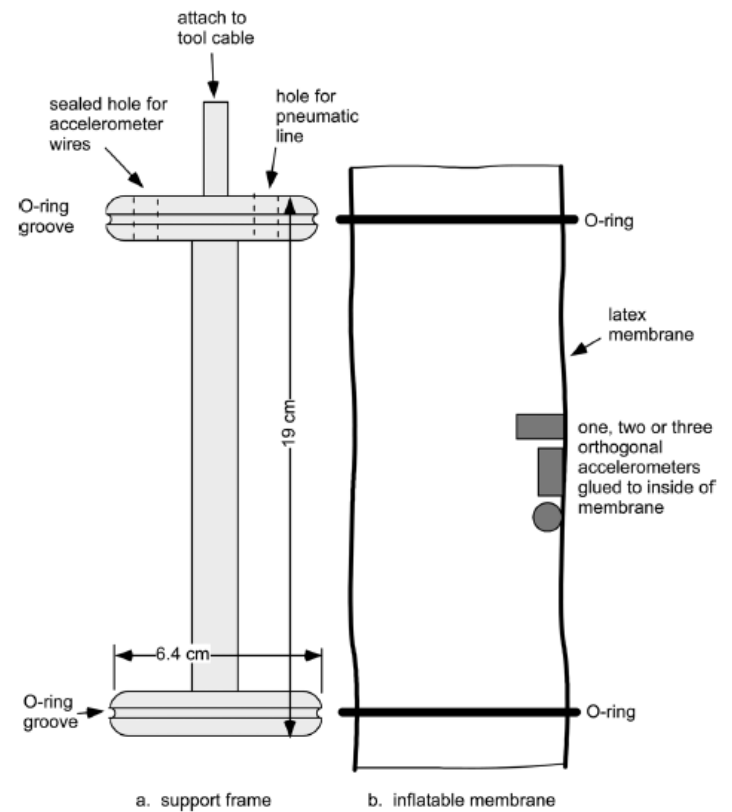
Kalinski Borehole Receiver



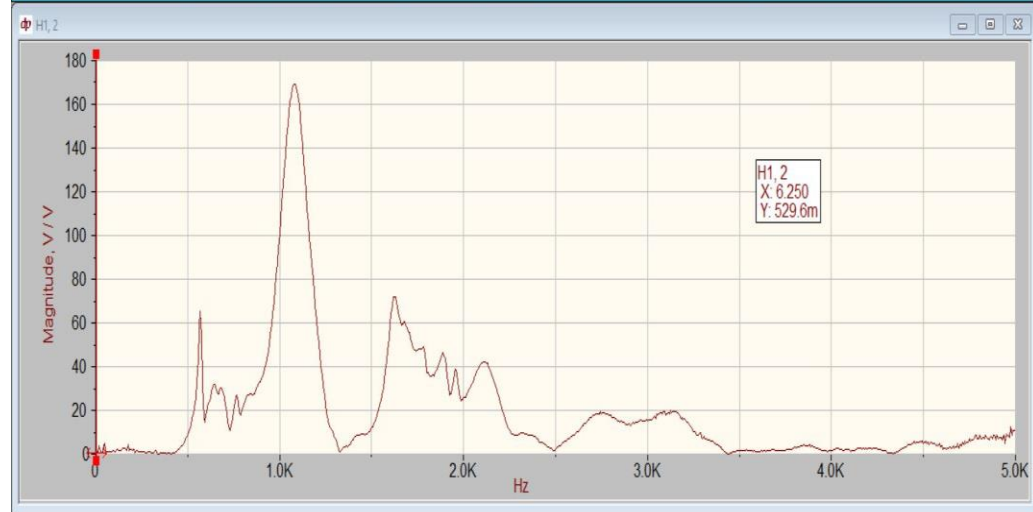
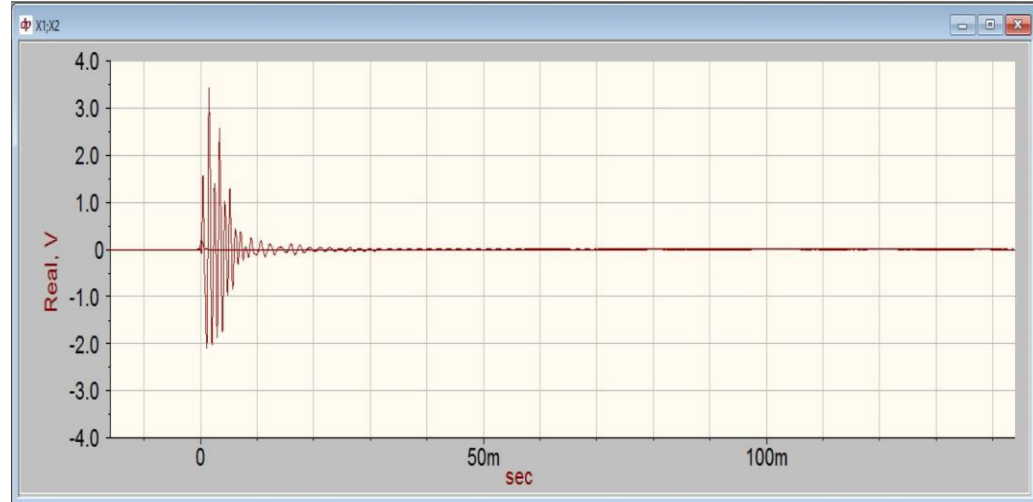
a. assembled view



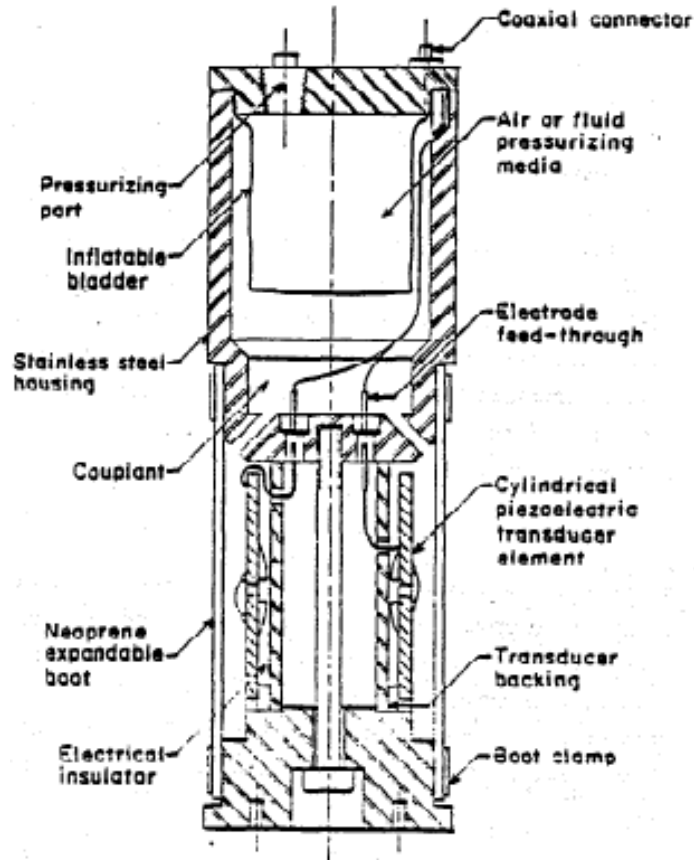
b. exploded view



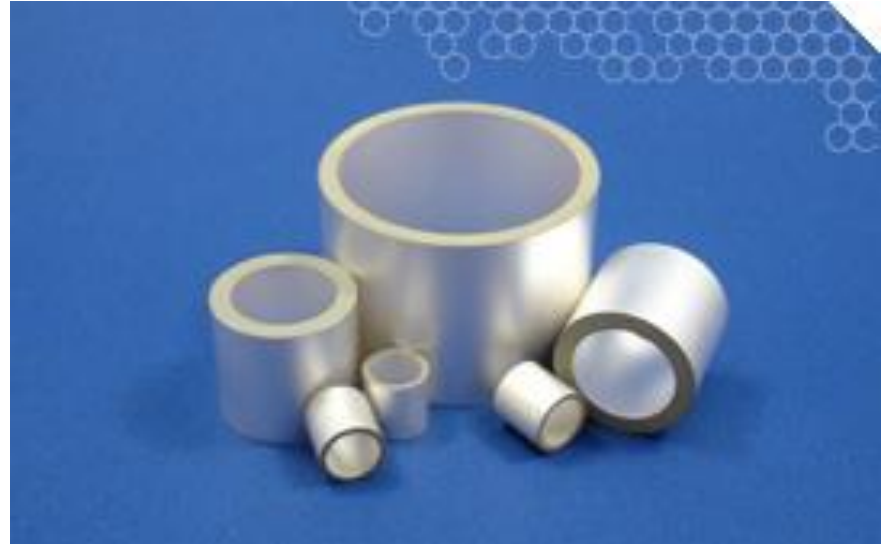
Borehole Receiver



Piezoelectric Borehole Source



Thill (1978)

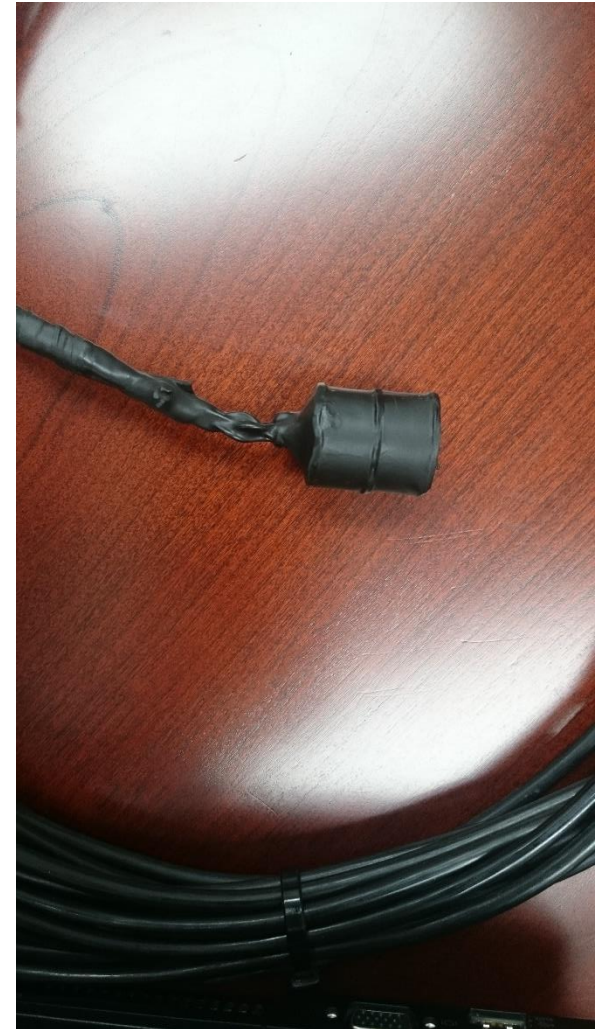


Piezoelectric Cylinders

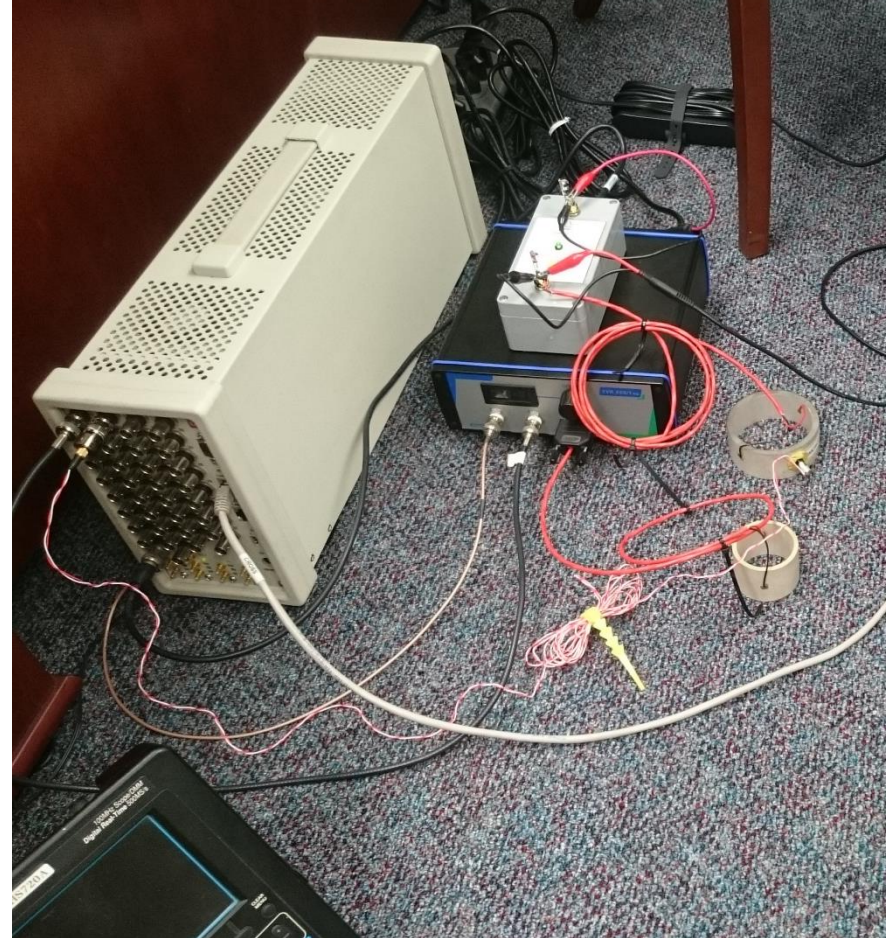
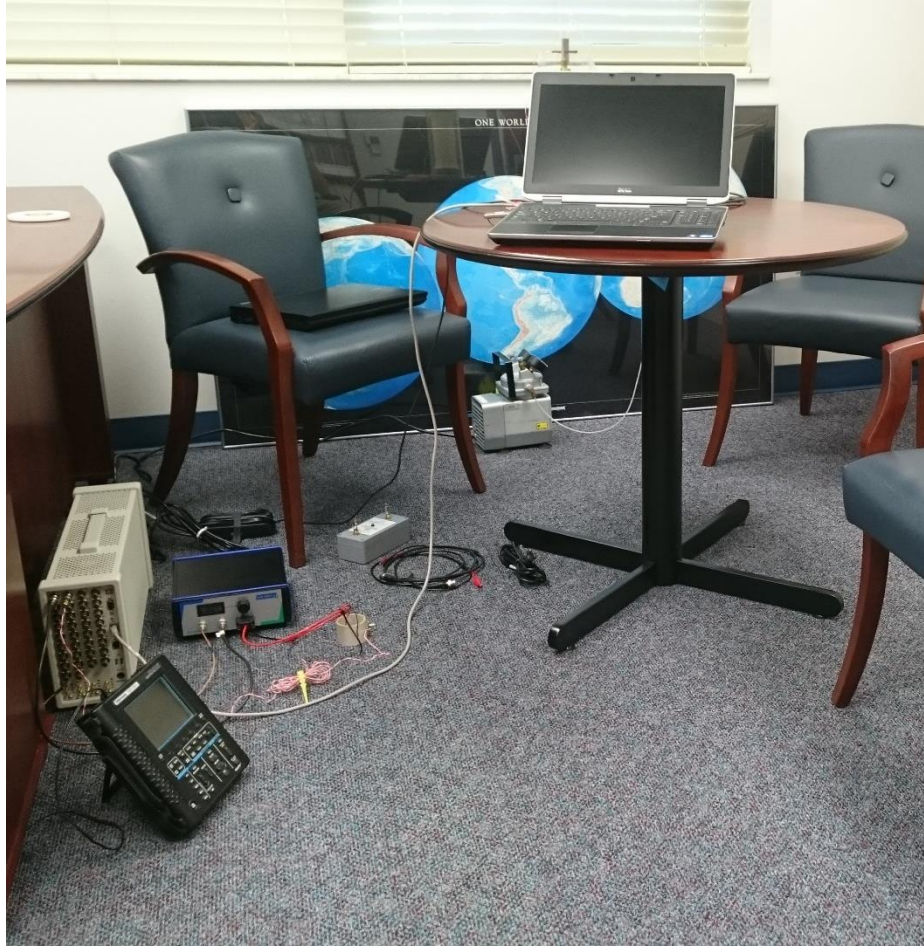


CSL Sensor

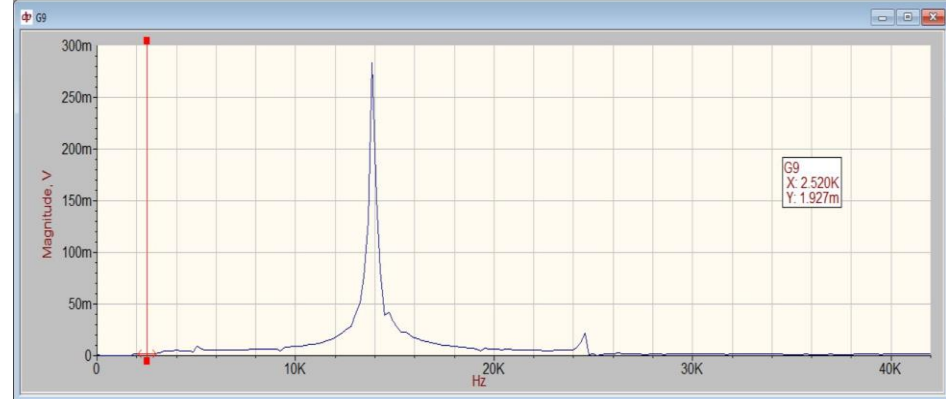
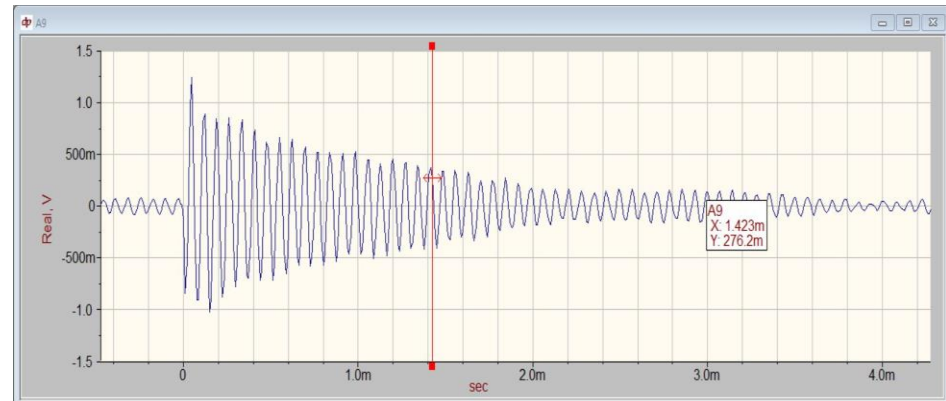
Cylinder and Amplifier: First Draft



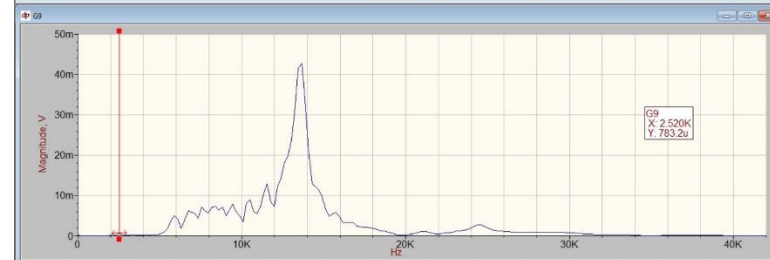
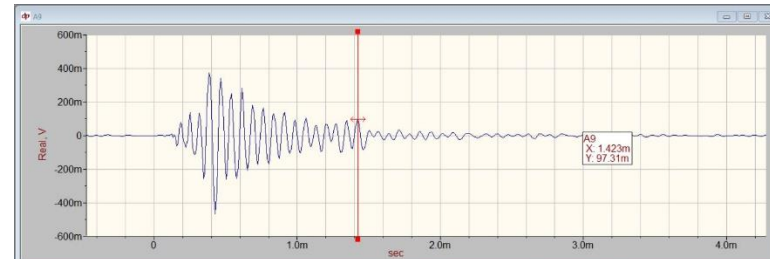
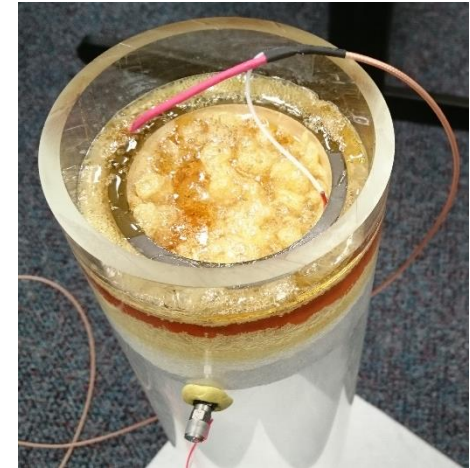
Cylinder and Amplifier: 2nd Generation



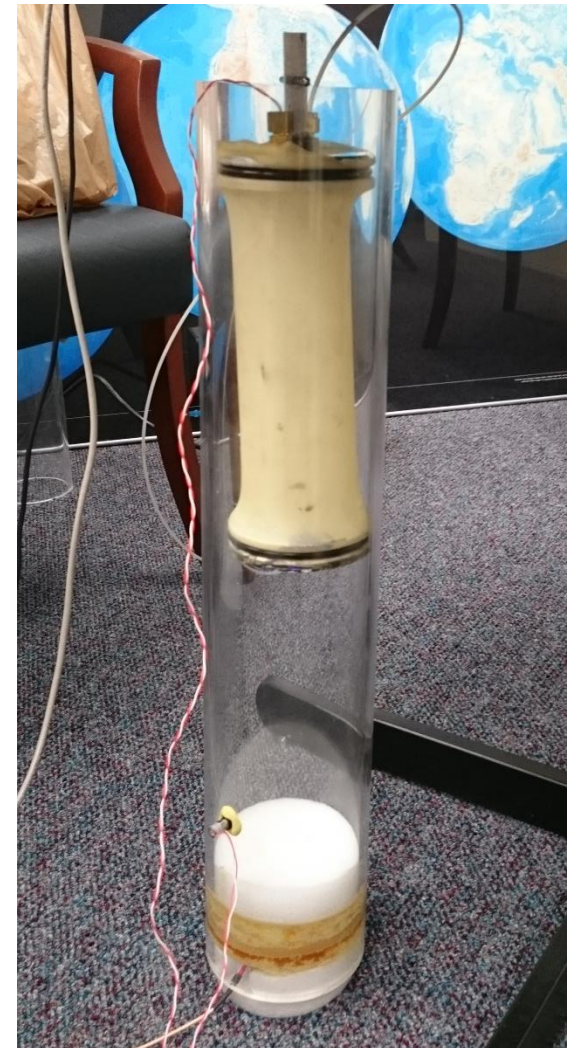
Cylinder and Amplifier: 3rd Generation



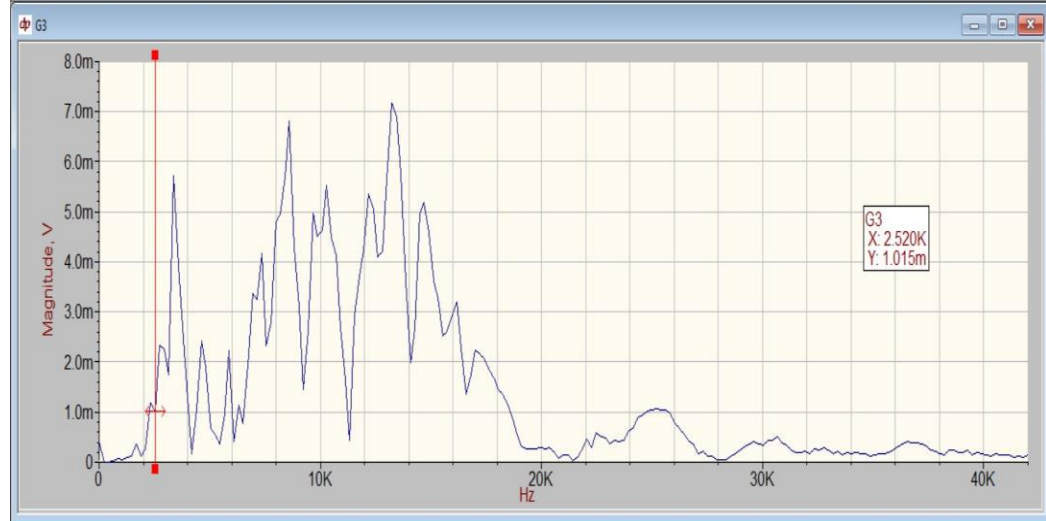
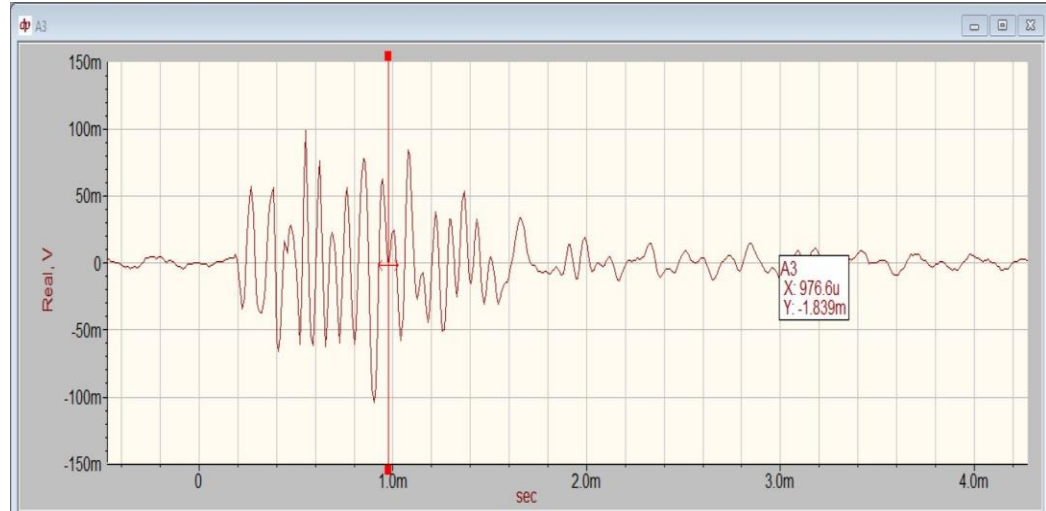
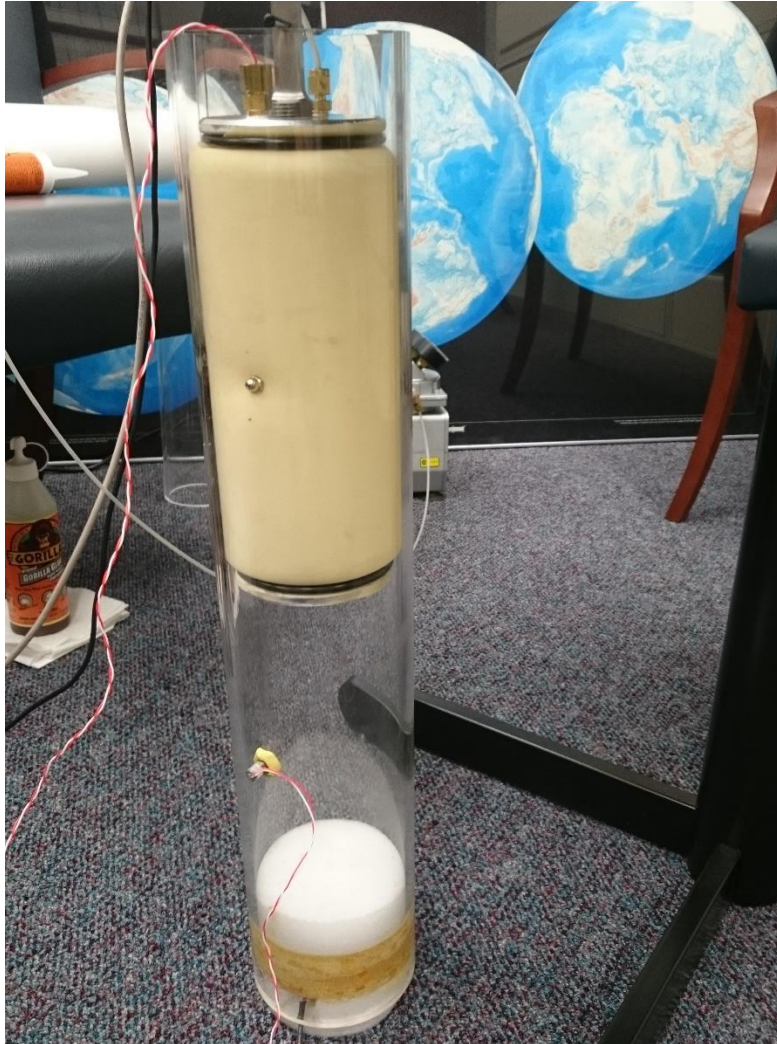
Acrylic Tube



Combined Source/Receiver Concept



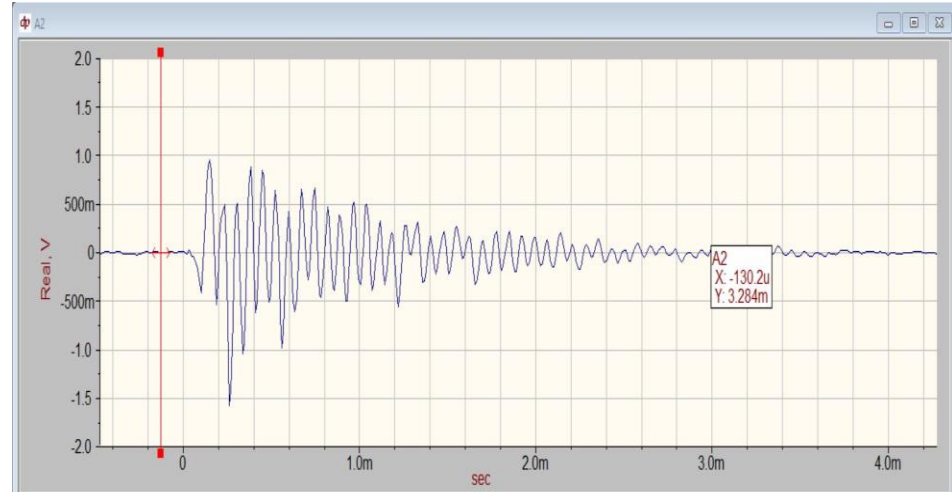
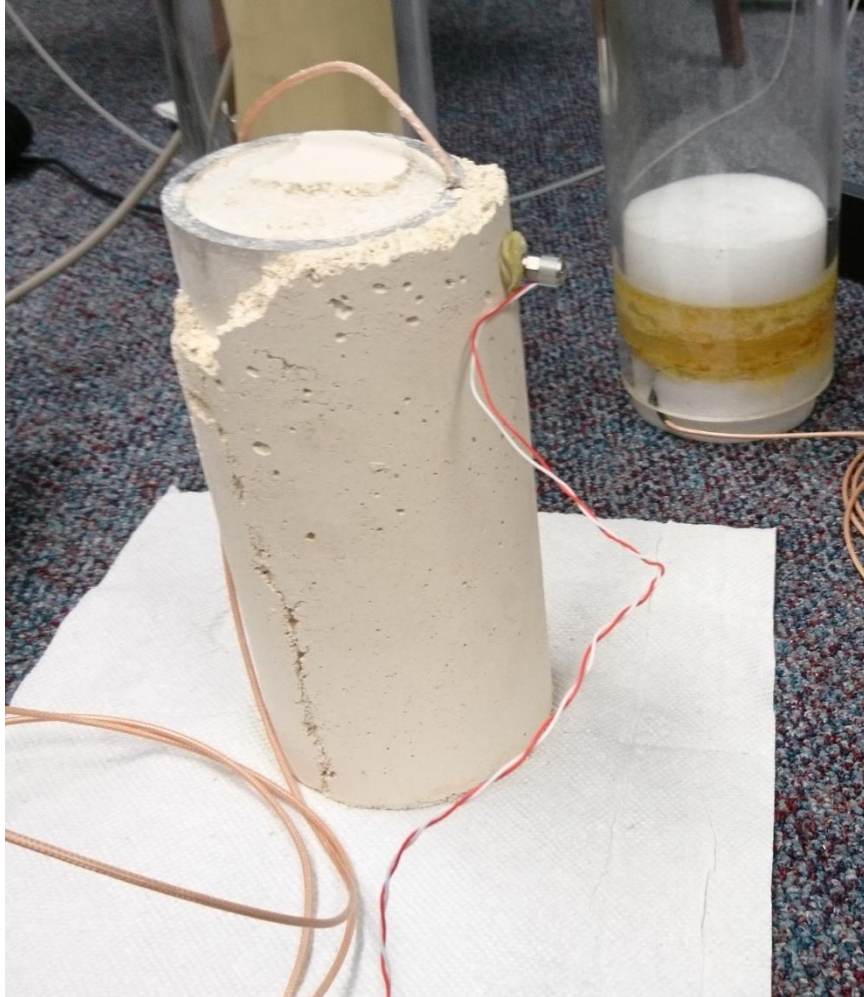
Receiver Improvements



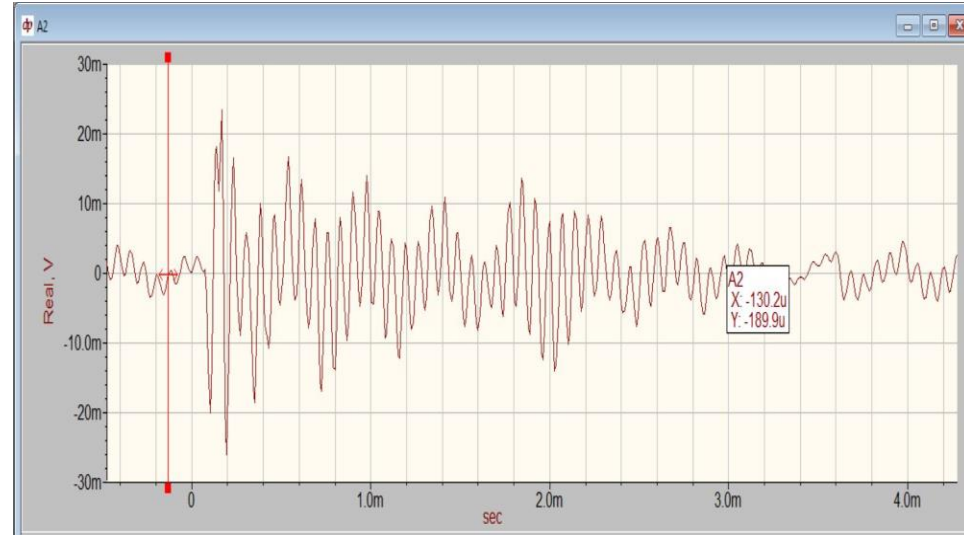
Synthetic Limerock Specimens



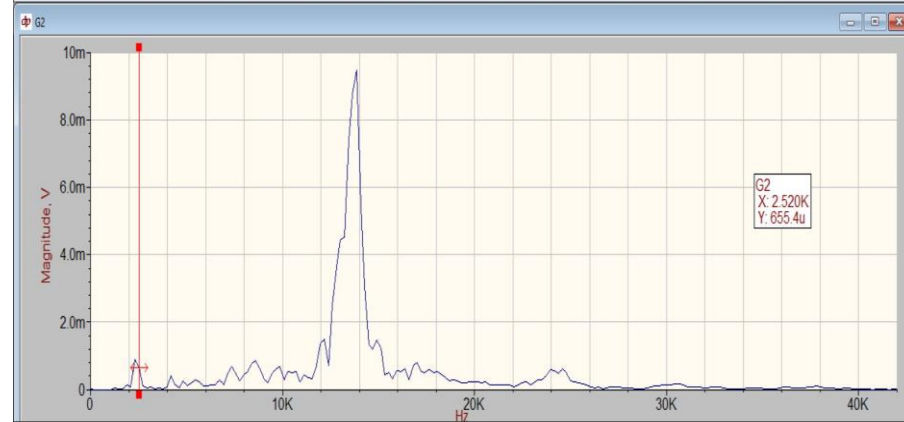
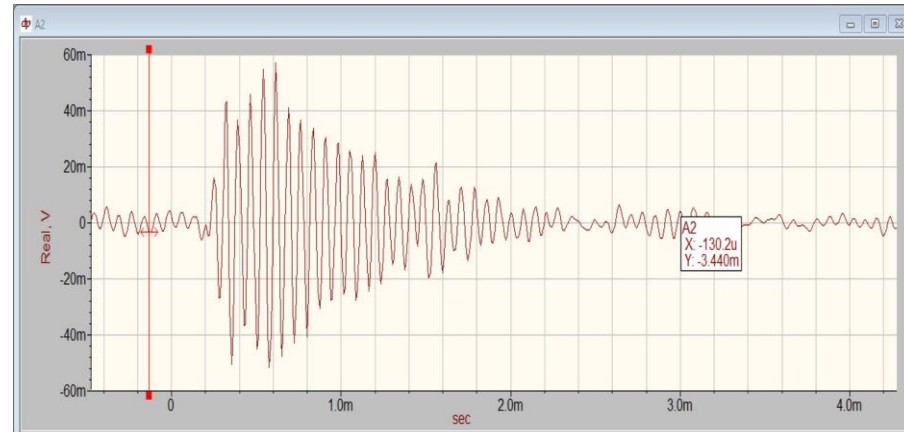
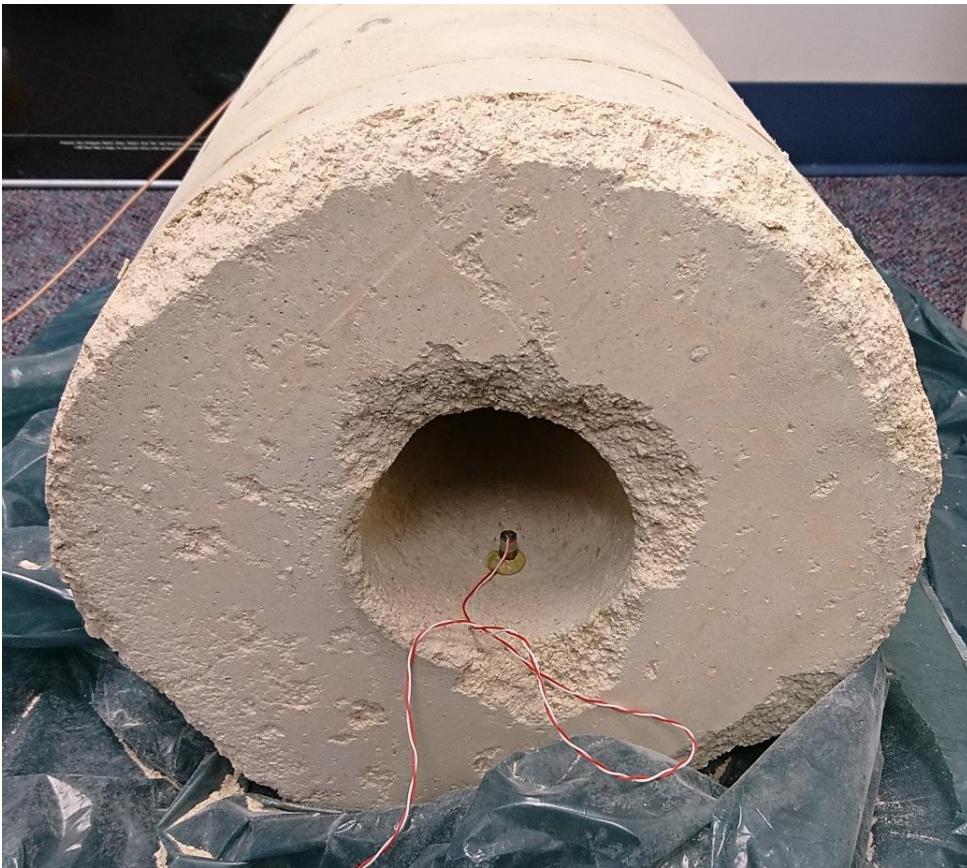
Synthetic Limerock Cylinder



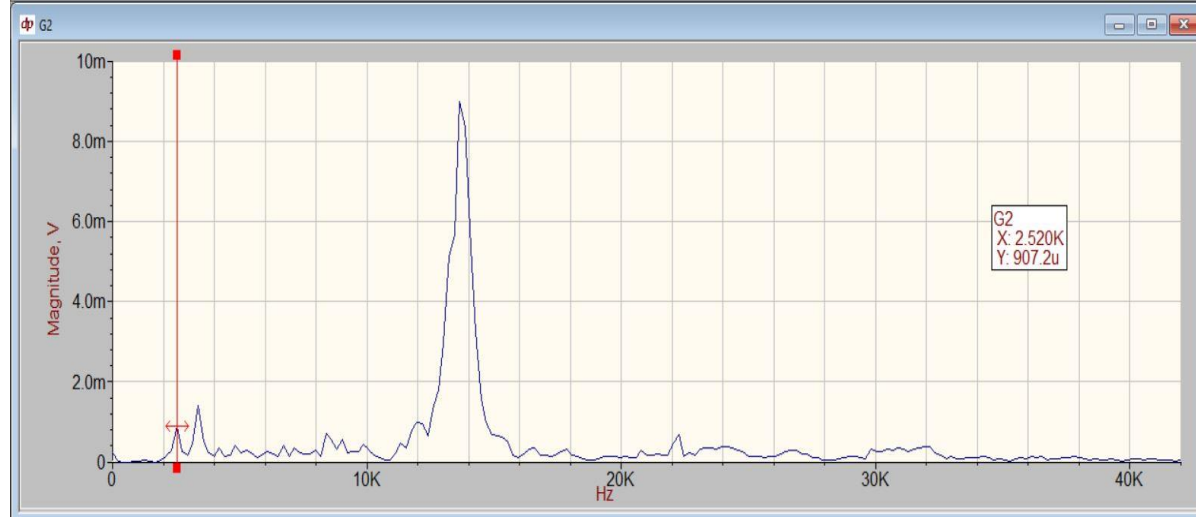
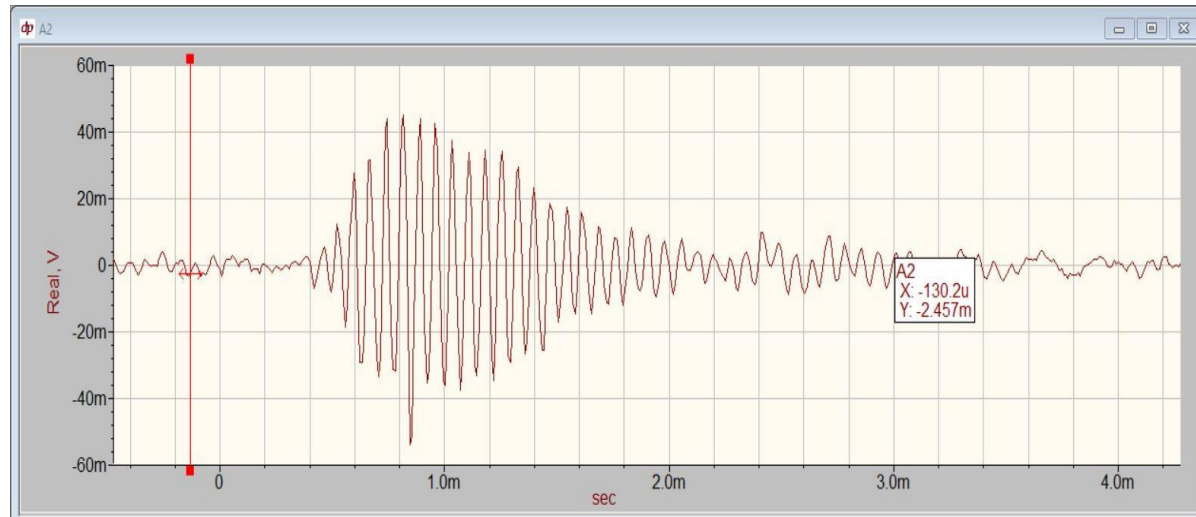
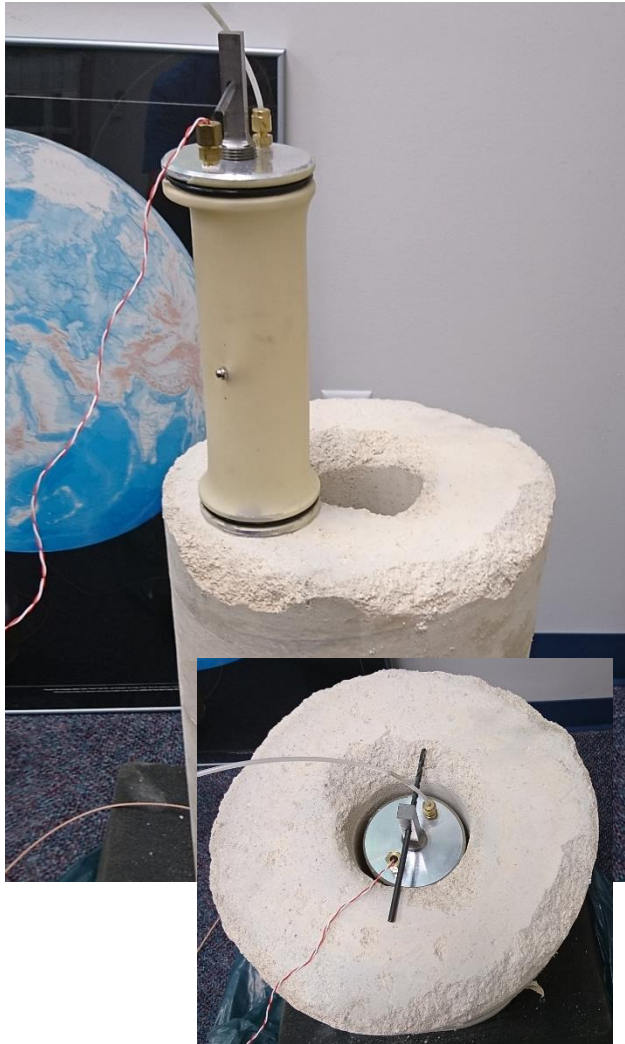
Synthetic Limerock Borehole Model



Synthetic Limerock Borehole Model



Synthetic Limerock Borehole Model

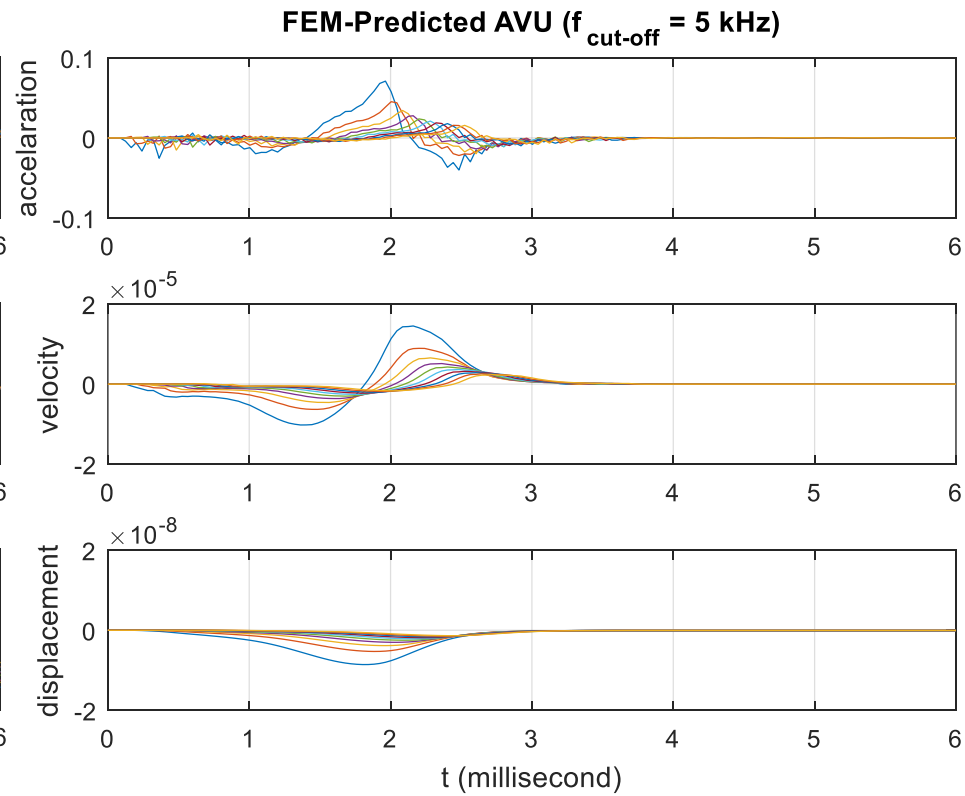
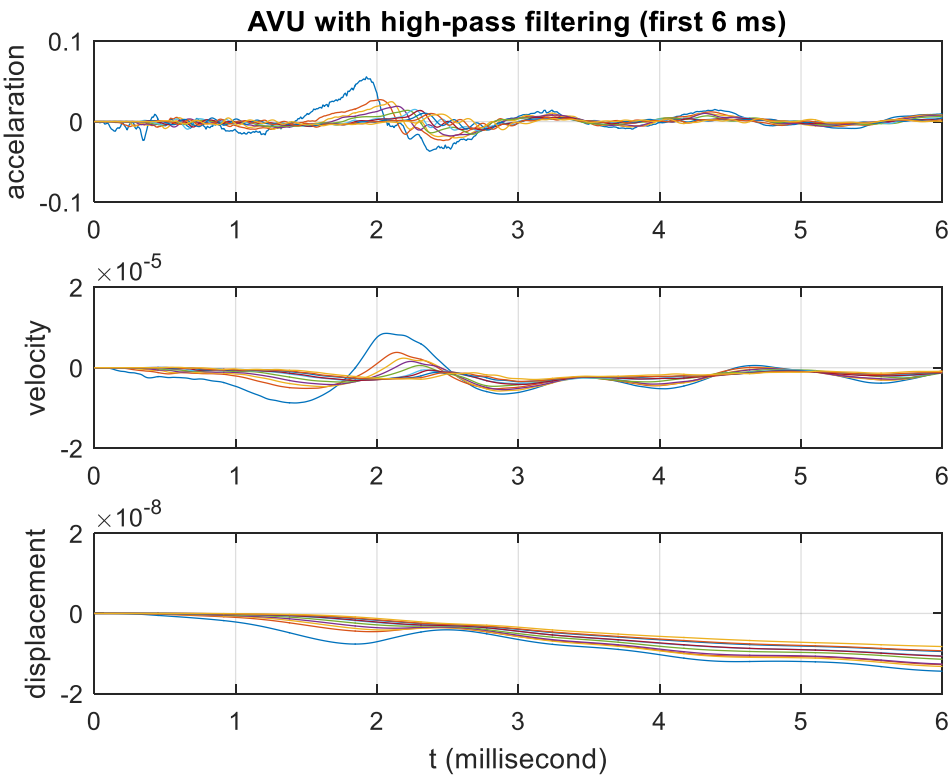


Synthetic Limerock Block

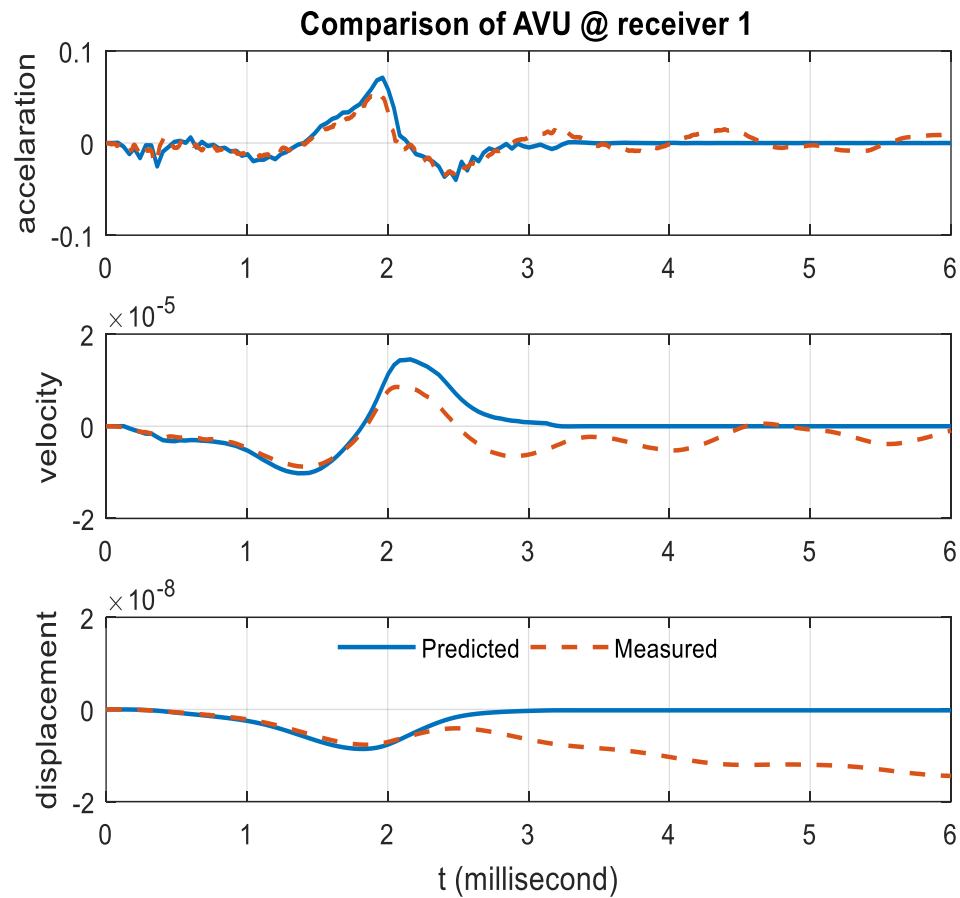
- Full waveform tests on top surface
- Free-free resonant column tests on companion cylinder
 - $V_p = 1500$ m/s
 - Poisson's ratio = 0.2
 - Thus $V_s = 890$ m/s



Synthetic Limerock Block

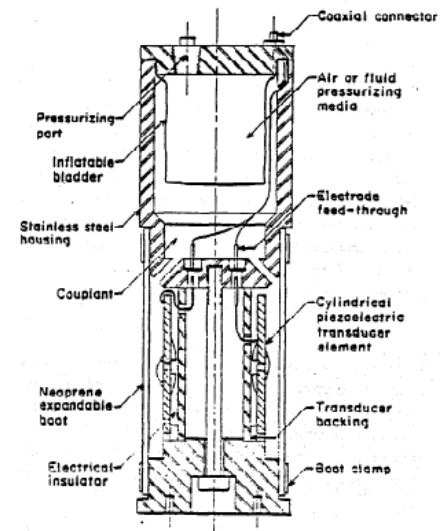


Synthetic Limerock Block



Next Activities

- 3-component accelerometers
- Repeatable, reusable coupling of borehole source
- Continue development of processing and inversion techniques on data from field experiments



Thank You!

